

R88M-1 / R88D-1 SN - ECT-51

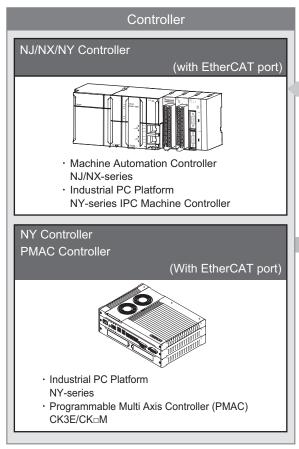
SS1 and SLS Realize More Efficient Production

- Simple installation and wiring contributes to board design efficiency
- EtherCAT Communications Cycle of 125 μs
- Achievement of Safety on EtherCAT Network
- Supports two-degree-of-freedom control
- Battery-free system reduces maintenance and space
- · Comes equipped with a 23-bit ABS encoder
- 350% momentary maximum torque (200 V, 750 W max.)
- The following three safety functions are provided: STO, SS1, and SLS



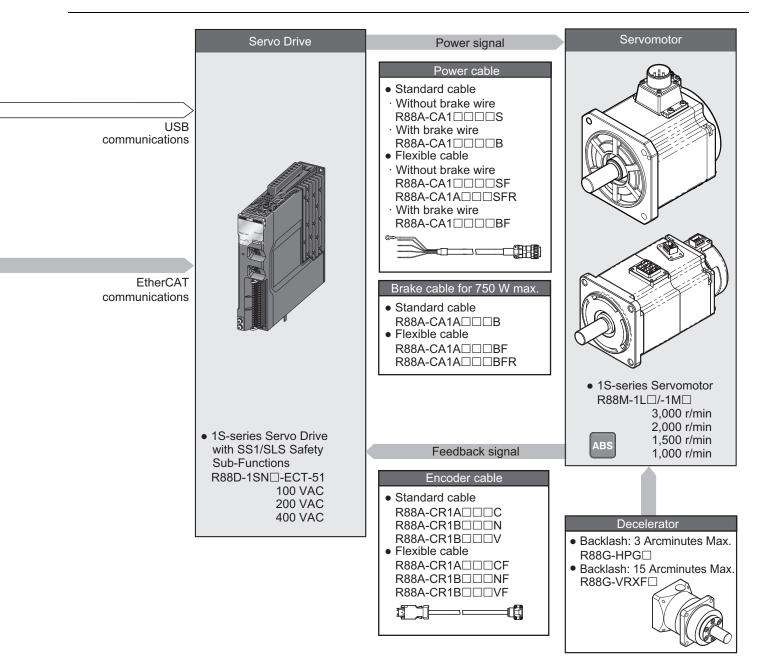


AC Servo System 1S-series with SS1/SLS Safety Sub-Functions System Configuration





Note: PMAC is an abbreviation for Programmable Multi Axis Controller.



R88D-1SN□-ECT-51

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- EtherCAT Communication Specifications
- Version Information
- Names and Functions
- Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

	Item		Specifications		
Operating am	bient temperature an	d humidity	0 to 55°C, 90% max. (with no condensation)		
Storage ambie	ent temperature and	humidity	-20 to 65°C, 90% max. (with no condensation)		
Operating and	l storage atmosphere)	No corrosive gases		
Operating alti	tude		1,000 m max.		
Vibration resis	stance		10 to 60 Hz and at an acceleration of 5.88 m/s² or less (Not to be run continuously at the resonance frequency)		
Insulation res	istance		Between power supply terminals/power terminals and PE terminals: 0.5 $\text{M}\Omega$ min. (at 500 VDC)		
Dielectric strength			Between power supply terminals/power terminals and PE terminals: 1,500 VAC for 1 min (at 50/60 Hz)		
Protective str	ucture		IP20 (Built into IP54 panel)		
	EU Directives	EMC	EN 61800-3 second environment, C3 category		
	and UK legislation	Low Voltage	EN 61800-5-1		
		Machinery	EN ISO 13849-1 (Cat.3), EN 61508, EN 62061, EN 61800-5-2		
	UL standards		UL 61800-5-1		
International	CSA standards		CSA C22.2 No. 274		
standard *1			Compliant		
	Australian EMC Labelling Requirements (RCM)		Compliant		
	SEMI standards		Can conform to the standard for momentary power interruptions (for no-load operation).		
	Ship standards (NK	/LR)	Not compliant		

^{*1.} Refer to the OMRON website (http://www.ia.omron.com/) or consult your OMRON representative for the most recent applicable standards for each model.

Note: The above items reflect individual evaluation testing. The results may differ under compound conditions.

The detail of Machinery Directive is as follows:

The STO function via safety input signals: EN ISO 13849-1 (Cat3 PLe), EN 61508, EN 62061, EN 61800-5-2 (SIL3)

The safety function via FSoE communications: EN ISO 13849-1 (Cat.3 PLd), EN 61508 (SIL2), EN 62061 (SIL2), EN 61800-5-2

Precautions for Correct Use

Disconnect all connections to the Servo Drive before attempting a megger test (insulation resistance measurement) on a Servo Drive. Not doing so may result in the Servo Drive failure.

Do not perform a dielectric strength test on the Servo Drive. Internal elements may be damaged.

Characteristics

100-VAC Input Models

Servo Drive model (R88D-)			1SN01L-ECT-51	1SN02L-ECT-51	1SN04L-ECT-51			
	Item		100 W	200 W	400 W			
	Main circuit	Power supply voltage	Single-ph	Single-phase 100 to 120 VAC (85 to 132 V) ★ 1				
		Frequency		50/60 Hz (47.5 to 63 Hz) *1				
Input	Control circuit	Power supply voltage		24 VDC (21.6 to 26.4 V)				
put	Control Circuit	Current consumption *2		600 mA				
	Rated input current [A (rms)]	Single-phase	2.9	4.9	8.4			
	(Main circuit power supply voltage: 120 VAC)	3-phase						
Output	Rated current [A (rms)]		1.5	2.5	4.8			
Juipui	Maximum current [A (rms)]		4.7	8.4	14.7			
leat val	uo DA/I	Main circuit *3	14.8	23.4	33.1			
neat van	ue [vv]	Control circuit	11	11	13.2			
Applicat	ole Servomotor rated output [W]	100	200	400			
3,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M05030S 1M10030S	1M20030S	1M40030S				
Hold time at momentary power interruption (Main circuit power supply voltage: 100 VAC)		10 ms (Load condition: rated output) *4						
SCCR [A (rms)]			5000					
Weight [kg]		1.2	1.5	1.9			

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

Refer to the table on the page 14 for the Heating Values of Applicable Servomotors.

^{*2.} Select a DC power supply in consideration of the current values that are specified in the current consumption. The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive. Therefore, you do not need to consider it when you select a DC power supply for each model.

^{*3.} This is the maximum heating value in applicable Servomotors.

^{*4.} It is a hold time at momentary power interruption of the main circuit. However, if the main circuit power supply voltage falls below the rated voltage, even if it is a momentary power interruption within the hold time at momentary power interruption, a Main Power Supply Undervoltage (Error No. 13.00) may occur. In addition, use a DC power supply to fulfill the following conditions so that the power supply of the control circuit is held during momentary power interruption. Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

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Servo Drive model (R88D-)			1SN01H-ECT-51	1SN02H-ECT-51	1SN04H-ECT-51	1SN08H-ECT-51		
	Item		100 W	200 W	400 W	750 W		
	Main circuit	Power supply voltage	Single-phase and 3-phase 200 to 240 VAC (170 to 252 V) * 1					
		Frequency		50/60 Hz (47.	5 to 63 Hz) * 1			
Input	Control circuit	Power supply voltage		24 VDC (21	.6 to 26.4 V)			
put	Control circuit	Current consumption *2		600	mA			
	Rated current [A (rms)]	Single-phase	1.8	2.7	4.6	7.3		
	(Main circuit power supply voltage: 240 VAC)	3-phase	1.0	1.5	2.7	4.0		
Output	Rated current [A (rms)]		0.8	1.5	2.5	4.6		
Output	Maximum current [A (rms)]	3.1	5.6	9.1	16.9		
Heat val	[]A/[Main circuit *3	15.7/15.3 *4	15.2/14.6 *4	22.4/22.4 *4	40/39.7 *4		
Heat val	ue [vv]	Control circuit	11	11	11	13.2		
Applicat	ole Servomotor rated output	[W]	100	200	400	750		
3,000-r/n	nin Servomotor (R88M-)	Batteryless 23-bit ABS	1M05030T 1M10030T	1M20030T	1M40030T	1M75030T		
2,000-r/n	nin Servomotor (R88M-)	Batteryless 23-bit ABS						
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS								
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)		10 ms (Load condition: rated output) ≯ 5						
SCCR [A	(rms)]		5000					
Weight [kg]		1.2	1.2	1.5	2.0		

Servo Drive model (R88D-)			1SN10H-ECT-51	1SN15H-ECT-51	1SN20H-ECT-51	1SN30H-ECT-51		
Item			1 kW	1.5 kW	2 kW	3 kW		
	Main circuit	Power supply voltage	3-phase 200 to 240 VAC (170 to 252 V) *1	Single-phase and 3-phase 200 to 240 VAC (170 to 2 VAC (170 to 252 V) *1 *1				
		Frequency		50/60 Hz (47.	5 to 63 Hz) * 1			
Input	Control circuit	Power supply voltage		24 VDC (21	.6 to 26.4 V)			
	Control circuit	Current consumption *2	600 mA	900 mA				
	Rated current [A (rms)]	Single-phase		15.7				
	(Main circuit power supply voltage: 240 VAC)	3-phase	5.8	9.0	13.0	15.9		
Output	Rated current [A (rms)]		7.7	9.7	16.2	22.3		
Output	Maximum current [A (rms)]	16.9	28.4	41.0	54.7		
Heat valu	IN/I	Main circuit *3	46.5	85.5/85.5 * 4	128.9	167.5		
rieat vait	ne [AA]	Control circuit	13.2	20.4	20.4	20.4		
Applicab	le Servomotor rated output	[W]	1,000	1,500	2,000	3,000		
3,000-r/m	nin Servomotor (R88M-)	Batteryless 23-bit ABS	1L1K030T	1L1K530T	1L2K030T	1L3K030T		
2,000-r/m	nin Servomotor (R88M-)	Batteryless 23-bit ABS	1M1K020T	1M1K520T	1M2K020T	1M3K020T		
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M90010T		1M2K010T	1M3K010T			
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition: rated output) *5					
SCCR [A	(rms)]		5000					
Weight [kg]		2.0	3.4	3.4	3.4		

	Servo Drive model (R8	8D-)	1SN55H-ECT-51	1SN75H-ECT-51	1SN150H-ECT-51		
	Item		5.5 kW	7.5 kW	15 kW		
	Main circuit	Power supply voltage	3-phase 200 to 240 VAC (170 to 252 V) * 1				
		Frequency		50/60 Hz (47.5 to 63 Hz) *1			
Input	Control circuit	Power supply voltage		24 VDC (21.6 to 26.4 V)			
put	Control circuit	Current consumption *2	900) mA	1,200 mA		
	Rated current [A (rms)] (Main circuit power supply voltage: 240 VAC)	3-phase	27.0	38.0	77.0		
O. 14m . 14	Rated current [A (rms)]		28.6	42.0	70.0		
Output	Output Maximum current [A (rms)]		84.8	113	169.7		
Heat value [W]		Main circuit *3	290	360	610		
neat vait	ue [vv]	Control circuit	19	29.7			
Applicab	le Servomotor rated output	[W]	5,500	7,500	15,000		
3,000-r/m	nin Servomotor (R88M-)	Batteryless 23-bit ABS	1L4K030T 1L4K730T				
2,000-r/m	nin Servomotor (R88M-)	Batteryless 23-bit ABS					
1,500-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1M4K015T 1M5K015T	1M7K515T	1M11K015T 1M15K015T		
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS							
	e at momentary power inter cuit power supply voltage:		10 ms (Load condition: rated output) *5				
SCCR [A	(rms)]			5000			
Weight [kg]		9.4	9.4	21		

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

Refer to the table on the next page for the heating value of each applicable Servomotor.

^{*2.} Select a DC power supply in consideration of the current values that are specified in the current consumption.

The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive. Therefore, you do not need to consider it when you select a DC power supply for each model.

^{*3.} This is the maximum heating value in applicable Servomotors.

^{*4.} The first value is for single-phase input power and the second value is for 3-phase input power.

^{*5.} It is a hold time at momentary power interruption of the main circuit. However, if the main circuit power supply voltage falls below the rated voltage, even if it is a momentary power interruption within the hold time at momentary power interruption, a Main Power Supply Undervoltage (Error No. 13.00) may occur. In addition, use a DC power supply to fulfill the following conditions so that the power supply of the control circuit is held during momentary power interruption. Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

400-VAC Input Models

Use a neutral grounded 400 VAC 3-phase power supply for the 400 VAC input models.

Servo Drive model (R88D-)		el (R88D-)	1SN06F-ECT-51	1SN10F-ECT-51	1SN15F-ECT-51	1SN20F-ECT-51		
	Item		600 W	1 kW	1.5 kW	2 kW		
	Main circuit	Power supply voltage	3-	3-phase 380 to 480 VAC (323 to 504 V) ★ 1				
	Main Circuit	Frequency		50/60 Hz (47.	5 to 63 Hz) * 1			
	Control circuit	Power supply voltage		24 VDC (21	.6 to 26.4 V)			
Input	Control circuit	Current consumption *2		900	mA			
	Rated current [A (rms)] (Main circuit power supply voltage: 480 VAC)	3-phase	2.4	3.1	4.3	6.5		
Output	Rated current [A (rms)]		1.8	4.1	4.7	7.8		
Output	Maximum current [A (rms	[(5.5	9.6	14.1	19.8		
Heat va	duo FWI	Main circuit *3	20.2	52.1	77.5	106.8		
neat va	iide [vv]	Control circuit	20.4	20.4	20.4	20.4		
Applica	ble Servomotor rated outpo	ut [W]	600	1,000	1,500	2,000		
3,000-r/	min Servomotor (R88M-)	Batteryless 23-bit ABS		1L75030C 1L1K030C	1L1K530C	1L2K030C		
2,000-r/	min Servomotor (R88M-)	Batteryless 23-bit ABS	1M40020C 1M60020C	1M1K020C	1M1K520C	1M2K020C		
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS			1M90010C		1M2K010C			
Hold time at momentary power interruption (Main circuit power supply voltage: 400 VAC)			10 ms (Load condition: rated output) *4					
SCCR [A (rms)]			5000					
Weight	[kg]		3.4	3.4	3.4	3.4		

Servo Drive model (R88D-)		1SN30F-ECT-51	1SN55F-ECT-51	1SN75F-ECT-51	1SN150F-ECT-51			
	Item		3kW	5.5kW	7.5kW	15kW		
	Main circuit	Power supply voltage	3-	3-phase 380 to 480 VAC (323 to 504 V) *1				
	Main Circuit	Frequency		50/60 Hz (47.	5 to 63 Hz) * 1			
	Control circuit	Power supply voltage		24 VDC (21	.6 to 26.4 V)			
Input	Control circuit	Current consumption *2		900 mA		1,200 mA		
	Rated current [A (rms)] (Main circuit power supply voltage: 480 VAC)	3-phase	8.4	16.0	23.0	40.0		
Outnut	Rated current [A (rms)]		11.3	14.5	22.6	33.9		
Output	Maximum current [A (rms)]	28.3	42.4	56.5	84.8		
Llast va	lue DA/I	Main circuit *3	143.3	280.0	280.0	440.0		
Heat value [W] Control circuit		Control circuit	20.4	19	29.7			
Applica	ble Servomotor rated outpo	ut [W]	3,000	5,500	7,500	15,000		
3,000-r/	min Servomotor (R88M-)	Batteryless 23-bit ABS	1L3K030C	1L4K030C 1L5K030C				
2,000-r/	min Servomotor (R88M-)	Batteryless 23-bit ABS	1M3K020C					
1,500-r/	min Servomotor (R88M-)	Batteryless 23-bit ABS		1M4K015C 1M5K515C	1M7K515C	1M11K015C 1M15K015C		
1,000-r/min Servomotor (R88M-) Batteryless 23-bit ABS		1M3K010C						
Hold time at momentary power interruption (Main circuit power supply voltage: 400 VAC)		10 ms (Load condition: rated output) *4						
SCCR [A (rms)]		5000						
Weight	[kg]		3.4	9.4	9.4	21		

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

Therefore, you do not need to consider it when you select a DC power supply for each model. ***3.** This is the maximum heating value in applicable Servomotors.

^{*2.} Select a DC power supply in consideration of the current values that are specified in the current consumption. The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive.

^{*3.} This is the maximum heating value in applicable Servomotors.
Refer to the table below for the heating value of each applicable Servomotor.
*4. It is a hold time at momentary power interruption of the main circuit. However, if the main circuit power supply voltage falls below the rated voltage, even if it is a momentary power interruption within the hold time at momentary power interruption, a Main Power Supply Undervoltage (Error No. 13.00) may occur. In addition, use a DC power supply to fulfill the following conditions so that the power supply of the control circuit is held during momentary power interruption. Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

Servo Drive model	Servomotor model	Main circuit heat value [W
	R88M-1M05030S-	11.2
R88D-1SN01L-ECT-51	R88M-1M10030S-□	14.8
	R88M-1M05030T-	13.2/13.2 *
R88D-1SN01H-ECT-51	R88M-1M10030T-	15.7/15.3 *
	R88M-1L1K030T-□	46.5
R88D-1SN10H-ECT-51	R88M-1M1K020T-□	37.7
	R88M-1M90010T-□	42.9
	R88M-1L1K530T-□	85.5/85.5 *
R88D-1SN15H-ECT-51	R88M-1M1K520T-□	84/84 *
	R88M-1L2K030T-□	128.9
R88D-1SN20H-ECT-51	R88M-1M2K020T-	91.3
1.005 10112011 201 01	R88M-1M2K010T-	109.1
	R88M-1L3K030T-	167.5
R88D-1SN30H-ECT-51	R88M-1M3K020T-	125.5
100D-1010011-E01-91	R88M-1M3K010T-	156.7
	R88M-1L4K030T-	250
-	R88M-1M4K015T-	270
R88D-1SN55H-ECT-51	R88M-1L4K730T-	290
-	R88M-1M5K015T-	290
R88D-1SN75H-ECT-51		360
R00D-15N/5H-EC1-51	R88M-1M7K515T-	
R88D-1SN150H-ECT-51	R88M-1M11K015T-	490
	R88M-1M15K015T-	610
R88D-1SN06F-ECT-51	R88M-1M40020C-	14.4
	R88M-1M60020C-□ R88M-1L75030C-□	
-		51.1 52.1
R88D-1SN10F-ECT-51	R88M-1L1K030C-□ R88M-1M1K020C-□	
_		33.4
	R88M-1M90010C-	40.2
R88D-1SN15F-ECT-51	R88M-1L1K530C-	77.5
	R88M-1M1K520C-	47.9
	R88M-1L2K030C-	106.8
R88D-1SN20F-ECT-51	R88M-1M2K020C-	65.7
	R88M-1M2K010C-	79.6
	R88M-1L3K030C-□	143.3
R88D-1SN30F-ECT-51	R88M-1M3K020C-□	96.5
	R88M-1M3K010C-□	115.5
_	R88M-1L4K030C-□	250
R88D-1SN55F-ECT-51	R88M-1M4K015C-□	280
	R88M-1L5K030C-□	250
	R88M-1M5K515C-□	280
R88D-1SN75F-ECT-51	R88M-1M7K515C-□	280
R88D-1SN150F-ECT-51	R88M-1M11K015C-□	390
	R88M-1M15K015C-□	440

Outline of Safety Functions

Details about Safety Functions

Function	Description
Safe torque off (STO)	The function is used to cut off a motor current and stop the motor.
Safe stop 1 (SS1)	This function is used to stop a motor by activating STO function at any timing after receiving a command from a safety controller.
Safely-limited speed (SLS)	This function is used to monitor a safety present motor velocity. When the safety present motor velocity exceeds the velocity limit for monitoring, excessive limit value error occurs.

Safety Servo Drives have two type STO functions. Use either of these functions according to configuration of safety devices.

- · STO function by safety input signals
- · STO function via FSoE communications

When you use just STO function by safety input signals, you do not need a setting related EtherCAT network.

The specifications of each safety function are as follows.

Safety Function	Item	Specifications
STO	Reaction time *1	5 ms (STO function via safety input signals) 7 ms (STO function via FSoE)
SS1	Delay time	0 to 65535 ms
	Delay time	0 to 65535 ms
SLS	Velocity limit	30 to 20000 r/min
	Reaction time *2	10 to 25 ms

- *1. Time from receiving of STO command to STO state (torque-off state)
- *2. Time from motor velocity exceeding the monitoring limit to STO state (torque-off state)

Achievable safety levels for each safety function at maximum are shown as the below table:

Function	Achievable safety level EN61508/EN ISO 13849-1
STO function via safety input signals	SIL3/PLe
STO function via FSoE	SIL2/PLd
SS1 *1	SIL2/PLd
SLS * 2, * 3	SIL2/PLd

- *1. The method to activate STO when the motor stops is not supported. If you use an existing user program based on this method, you may need to change or modify the user program.
- *2. The method of activating SLS when reaching the monitoring velocity is not supported. If you use an existing user program based on this method, you may need to change or modify it.

After Servo ON, the SLS function should be activated when the speed is stable.

Although SLS velocity limit can be set to less than 100 r/min, Safety Present Motor Velocity may be displayed 100 r/min larger than Present Motor Velocity. Therefore, at a monitoring velocity of less than 100 r/min, SLS Monitoring Limit Exceeded may occur even though the monitoring velocity is not actually exceeded. Set an appropriate monitoring speed after thoroughly checking the operation.

To use the SLS function, we recommend to use an OMRON motor power cable of 20 m or less. Using a motor power cable longer than 20 m may cause the following phenomena even during normal operation, resulting in a false detection of Monitoring Limit Exceeded or Safety Present Motor Velocity Error 2. Set an appropriate monitoring speed after thoroughly checking the operation. In addition, using a noise filter on the power supply line may stabilize the Safety Present Motor Velocity and reduce false detections. For information on noise filters, refer to the manual listed below.

- a) Safety Present Motor Velocity, which is the velocity monitoring target of the SLS function, may exceed the actual velocity much more than 100 r/min.
- b) Safety Velocity Detection. Status (4F1A-82 hex) may be disabled. Consult your OMRON sales representative for details.
- *3. Using the SLS function when a vertical axis, etc., is subject to an unbalanced load may result in a false detection of Safety Present Motor Velocity Error 2 even during normal operation. For axes to which this applies, use the 1S Series with Safety Functionality R88D-1SAN.

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696) for details.

Configuration for Safety System

To make devices enter into safe state, a combined control among a safety controller, a standard controller and a Servo Drive is required. Typical roles of each device are shown as below.

Device	Role
Safety Controller	 Monitor safety input and output. Notify a standard controller of states of safety input and output. Issue commands to activate and interrupt safety functions to a Servo Drive. Issue commands to reset errors of safety functions to a Servo Drive.
Standard Controller	 Issue commands to turn Servo ON/OFF and reset errors to a Servo Drive. Issue command to control a specified position, velocity and torque of a Servomotor to a Servo Drive.
Servo Drive	 Turn Servo ON/OFF and reset errors after receiving commands from a standard controller. Control a Servomotor after receiving commands from a standard controller. Activate and interrupt safety functions after receiving commands from a safety controller. Reset errors of safety functions after receiving commands from a safety controller. Stop a Servomotor when an error occurs.

A procedure for the control is described as follow:

1. A safety controller detects the following cases with a safety sensor and a safety switch.

When workers entered exclusion zones

When workers are about to touch hazardous sites of the device

When workers come closely to the devices for the purpose of a check of devices/products, maintenance and supply of materials

- 2. A safety controller notifies a standard controller of the detected data.
- 3. A standard controller issues commands to decelerate and stop a Servomotor to a Servo Drive. At the same time, a safety controller issues commands to activate safety functions for use to a Servo Drive.
- 4. A Servo Drive receives and executes the commands from both controllers.

Thus, a safety controller and a standard controller must issue commands to a Servo Drive at an appropriate timing according to states of switches, sensors and devices, and then have the programs to issue the commands.

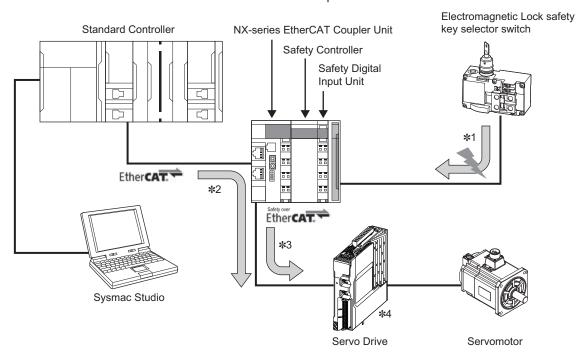
To secure the combined operation between a safety controller and a standard controller, design programs for each device with consideration of the following times. Without this consideration mentioned earlier, STO may be active and an Excessive Limit Value Error may occur.

- Time until safety functions starts the activations
 It refers to "Time until a safety controller issues command to activate safety functions + Delay time of safety functions".
- · Delay time of safety functions

Time until STO becomes active or a Servo Drive starts monitoring after it receives commands of safety functions.

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696) for details.

This section describes a flow of control of each device with an example such as SLS function.



Safety system configuration equipment	Model
Standard Controller	NX701
EtherCAT Coupler Unit	NX-ECC201 NX-ECC202
Safety Controller	NX-SL3300 NX-SL3500
Safety Digital Input Unit	NX-SIH400
Guard Lock Safety Key Selector Switch	A22LK
Servo Drive	R88D-1SN□□- ECT-51

- *1. The safety key selector switch and the safety controller detect that workers come closer to devices due to the reason such as maintenance, etc.
- *2. The standard controller reads data from the safety controller and checks a switch to maintenance mode. In such case, it issues a command to decelerate a velocity of the Servomotor and gives the command to the Servo Drive.
- *3. The safety controller issues/gives a command to activate SLS function to the Servo Drive.
- *4. The Servo Drive controls the motor's deceleration, following the command from the standard controller. In addition, it activates SLS function after receiving the command to activate SLS from the safety controller.

AC Servo System 1S-series with SS1/SLS Safety Sub-Functions EtherCAT Communications Specifications

Item	Specifications				
Communications standard	IEC 61158 Type 12, IEC 61800-7 CiA 402 Drive Profile				
Physical layer	100BASE-TX (IEEE802.3)				
Connectors	RJ45 × 2 (shielded) ECAT IN: EtherCAT input ECAT OUT: EtherCAT output				
Communications media	Recommended media: Twisted-pair cable, which is doubly shielded by the aluminum tape and braid, with Ethernet Category 5 (100BASE-TX) or higher				
Communications distance	Distance between nodes: 100 m max.				
Process data	Fixed PDO mapping Variable PDO mapping				
Mailbox (CoE)	Emergency messages, SDO requests, SDO responses, and SDO information				
Synchronization mode and communications cycle	DC Mode (Synchronous with Sync0 Event) Communications cycle: 125 μs, 250 μs, 500 μs, 750 μs, 1 to 10 ms (in 0.25 ms increments) Free Run Mode				
Indicators	ECAT-L/A IN (Link/Activity IN) × 1 ECAT-L/A OUT (Link/Activity OUT) × 1 ECAT-RUN × 1 ECAT-ERR × 1				
CiA 402 Drive Profile	Cyclic synchronous position mode Cyclic synchronous velocity mode Cyclic synchronous torque mode Profile position mode Profile velocity mode Homing mode Touch probe function Torque limit function				

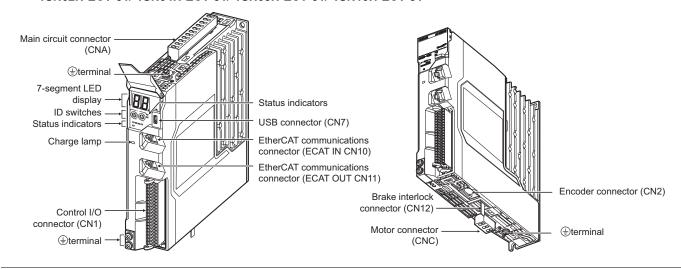
Version Information

1S-series S	Corresponding version	
Model	Sysmac Studio	
R88D-1SN□-ECT-51	Version 2.0	Version 1.59 or higher

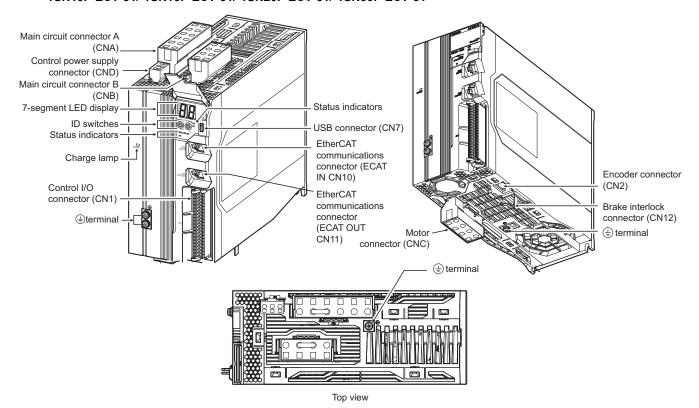
Part Names

Servo Drive Part Names

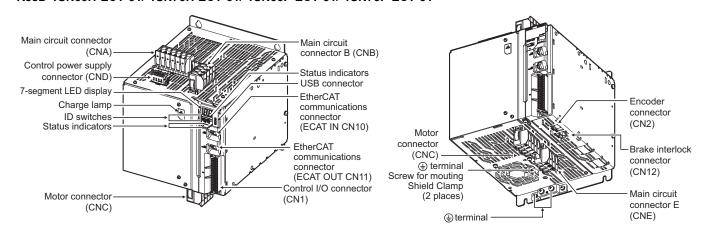
R88D-1SN01L-ECT-51/-1SN02L-ECT-51/-1SN04L-ECT-51/-1SN01H-ECT-51/ -1SN02H-ECT-51/-1SN04H-ECT-51/-1SN08H-ECT-51/-1SN10H-ECT-51

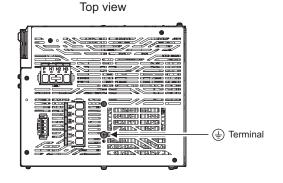


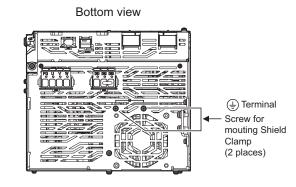
R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN06F-ECT-51/ -1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51



R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51

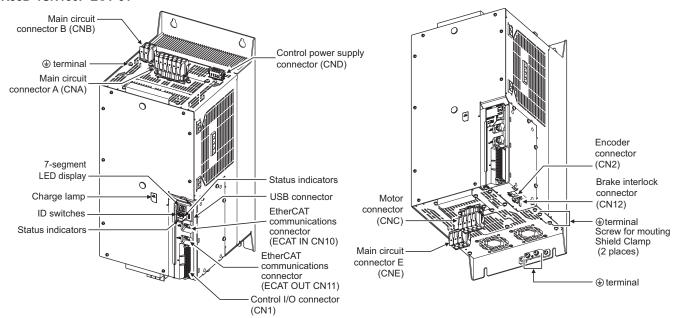






R88D-1SN150H-ECT-51 Main circuit connector B (CNB) Main circuit terminal block (CNA) Control power supply connector (CND) terminal Encoder connector 7-segment (CN2) LED display Status indicators Brake interlock Motor USB connector Charge lamp connector connection EtherCAT (CN12) ID switches terminal block communications (CNC) ⊕terminal Status indicators connector Screw for mouting Shield Clamp (ECAT IN CN10) Main circuit EtherCAT connector E (2 places) communications (CNE) connector (ECAT OUT CN11) ⊕ terminal Control I/O connector (CN1)

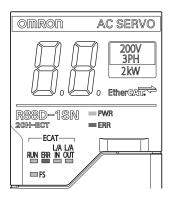
R88D-1SN150F-ECT-51



Servo Drive Functions

Status Indicators

The following seven indicators are mounted.



Name	Color	Description			
PWR	Green	Displays the status of control power supply.			
ERR	Red	Gives the Servo Drive error status.			
ECAT-RUN	Green	Displays the EtherCAT communications status			
ECAT-ERR	Red	Displays the EtherCAT communications status.			
ECAT-L/A IN, ECAT-L/A OUT	Green	Lights or flashes according to the status of a link in the EtherCAT physical layer.			
FS	Red/green	Displays the safety communications status.			

7-segment LED Display

A 2-digit 7-segment LED display shows error numbers, the Servo Drive status, and other information.

ID Switches

Two rotary switches (0 to F hex) are used to set the EtherCAT node address.

Charge Lamp

Lights when the main circuit power supply carries electric charge.

Control I/O Connector (CN1)

Used for command input signals, I/O signals, and as the safety device connector. The short-circuit wire is installed on the safety signals before shipment.

Encoder Connector (CN2)

Connector for the encoder installed in the Servomotor.

EtherCAT Communications Connectors (ECAT IN CN10, ECAT OUT CN11)

These connectors are for EtherCAT communications.

USB Connector (CN7)

USB-Micro B Communications connector for the computer. This connector enables USB 2.0 Full Speed (12 Mbps) communications.

Brake Interlock Connector (CN12)

Used for brake interlock signals.

Main Circuit Connector (CNA)

Connector for the main circuit power supply input, control power supply input, external regeneration resistor, and DC reactor. Applicable models: R88D-1SN01L-ECT-51/-1SN02L-ECT-51/-1SN04L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51/-1SN04

Main Circuit Connector A (CNA)

Connector for the main circuit power supply input and external regeneration resistor. The connector differs depending on the model. Applicable models: R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN10F-ECT-51/-1SN30F-ECT-51/-1SN30F-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51

Main Circuit Terminal Block (CNA)

Connector for the main circuit power supply input. Applicable models: R88D-1SN150H-ECT-51

Main Circuit Connector A (CNA)

Connector for the main circuit power supply input and AC reactor.

Applicable models: R88D-1SN150F-ECT-51

Main Circuit Connector B (CNB)

Connector for a DC reactor. The connector differs depending on the model.

Applicable models: R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN10F-ECT-51/-1SN10F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51

Main Circuit Connector B (CNB)

Connector for a external regeneration resistor.

Applicable models: R88D-1SN150H-ECT-51/ -1SN150F-ECT-51

Control Power Supply Connector (CND)

Connector for control power supply input. The connector differs depending on the model.

Applicable models: R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN150H-ECT-51/-1SN10F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51/-1SN55F-ECT-

-1SN75F-ECT-51/-1SN150F-ECT-51

Motor Connector (CNC)

Connector for the power line to the phase U, V, and W of the Servomotor. The connector differs depending on the model.

Motor Connection Terminal Block (CNC)

Connector for the power line to the phase U, V, and W of the Servomotor.

Applicable models: R88D-1SN150H-ECT-51

Main Circuit Connector E (CNE)

Connector for a External Dynamic Brake Resistor.

Applicable models: R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN150H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51/-1SN150F-ECT-51

Terminal

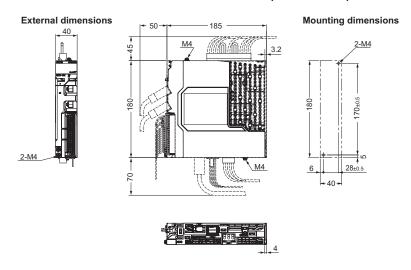
The number of \oplus terminals of the Servo Drives and their connection targets are as follows.

Model	Number of terminals	Connection to
R88D-1SN01L-ECT-51/-1SN02L-ECT-51/	1 on top	PE wire of the main circuit power supply cable.
-1SN04L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51/	2 on front	FG wire inside the control panel, and FG wire for the motor
-1SN04H-ECT-51/-1SN08H-ECT-51/-1SN10H-ECT-51	1 on bottom	cable and shielded wire.
R88D-1SN15H-ECT-51/-1SN20H-ECT-51/	1 on top	PE wire of the main circuit power supply cable.
-1SN30H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/	2 on front	FG wire inside the control panel and the motor cable shielded
-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51	1 on bottom	wire.
R88D-1SN55H-ECT-51/-1SN75H-ECT-51/	1 on top	PE wire of the main circuit power supply cable.
-1SN150H-ECT-51/-1SN55F-ECT-51/	2 on front	FG wire inside the control panel and the motor cable shielded
-1SN75F-ECT-51/-1SN150F-ECT-51	2 on bottom	wire.

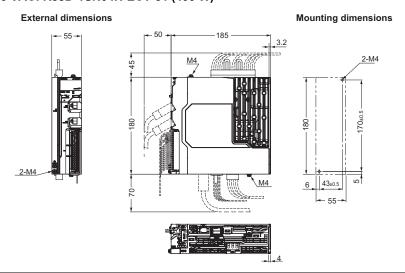
Dimensions (Unit: mm)

Single-phase 100 VAC: R88D-1SN01L-ECT-51 (100 W)

Single-phase/3-phase 200 VAC: R88D-1SN01H-ECT-51/-1SN02H-ECT-51 (100 to 200 W)



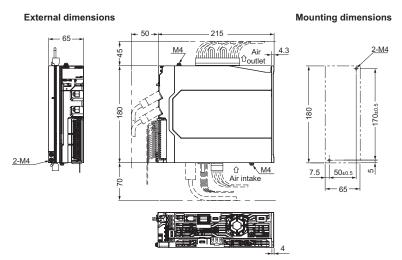
Single-phase 100 VAC: R88D-1SN02L-ECT-51 (200 W) Single-phase/3-phase 200 VAC: R88D-1SN04H-ECT-51 (400 W)



Single-phase 100 VAC: R88D-1SN04L-ECT-51 (400 W)

Single-phase/3-phase 200 VAC: R88D-1SN08H-ECT-51 (750 W)

3-phase 200 VAC: R88D-1SN10H-ECT-51 (1 kW)



Single-phase/3-phase 200 VAC: R88D-1SN15H-ECT-51 (1.5 kW) 3-phase 200 VAC: R88D-1SN20H-ECT-51/-1SN30H-ECT-51 (2 to 3 kW)

3-phase 400 VAC: R88D-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/ -1SN30F-ECT-51 (600 W to 3 kW)

External dimensions

Mounting dimensions

5.5

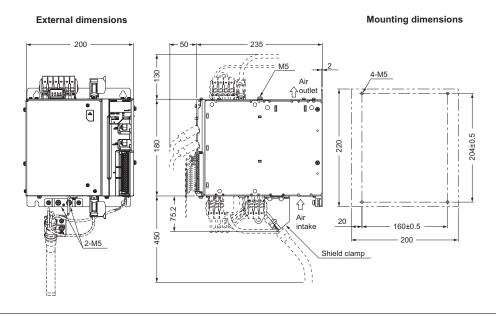
Air Doublet Intake

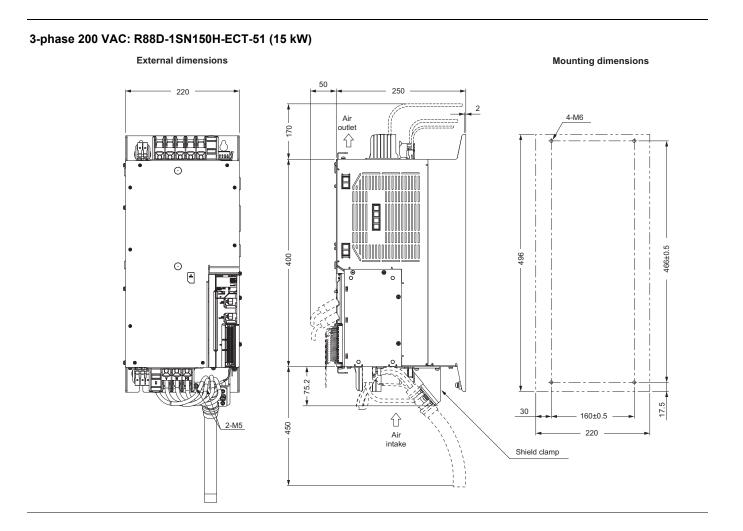
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Air Doublet Intake

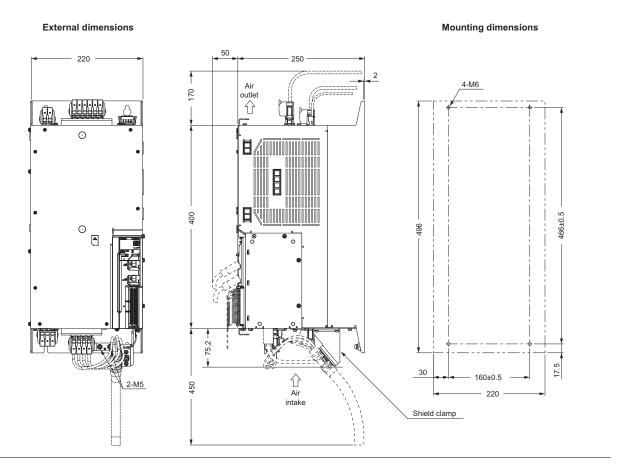
M4

3-phase 200 VAC: R88D-1SN55H-ECT-51/-1SN75H-ECT-51 (5.5 to 7.5 kW) 3-phase 400 VAC: R88D-1SN55F-ECT-51/-1SN75F-ECT-51 (5.5 to 7.5kW)





3-phase 400 VAC: R88D-1SN150F-ECT-51 (15 kW)



AC Servomotors 1S-series

R88M-1L□/-1M□

Contents

- Ordering Information
- Specifications
- Names and Functions
- External Dimensions





Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

ltem			Specifications		
Operating ambient temperature and humidity			0 to 40°C 20% to 90% (with no condensation)		
Storage ambie	ent temperature	and humidity	-20 to 65°C 20% to 90% (with no condensation)		
Operating and	storage atmos	ohere	No corrosive gases		
Vibration resis	stance *1		Acceleration of 49 m/s² *2 24.5 m/s² max. in X, Y, and Z directions when the motor is stopped		
Impact resista	nce		Acceleration of 98 m/s ² max. 3 times each in X, Y, and Z directions		
Insulation res	istance		Between power terminals and FG terminals: 10 M Ω min. (at 500 VDC Megger)		
Dielectric stre	ngth		Between power terminals and FG terminals: 1,500 VAC for 1 min (voltage 100 V, 200 V) Between power terminals and FG terminals: 1,800 VAC for 1 min (voltage 400 V) Between brake terminal and FG terminals: 1,000 VAC for 1 min		
Insulation class	SS		Class F		
Protective stru	ucture		IP67 (except for the through-shaft part and connector pins) IP20 if you use a 30-meter or longer encoder cable.		
International	EU Directives and UK legislation	Low Voltage	EN 60034-1/-5		
standard	UL standards		UL 1004-1/-6		
CSA standards		3	CSA C22.2 No.100 (with cUR mark)		

*1. The amplitude may be increased by machine resonance. As a guideline, 80% of the specified value must not be exceeded.

***2.** 24.5 m/s² for servomotors of 7.5 kW or more.

Note: 1. Do not use the cable when it is laying in oil or water.

2. Do not expose the cable outlet or connections to stress due to bending or its own weight.

Encoder Specifications

Item	Specifications
Encoder system	Optical batteryless absolute encoder
Resolution per rotation	23 bits
Multi-rotation data hold	16 bits
Power supply voltage	5 VDC±10%
Current consumption	230 mA max.
Output signal	Serial communications
Output interface	RS485 compliant

Note: It is possible to use an absolute encoder as an incremental encoder.

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.I696) for details.

Characteristics

3,000-r/min Servomotors

Model (R88M-)			100 VAC				
	Item	Unit	1M05030S	1M10030S	1M20030S	1M40030S	
Rated output *1	*2	W	50	100	200	400	
Rated torque *1 *2		N·m	0.159	0.318	0.637	1.27	
Rated rotation s	speed *1 *2	r/min		3,0	000	ll.	
Maximum rotati	on speed	r/min		6,0	000		
Momentary max	ximum torque *1 *3	N·m	0.48	0.95	1.91	3.8	
Rated current *	1 *2	A (rms)	1.20	1.50	2.50	4.8	
Momentary max	imum current *1	A (rms)	4.00	4.70	8.40	14.7	
	Without brake	× 10⁻⁴ kg⋅m²	0.0418	0.0890	0.2232	0.4452	
Rotor inertia	With brake	× 10⁻⁴ kg⋅m²	0.0496	0.0968	0.2832	0.5052	
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	0.810	1.62	4.80	8.40	
Torque constan	t *1	N·m/ A (rms)	0.14	0.24	0.28	0.30	
Power rate *1 *	:5	kW/s	6.7	11.9	18.5	36.6	
Mechanical time	constant *5	ms	1.7	1.1	0.76	0.61	
Electrical time o	onstant	ms	0.67	0.84	2.4	2.4	
Allowable radial	l load *6	N	68	68	245	245	
Allowable thrus	t load *6	N	58	58	88	88	
At a Laula 4	Without brake	kg	0.35	0.52	1.0	1.4	
Neight	With brake	kg	0.59	0.77	1.3	1.9	
Radiator plate d	limensions (material)	mm	250 × 250 × t6 (aluminum)				
	Excitation voltage *8	V		24 VD	C±10%		
	Current consumption (at 20°C)	Α	0.27	0.27	0.32	0.32	
	Static friction torque	N·m	0.32 min.	0.32 min.	1.37 min.	1.37 min.	
	Attraction time	ms	25 max.	25 max.	30 max.	30 max.	
	Release time *9	ms	15 max.	15 max.	20 max.	20 max.	
Brake	Backlash	0	1.2 max.	1.2 max.	1.2 max.	1.2 max.	
specifications k7	Allowable braking work	J	9	9	60	60	
· 1	Allowable total work	J	9000	9,000	60,000	60,000	
	Allowable angular acceleration	rad/s²	10,000 max.				
	Brake lifetime (acceleration/ deceleration)		10 million times min.				
	Insulation class			Cla	ss F		

For models with an oil seal, the following derating is used due to increase in friction torque.

Model (R88M-)		1M05030S-O/ -OS2/	1M10030S-O/ -OS2/	1M20030S-O/ -OS2/	1M40030S-O/ -OS2/
Item	Unit	-BO/ -BOS2	-BO/ -BOS2	-BO/ -BOS2	-BO/ -BOS2
Derating rate	%	90	95	95	80
Rated output	W	45	95	190	320
Rated current	A (rms)	1.20	1.50	2.50	4.0

Model (R88M-)			200 VAC				
	Item	Unit	1M05030T	1M10030T	1M20030T	1M40030T	1M75030T
Rated output *1 *2 W			50	100	200	400	750
Rated torque *1	*2	N·m	0.159	0.318	0.637	1.27	2.39
Rated rotation s	peed *1 *2	r/min		1	3,000	il.	I
Maximum rotati	on speed	r/min			6,000		
Momentary max	imum torque *1 *3	N⋅m	0.56 *4	1.11 *4	2.2 *4	4.5 *4	8.4 *4
Rated current *	1 *2	A (rms)	0.67	0.84	1.5	2.5	4.6
Momentary max	imum current *1	A (rms)	2.60	3.10	5.6	9.1	16.9
D - 4 !4! -	Without brake	× 10 ⁻⁴ kg·m ²	0.0418	0.0890	0.2232	0.4452	1.8242
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	0.0496	0.0968	0.2832	0.5052	2.0742
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	0.810	1.62	4.80	8.40	19.4
Torque constan	t *1	N·m/ A (rms)	0.25	0.42	0.48	0.56	0.59
Power rate *1 *	:5	kW/s	6.7	11.9	18.5	36.6	31.4
Mechanical time	constant *5	ms	1.7	1.2	0.78	0.56	0.66
Electrical time c	onstant	ms	0.67	0.83	2.4	2.6	3.3
Allowable radial	l load *6	N	68	68	245	245	490
Allowable thrus	t load *6	N	58	58	88	88	196
\A/a:b4	Without brake	kg	0.35	0.52	1.0	1.4	2.9
Weight	With brake	kg	0.59	0.77	1.3	1.9	3.9
Radiator plate d	imensions (material)	mm	250 × 250 × t6 (aluminum)				
	Excitation voltage *8	V			24 VDC±10%		
	Current consumption (at 20°C)	Α	0.27	0.27	0.32	0.32	0.37
	Static friction torque	N⋅m	0.32 min.	0.32 min.	1.37 min.	1.37 min.	2.55 min.
	Attraction time	ms	25 max.	25 max.	30 max.	30 max.	40 max.
	Release time *9	ms	15 max.	15 max.	20 max.	20 max.	35 max.
Brake	Backlash	0	1.2 max.	1.2 max.	1.2 max.	1.2 max.	1.0 max.
specifications *7	Allowable braking work	J	9	9	60	60	250
ጥ <i>1</i>	Allowable total work	J	9000	9,000	60,000	60,000	250,000
	Allowable angular acceleration	rad/s²	10,000 max.				
	Brake lifetime (acceleration/ deceleration)		10 million times min.				
	Insulation class				Class F		

For models with an oil seal, the following derating is used due to increase in friction torque.

N	lodel (R88M-)	1M05030T-O/ -OS2/	1M10030T-O/	1M20030T-O/	1M40030T-O/	1M75030T-O/
Item	Unit	-BO/ -BOS2	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2	-OS2/ -BO/ -BOS2
Derating rate	%	90	95	95	80	90
Rated output	W	45	95	190	320	675
Rated current	A (rms)	0.67	0.84	1.5	2.1	4.2

		Model (R88M-)		200 VAC						
	Item	Unit	1L1K030T	1L1K530T	1L2K030T	1L3K030T	1L4K030T	1L4K730T		
Rated output *1	*2	W	1,000	1,500	2,000	3,000	4,000	4,700		
Rated torque *1	*2	N·m	3.18	4.77	6.37	9.55	12.7	15.0		
Rated rotation s	peed *1 *2	r/min	3,000							
Maximum rotation speed r/min		r/min	5,000							
Momentary maximum torque *1 *3		N·m	9.55	14.3	19.1	28.7	38.2	47.7		
Rated current *	1 *2	A (rms)	5.2	8.8	12.5	17.1	22.8	25.7		
Momentary max	imum current *1	A (rms)	16.9	28.4	41.0	54.7	74	84.8		
5	Without brake	× 10 ⁻⁴ kg·m ²	2.1042	2.1042	2.4042	6.8122	8.8122	10.6122		
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	2.5542	2.5542	2.8542	7.3122	11.3122	13.1122		
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	35.3	47.6	60.2	118	213	279		
Torque constan	t *1	N·m/ A (rms)	0.67	0.58	0.56	0.64	0.63	0.65		
Power rate *1 *	5	kW/s	48	108	169	134 183 2		209		
Mechanical time	constant *5	ms	0.58	0.58	0.50	0.47	0.37	0.37		
Electrical time constant		ms	5.9	6.1	6.4	11	12	12		
Allowable radial load *6		N	490				880			
Allowable thrus	t load *6	N	196				343			
	Without brake	kg	5.7	5.7	6.4	11.5	13.5	16		
Weight	With brake	kg	7.4	7.4	8.1	12.5	13.5	18.5		
Radiator plate d	imensions (material)	mm	400 × 400 × t20 470 × 470 × t2 (aluminum) (aluminum)			20	540 × 540 × t20 (aluminum)			
	Excitation voltage *8	V			24 V	DC±10%				
	Current consumption (at 20°C)	Α	0.70	0.70	0.70	0.66	12.7 38.2 22.8 74 8.8122 11.3122 213 0.63 183 0.37 12 13.5 16 120 0.6 16 min. 150 max. 50 max. 0.6 max. 350 1,000,000	0.6		
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.	12.0 min.	16 min.	16 min.		
	Attraction time	ms	100 max.	100 max.	100 max.	100 max.	150 max.	150 max.		
	Release time *9	ms	30 max.	30 max.	30 max.	30 max.	50 max.	50 max.		
Brake	Backlash	٥	1.0 max.	1.0 max.	1.0 max.	0.8 max.	0.6 max.	0.6 max.		
Brake specifications k7	Allowable braking work	J	500	500	500	1,000	350	350		
~ 1	Allowable total work	J	900,000	0,000 900,000 900,000 3,000,000 1,000	1,000,000	1,000,000				
	Allowable angular acceleration	rad/s²			10,0	000 max.				
	Brake lifetime (acceleration/ deceleration)				10 millio	on times min.				
	Insulation class				С	lass F				

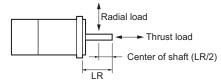
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

	Model (R88M-)			400 VAC			
	Item	Unit	1L75030C	1L1K030C	1L1K530C		
Rated output *1	*2	W	750	1,000	1,500		
Rated torque *1	*2	N·m	2.39	3.18	4.77		
Rated rotation s	speed *1 *2 r/min		3,000				
Maximum rotation speed r/min		5,000					
Momentary max	rimum torque *1 *3	N·m	7.16	9.55	14.3		
Rated current *	1 *2	A (rms)	3.0 3.0 4		4.5		
Momentary max	imum current *1	A (rms)	9.6	9.6	14.1		
Data u in autia	Without brake	× 10 ⁻⁴ kg·m ²	1.3042	2.1042	2.1042		
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	1.7542	2.5542	2.5542		
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	38.6	35.3	47.6		
Torque constan	t *1	N·m/ A (rms)	0.91	1.17	1.17		
Power rate *1 *	5	kW/s	44	48 10			
Mechanical time	e constant *5	ms	1.09	0.6 0.9			
lectrical time constant		ms	4.3	5.9	5.9		
Allowable radial	owable radial load *6 N		490				
llowable thrust load *6		N	196				
Maimbé	Without brake	kg	4.1	5.7	5.7		
weignt	With brake	kg	5.8	7.4	7.4		
Radiator plate d	limensions (material)	mm	305 × 305 × t20				
	Excitation voltage *8	V	24 VDC±10%				
	Current consumption (at 20°C)	Α	0.70	0.70	0.70		
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.		
	Attraction time	ms	100 max.	100 max.	100 max.		
	Release time *9	ms	30 max.	30 max.	30 max.		
Brake	Backlash	۰	1.0 max.	1.0 max.	1.0 max.		
specifications	Allowable braking work	J	500	500	500		
₹ <i>1</i>	Allowable total work	J	900,000	900,000	900,000		
	Allowable angular acceleration	rad/s²		10,000 max.	1,500 4.77 14.3 4.5 14.1 2.1042 2.5542 47.6 1.17 108 0.58 5.9 5.7 7.4 20 (aluminum) 0.70 9.3 min. 100 max 30 max. 1.0 max. 500		
	Brake lifetime (acceleration/ deceleration)			10 million times min.			
Rated rotation sp. Maximum rotation Momentary maxim Rated current *1 Momentary maxim Rotor inertia Applicable load in Forque constant : Power rate *1 *5 Mechanical time co Allowable radial le Allowable thrust I Radiator plate din Brake Specifications 7	Insulation class			Class F			

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

		Model (R88M-)	400 VAC						
	Item	Unit	1L2K030C	1L3K030C	1L4K030C	1L5K030C			
Rated output *1	Rated output *1 *2		2,000	3,000	4,000	5,000			
Rated torque *1	*2	N·m	6.37	9.55	12.7	15.9			
Rated rotation speed *1 *2 r/min		r/min	3,000						
Maximum rotation speed r/min		r/min	5,000						
Momentary maxi	Iomentary maximum torque *1 *3 N-		19.1	28.7	38.2	47.7			
Rated current *1	1 *2	A (rms)	6.3	8.7	12.8 13.6				
Momentary maxi	imum current *1	A (rms)	19.8	27.7	42.4	42.4			
Datan in autia	Without brake	× 10 ⁻⁴ kg⋅m²	2.4042	6.8122	8.8122	10.6122			
Rotor inertia	With brake	× 10 ⁻⁴ kg⋅m²	2.8542	7.3122	11.3122	13.1122			
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	60.2	118	213	279			
Torque constant	t *1	N·m/ A (rms)	1.15	1.23	1.11 1.32				
Power rate *1 *	5	kW/s	169	134	183 238				
Mechanical time	constant *5	ms	0.52	0.49	0.36	0.35			
Electrical time constant		ms	6.3	11	12	13			
Allowable radial load *6		N	490		880				
Allowable thrust	load *6	N	19	96	343				
Weight	Without brake	kg	6.4	11.5	13.5	16			
weignt	With brake	kg	8.1	12.5	16	18.5			
Radiator plate di	imensions (material)	mm	470) × 470 × t20 (alumin	um)	540 × 540 × t20 (aluminum)			
	Excitation voltage *8	V		24 VD	C±10%	1			
	Current consumption (at 20°C)	Α	0.70	0.66	1L4K030C 4,000 12.7 00 00 38.2 12.8 42.4 8.8122 11.3122 213 1.11 183 0.36 12 81 3.13.5 16 Im) 6±10% 0.6 16 min. 150 max. 50 max. 0.6 max. 350 1,000,000 max. imes min.	0.6			
	Static friction torque	N·m	9.3 min.	12 min.	16 min.	16 min.			
	Attraction time	ms	100 max.	100 max.	150 max.	150 max.			
	Release time *9	ms	30 max.	30 max.	50 max.	50 max.			
Brake	Backlash	0	1.0 max.	0.8 max.	0.6 max.	0.6 max.			
specifications	Allowable braking work	J	500	1,000	350	350			
*7	Allowable total work	J	900,000	3,000,000	1,000,000	1,000,000			
	Allowable angular acceleration	rad/s²		10,00	0 max.	1			
	Brake lifetime (acceleration/ deceleration)			10 million	12.8 42.4 8.8122 11.3122 213 1.11 183 0.36 12 88 34 13.5 16 um) C±10% 0.6 16 min. 150 max. 50 max. 0.6 max. 350				
	Insulation class			01	-				

- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- ***2.** The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- *3. The momentary maximum torque is approximately 300% of the rated torque, except for some models.
- *4. The momentary maximum torque is approximately 350% of the rated torque. Output at the momentary maximum torque shortens detection time of the overload protection function. Refer to Electronic Thermal Function in the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.1696) for details.
- *5. This value is for models without options.
- ***6.** The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



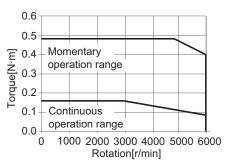
- *7. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.1696) to set an appropriate value for Brake Interlock Output (4610 hex).
- ***8.** This is a non-excitation brake. It is released when excitation voltage is applied.
- *9. This value is a reference value.

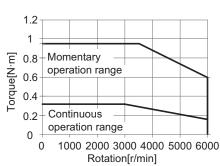
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

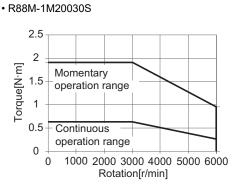
Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (100 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 100 VAC input.

• R88M-1M10030S

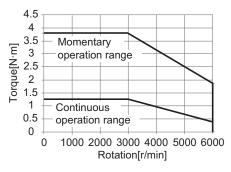






• R88M-1M40030S

R88M-1M05030S

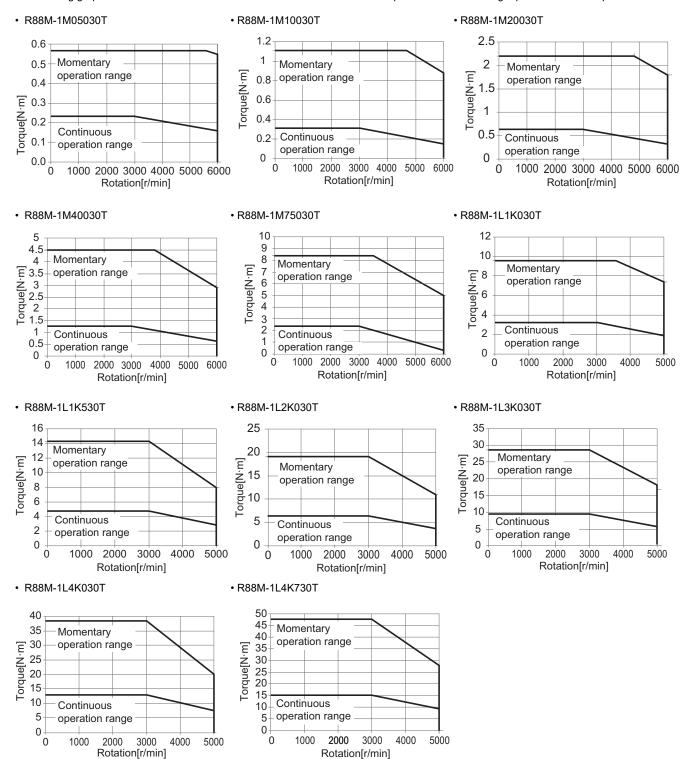


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

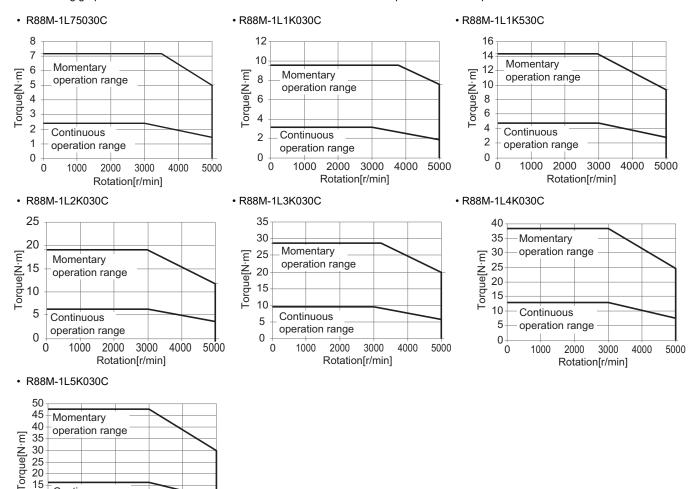


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 400 VAC input.



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

5000

4000

Continuous

1000

operation range

2000

3000

Rotation[r/min]

10

5

0

2,000-r/min Servomotors

		Model (R88M-)	200 VAC					
	Item	Unit	1M1K020T	1M1K520T	1M2K020T	1M3K020T		
Rated output *1	*2	W	1,000	1,500	2,000	3,000		
Rated torque *1	*2	N·m	4.77	7.16	9.55	14.3		
Rated rotation speed *1 *2 r/min		r/min	2,000					
Maximum rotation speed r/		r/min						
Momentary maximum torque *1		N⋅m	14.3	21.5	28.7	43.0		
Rated current *	1 *2	A (rms)	5.2 8.6 11.3		15.7			
Momentary max	imum current *1	A (rms)	16.9	28.4	40.6 54.7			
5	Without brake	× 10 ⁻⁴ kg⋅m²	6.0042	9.0042	12.2042	15.3122		
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	6.5042	9.5042	12.7042	17.4122		
Applicable load	inertia	× 10 ⁻⁴ kg⋅m²	59.0	79.9	100	142		
orque constan	t *1	N·m/ A (rms)	0.93	0.83	0.85	0.93		
Power rate *1 *	3	kW/s	38	57	75	134		
Mechanical time	constant *3	ms	0.94	0.78	0.81	0.80		
Electrical time constant		ms	13	15	14	19		
Allowable radial load *4		N	+	784				
Allowable thrust load *4		N		343				
	Without brake	kg	6.6	8.5	10	12		
Veight	With brake	kg	8.6	10.5	12	15		
Radiator plate d	imensions (material)	mm	400 × 400 × t20 (aluminum)	470	× 470 × t20 (alumin	um)		
	Excitation voltage *6	V	24 VDC±10%					
	Current consumption (at 20°C)	Α	0.51	0.51	0.66	0.60		
	Static friction torque	N⋅m	9.0 min.	9.0 min.	12 min.	16 min.		
	Attraction time	ms	100 max.	100 max.	100 max.	150 max.		
	Release time *7	ms	30 max.	30 max.	30 max.	50 max.		
Brake	Backlash	0	0.6 max.	0.6 max.	0.6 max.	0.6 max.		
pecifications	Allowable braking work	J	1,000	1,000	1,000	350		
•5	Allowable total work	J	3,000,000	3,000,000	3,000,000	1,000,000		
	Allowable angular acceleration	rad/s²	1	10,000) max.			
	Brake lifetime (acceleration/ deceleration)			10 million	11.3 40.6 12.2042 12.7042 100 0.85 75 0.81 14 10 12 × 470 × t20 (aluminu ±10% 0.66 12 min. 100 max. 30 max. 0.6 max. 1,000 3,000,000 max. imes min.			
	Insulation class			Cla	ss F			

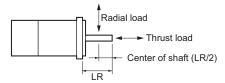
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

	Model (R88M-)			400 VAC				
	Item	Unit	1M40020C	1M60020C	1M1K020C			
Rated output *1	*2	W	400	600	1,000			
Rated torque *1	*2	N·m	1.91	2.86	4.77			
Rated rotation s	peed *1 *2	r/min		2,000				
Maximum rotation speed r/min		r/min	3,000					
Momentary max	imum torque *1	N·m	5.73	8.59	14.3			
Rated current *	1 *2	A (rms)	1.1 1.6 2.		2.9			
Momentary max	rimum current *1	A (rms)	3.9	5.5	9.4			
	Without brake	× 10 ⁻⁴ kg·m ²	2.5042	3.9042	6.0042			
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	2.8472	4.2472	6.5042			
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	19.0	23.5	59.0			
Torque constan	t *1	N·m/ A (rms)	1.75	1.84	1.69			
Power rate *1 *	3	kW/s	14.6	21.0	38			
Mechanical time	constant *3	ms	1.57 1.21 (0.94			
Electrical time c	onstant	ms	6.8	7.8	13			
Allowable radial load *4		N	490					
Allowable thrust load *4		N	196					
	Without brake	kg	3.9	4.7	6.6			
Weight	With brake	kg	4.8	5.8	8.6			
Radiator plate d	imensions (material)	mm	305 × 305 × t	12 (aluminum)	400 × 400 × t20 (aluminum)			
	Excitation voltage *6	V	24 VDC±10%					
	Current consumption (at 20°C)	A	0.30	0.30	0.51			
	Static friction torque	N·m	3.92 min.	3.92 min.	9.0 min.			
	Attraction time	ms	40 max.	40 max.	100 max.			
	Release time *7	ms	25 max.	25 max.	30 max.			
Brake	Backlash	۰	1.0 max.	1.0 max.	1,000 4.77 14.3 2.9 9.4 6.0042 6.5042 59.0 1.69 38 0.94 13 6.6 8.6 400 × 400 × t2 (aluminum) 0.51 9.0 min. 100 max.			
specifications	Allowable braking work	J	330	330	1,000			
* 5	Allowable total work	J	330,000	330,000	3,000,000			
	Allowable angular acceleration	rad/s²		10,000 max.				
	Brake lifetime (acceleration/ deceleration)			10 million times min.				
	Insulation class			Class F				

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Model (R88M-)			400 VAC			
	Item	Unit	1M1K520C	1M2K020C	1M3K020C	
Rated output *1	l * 2	W	1,500	2,000	3,000	
Rated torque *1	*2	N·m	7.16	9.55	14.3	
Rated rotation s	speed *1 *2	r/min		2,000		
Maximum rotation speed		r/min		3,000		
Momentary max	imum torque *1	N·m	21.5 28.7		43.0	
Rated current *	1 *2	A (rms)	4.1	5.7	8.6	
Momentary max	imum current *1	A (rms)	13.5	19.8	28.3	
	Without brake	× 10 ⁻⁴ kg⋅m ²	9.0042	12.2042	15.3122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	12.7042	17.4122	
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	79.9	100	142	
Torque constan	t *1	N·m/ A (rms)	1.75	1.75	1.74	
Power rate *1 *		kW/s	57	75	134	
Mechanical time	constant *3	ms	0.85	0.80	0.76	
Electrical time of	constant	ms	13 14		20	
Allowable radia	lowable radial load *4		490		784	
Allowable thrus	t load *4	N	196		343	
	Without brake	kg	8.5	10	12	
Weight	With brake	kg	10.5	12	15	
Radiator plate d	imensions (material)	mm	470 × 470 × t20 (aluminum)			
<u> </u>	Excitation voltage *6	V	24 VDC±10%			
	Current consumption (at 20°C)	Α	0.51	0.66	0.60	
	Static friction torque	N·m	9.0 min.	12 min.	16 min.	
	Attraction time	ms	100 max.	100 max.	150 max.	
	Release time *7	ms	30 max.	30 max.	50 max.	
Brake	Backlash	0	0.6 max.	0.6 max.	0.6 max.	
specifications	Allowable braking work	J	1,000	1,000	350	
* 5	Allowable total work	J	3,000,000	3,000,000	1,000,000	
	Allowable angular acceleration	rad/s²	<u> </u>	10,000 max.		
	Brake lifetime (acceleration/ deceleration)			10 million times min.		
	Insulation class			Class F		

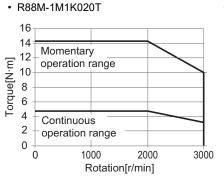
- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- *4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.

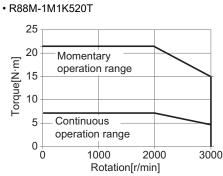


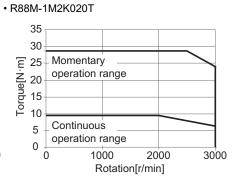
- *5. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.1696) to set an appropriate value for Brake Interlock Output (4610 hex).
- *6. This is a non-excitation brake. It is released when excitation voltage is applied.
- *7. This value is a reference value.
- Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

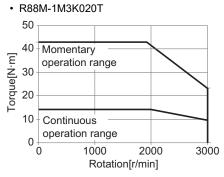
Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.







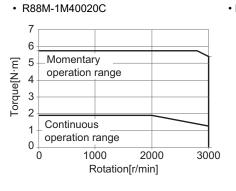


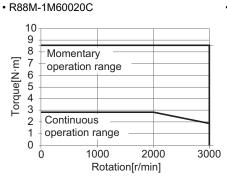
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

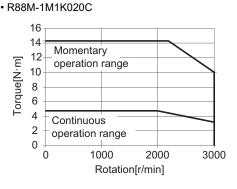
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

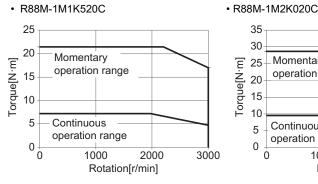
Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (400 VAC)

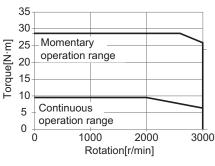
The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.

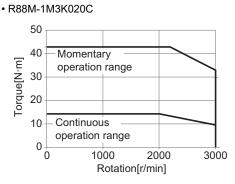












Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

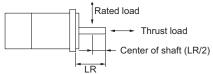
1,500-r/min Servomotors

		Model (R88M-)			200 VAC			
Item		Unit	1M4K015T	1M5K015T	1M7K515T	1M11K015T	1M15K015T	
Rated output *	1 *2	W	4,000	5,000	7,500	11,000	15,000	
Rated torque *	1 *2	N·m	25.5	31.8	47.8	70.0	95.5	
Rated rotation speed *1 *2		r/min			1,500	I	II.	
Maximum rotation speed		r/min	3,000 2,000					
Momentary maximum torque *1		N·m	75	95	119	175	224	
Rated current *1 *2		A (rms)	25.7	25.8	41.2	57	60.7	
Momentary max	ximum current *1	A (rms)	84.8	84.8	113.0	150.0	150.0	
Datau in autia	Without brake	× 10 ⁻⁴ kg·m ²	54.0122	77.0122	113.0122	229.0122	340.0122	
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	60.0122	83.0122	118.0122	253.0122	365.0122	
Applicable load	l inertia	× 10 ⁻⁴ kg·m ²	687	955	1,070	2,200	3,110	
Torque constar	nt *1	N·m/ A (rms)	1.08	1.36	1.29	1.40	1.79	
Power rate *1 *	k 3	kW/s	120	131	202	214	268	
Mechanical time	e constant *3	ms	1	1.1	0.75	0.61	0.56	
Electrical time constant		ms	19	19	24	32	32	
Allowable radial load *4		N	1,200	1,470	1,470	2,500	2,500	
Allowable thrust load *4		N	343	490	490	686	686	
NA/a:a:b4	Without brake	kg	21	29	39	63	85	
Weight With brake	With brake	kg	26	34	45	73	99	
Radiator plate o	dimensions (material)	mm	470 × 470 × t20 (aluminum)	540 × 540 × t	20 (aluminum)	670 × 630 × t	35 (aluminum)	
	Excitation voltage *6	V		24 VDC±10%				
	Current consumption (at 20°C)	Α	1.0	1.0	1.4	1.7	0.92	
	Static friction torque	N⋅m	32 min.	42 min.	54.9 min.	90 min.	100 min.	
	Attraction time	ms	150 max.	150 max.	300 max.	300 max.	600 max.	
	Release time *7	ms	60 max.	60 max.	140 max.	140 max.	215 max.	
Brake	Backlash	0	0.8 max.	0.8 max.	0.2 max.	0.2 max.	0.2 max.	
specifications *5	Allowable braking work	J	1,400	1,400	830	1,400	1,400	
で じ	Allowable total work	J	4,600,000	4,600,000	2,500,000	4,600,000	6,100,000	
	Allowable angular acceleration	rad/s²	10,000	10,000 max. 5,000 max.		3,000 max.		
	Brake lifetime (acceleration/ deceleration)			10 million times mir				
	Insulation class				Class F			

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

		Model (R88M-)		400 VAC					
Item		Unit	1M4K015C	1M5K515C	1M7K515C	1M11K015C	1M15K015C		
Rated output *	1 *2	W	4,000	5,500	7,500	11,000	15,000		
Rated torque *	1 *2	N·m	25.5	35.0	47.8	70	95.5		
Rated rotation	speed *1 *2	r/min		1	1,500	1	II.		
Maximum rotat	ion speed	r/min		3,000		2,0	000		
Momentary ma	ximum torque *1	N·m	75	95	119	175	224		
Rated current *	*1 *2	A (rms)	12.8	14.0	22.0	31.4	33.3		
Momentary ma	ximum current *1	A (rms)	42.4	42.4	56.5	80.7	81.2		
Rotor inertia	Without brake	× 10 ⁻⁴ kg·m ²	54.0122	77.0122	113.0122	229.0122	340.0122		
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	60.0122	83.0122	118.0122	253.0122	365.0122		
Applicable load	l inertia	× 10⁻⁴ kg⋅m²	687	955	1070	2200	3110		
Torque constar	nt * 1	N·m/ A (rms)	2.07	2.68	2.49	2.6	3.27		
Power rate *1	k3	kW/s	120	159	202	214	268		
Mechanical tim	e constant *3	ms	1.2	1	0.78	0.63	0.62		
Electrical time	constant	ms	18	19	23	29	29		
Allowable radial load *4		N	1,200	1,470	1470	2,500	2,500		
Allowable thrust load *4		N	343	490	490	686	686		
\Maiabt	Without brake	kg	21	29	39	63	85		
Weight	With brake	kg	26	34	45	73	99		
Radiator plate	dimensions (material)	mm	470 × 470 × t20	540 y 540y f20 (aluminum)		670 × 630 × t35 (aluminum)			
	Excitation voltage *6	V		1	24 VDC ± 10%				
	Current consumption (at 20°C)	А	1.0	1.0	1.4	1.7	0.92		
	Static friction torque	N·m	32 min.	42 min.	54.9 min.	90 min.	100 min.		
	Attraction time	ms	150 max.	150 max.	300 max.	300 max.	600 max.		
	Release time *7	ms	60 max.	60 max.	140 max.	140 max.	215 max.		
Brake	Backlash	٥	0.8 max.	0.8 max.	0.2 max.	0.2 max.	0.2 max.		
specifications *5	Allowable braking wor	k J	1,400	1,400	830	1,400	1,400		
~J	Allowable total work	J	4,600,000	4,600,000	2,500,000	4,600,000	6,100,000		
	Allowable angular acceleration	rad/s²	10,000	0 max.	5,000 max.	3,000	max.		
	Brake lifetime (acceleration/ deceleration)			1	0 million times m	in.			
	Insulation class				Class F				

- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- ***4.** The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.

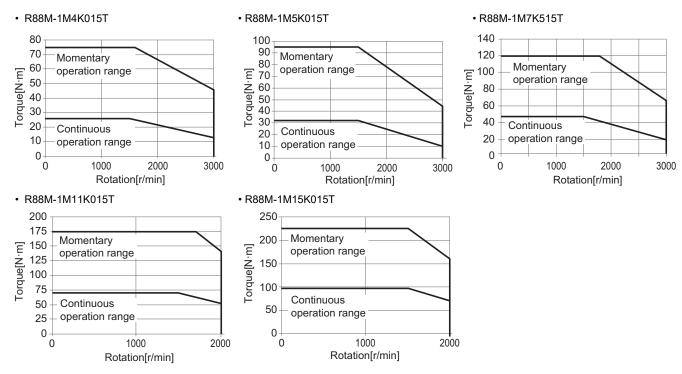


- *5. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.1696) to set an appropriate value for Brake Interlock Output (4610 hex).
- ***6.** This is a non-excitation brake. It is released when excitation voltage is applied.
- ***7.** This value is a reference value.

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC input.

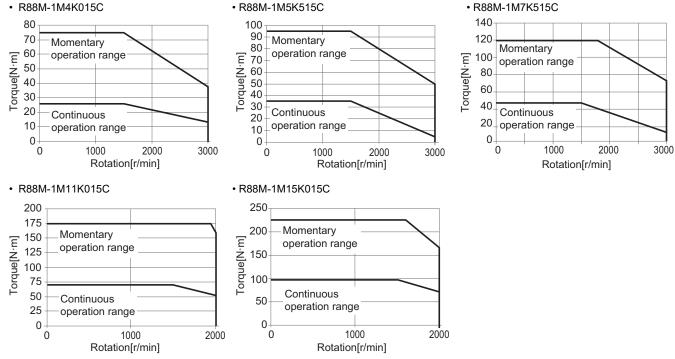


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

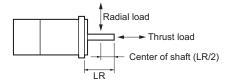
1,000-r/min Servomotors

Model (R88M-)			200 VAC					
Item U		Unit	1M90010T	1M2K010T	1M3K010T			
Rated output *1	*2	W	900	2,000	3,000			
Rated torque *1	*2	N·m	8.59	19.1	28.7			
Rated rotation s	speed *1 *2	r/min		1,000				
Maximum rotati	on speed	r/min		2,000				
Momentary max	imum torque *1	N·m	19.3	47.7	71.7			
Rated current *	1 *2	A (rms)	6.7	14.4	21.2			
Momentary max	imum current *1	A (rms)	16.9	40.6	54.7			
D - 4 ! 4! -	Without brake	× 10 ⁻⁴ kg⋅m²	9.0042	40.0122	68.0122			
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	45.1122	73.1122			
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	79.9	314	492			
Torque constan	t *1	N·m/ A (rms)	1.28	1.45	1.51			
Power rate *1 *	3	kW/s	82	91	121			
Mechanical time	constant *3	ms	0.77	1.0	0.83			
Electrical time constant		ms	15	18	22			
Allowable radial	Illowable radial load *4		686	1,176	1,470			
Allowable thrus	t load *4	N	196	490				
Majaht	Without brake	kg	8.5	18	28			
Weight	With brake	kg	10.5	22	33			
Radiator plate d	limensions (material)	mm	470 × 470 × t	540 × 540 × t20 (aluminum)				
	Excitation voltage *6	V		*				
	Current consumption (at 20°C)	Α	0.51	0.51 1.2				
	Static friction torque	N⋅m	9.0 min.	22 min.	42 min.			
	Attraction time	ms	100 max.	120 max.	150 max.			
	Release time *7	ms	30 max.	50 max.	60 max.			
Brake	Backlash	0	0.6 max.	0.8 max.	0.8 max.			
specifications *5	Allowable braking work	J	1,000	1,400	1,400			
ಗ ರ	Allowable total work	J	3,000,000	4,600,000	4,600,000			
	Allowable angular acceleration	rad/s²						
	Brake lifetime (acceleration/ deceleration)		10 million times min.					
	Insulation class			Class F				

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Model (R88M-			400 VAC					
	Item	Unit	1M90010C	1M2K010C	1M3K010C			
Rated output *1	*2	W	900	2,000	3,000			
Rated torque *1	*2	N·m	8.59	19.1	28.7			
Rated rotation s	peed *1 *2	r/min		1,000				
Maximum rotation	on speed	r/min		2,000				
Momentary max	imum torque *1	N·m	19.3	47.7	71.7			
Rated current *	1 *2	A (rms)	3.6	7.1	10.6			
Momentary max	imum current *1	A (rms)	9.0	19.5	27.7			
Datas is autic	Without brake	× 10 ⁻⁴ kg·m ²	9.0042	40.0122	68.0122			
Rotor inertia	With brake	× 10 ⁻⁴ kg·m ²	9.5042	45.1122	73.1122			
Applicable load	inertia	× 10 ⁻⁴ kg·m ²	79.9	314	492			
Forque constan	t *1	N·m/ A (rms)	2.41	3.00	2.97			
Power rate *1 *	3	kW/s	82	91	121			
Mechanical time	constant *3	ms	0.88	1.2	0.92			
Electrical time constant		ms	13	16	19			
Allowable radial load *4		N	686	1,176	1,470			
Allowable thrust load *4		N	196	490				
At - 1 - I - 4	Without brake	kg	8.5	18	28			
Neight	With brake	kg	10.5	22	33			
Radiator plate d	imensions (material)	mm	470 × 470 × t	540 × 540 × t20 (aluminum)				
	Excitation voltage *6	V		24 VDC±10%				
	Current consumption (at 20°C)	Α	0.51	1.2	1.0			
	Static friction torque	N·m	9.0 min.	22 min.	42 min.			
	Attraction time	ms	100 max.	120 max.	150 max.			
	Release time *7	ms	30 max.	50 max.	60 max.			
Brake	Backlash	0	0.6 max.	0.8 max.	0.8 max.			
specifications	Allowable braking work	J	1,000	1,400	1,400			
\$ 5	Allowable total work	J	3,000,000	4,600,000	4,600,000			
	Allowable angular acceleration	rad/s²		10,000 max.	1			
	Brake lifetime (acceleration/ deceleration)			10 million times min.				
	Insulation class			Class F				

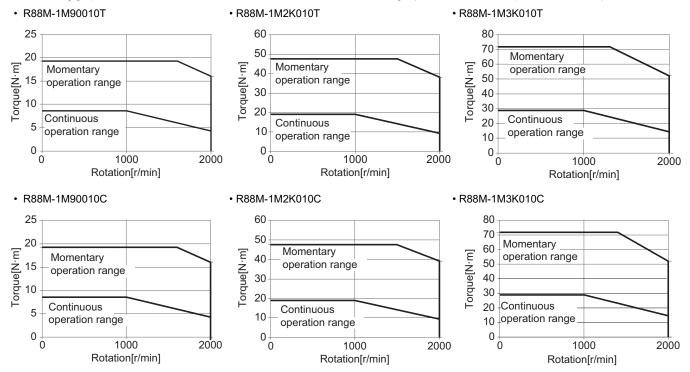
- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- ***2.** The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- ***3.** This value is for models without options.
- ***4.** The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



- *5. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.l696) to set an appropriate value for Brake Interlock Output (4610 hex).
- ***6.** This is a non-excitation brake. It is released when excitation voltage is applied.
- ***7.** This value is a reference value.
- Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Torque-Rotation Speed Characteristics for 1,000-r/min Servomotors (200 V/400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a single-phase 220-VAC or 3-phase 400-VAC input.



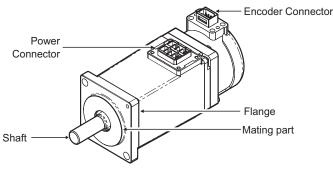
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

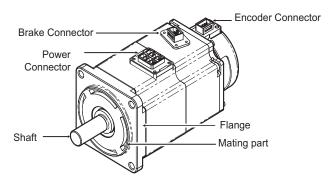
Part Names

Servomotor Part Names

Flange Size of 80 × 80 or less

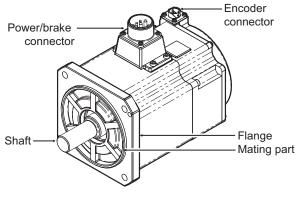


100 VAC 100 W Servomotors (without Brake)



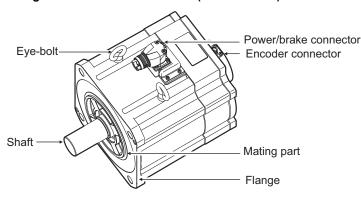
200 VAC 200 W Servomotors (with Brake)

Flange Size of 100 × 100 or more



200 VAC 1.5 kW Servomotors (with Brake)

Flange Size of 130 × 130 or more (4 kW or more)



200VAC 4kW Servomotors (with Brake)

Servomotor Functions

Shaft

The load is mounted on this shaft.

The direction which is in parallel with the shaft is called the thrust direction, and the direction which is perpendicular to the shaft is called the radial direction.

Flange

Used for mounting the Servomotor on the equipment.

Fit the mating part into the equipment and use the mounting holes to screw the Servomotor.

Power Connector

Used for supplying power to the phase U, V, and W of the Servomotor.

For Servomotors with a brake and flange size of 100 × 100 or more, the pins for power and brake are set on the same connector.

In the case of a Servomotor with its flange size □130 or more, the cable outlet direction can be selected. The change of the cable outlet direction shall be up to five times.

Encoder Connector

Used for supplying power to the encoder of the Servomotor and communicating with the Servo Drive.

When a Servomotor at 3000 r/min 4 kW or more and a Servomotor at 1500 r/min are selected, use encoder cables with metal shell type (for applicable Servomotor type B at 4 kw or more).

Brake Connector

Used for supplying power to the brake coil of the Servomotor.

This part is attached only to the Servomotors with a brake and flange size of 80×80 or less.

Eye-bolt

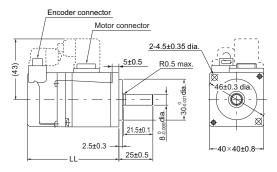
Used for lifting and moving the motor by putting a wire rope, for example, through the shaft.

External Dimensions

(Unit: mm)

3,000-r/min Servomotors (100 V and 200 V) 50 W (without Brake)

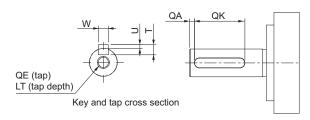
R88M-1M05030S(-O/-S2/-OS2) R88M-1M05030T(-O/-S2/-OS2)



Model	Dimensions [mm]
Wiodei	LL
R88M-1M05030S(-S2) R88M-1M05030T(-S2)	67.5±1
R88M-1M05030S-O(S2) R88M-1M05030T-O(S2)	72.5±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

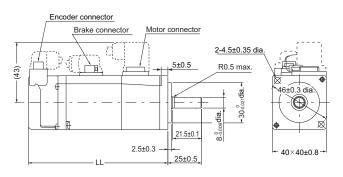
Shaft-end with key and tap



Model	Dimensions [mm]						
Woder	QA	QK	w	Т	U	QE	LT
R88M-1M05030S (-S2/-OS2)	2	12	3-0.025	3	1.2-0.2	МЗ	8
R88M-1M05030T (-S2/-OS2)	2	12	3-0.025	3	1.2.0.2	МЗ	8

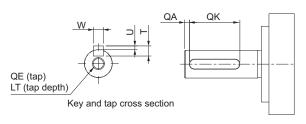
50 W (with Brake)

R88M-1M05030S-B(O/S2/OS2) R88M-1M05030T-B(O/S2/OS2)



Model	Dimensions [mm]
Wiodei	LL
R88M-1M05030S-B(S2) R88M-1M05030T-B(S2)	103.5±1
R88M-1M05030S-BO(S2) R88M-1M05030T-BO(S2)	108.5±1

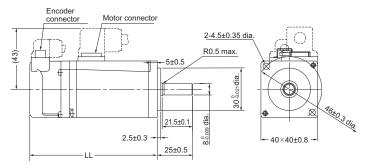
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]						
Model	QA	QK	w	Т	U	QE	LT
R88M-1M05030S-B (S2/OS2)	2	12	3-0.025	3	1.2-0.2	М3	8
R88M-1M05030T-B (S2/OS2)	2	12	3-0.025	3	1.2 0	М3	8

100 W (without Brake)

R88M-1M10030S(-O/-S2/-OS2) R88M-1M10030T(-O/-S2/-OS2)

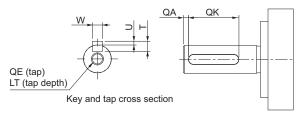


Model	Dimensions [mm]
Wodei	LL
R88M-1M10030S(-S2) R88M-1M10030T(-S2)	90±1
R88M-1M10030S-O(S2) R88M-1M10030T-O(S2)	95±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

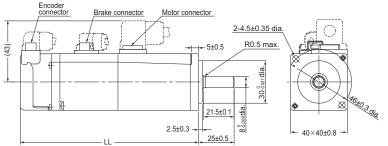
Shaft-end with key and tap



Model	Dimensions [mm]						
Wodei	QA	QK	w	Т	U	QE	LT
R88M- 1M10030S(-S2/-OS2)	2	12	3-0.025	3	1.2 0	М3	8
R88M- 1M10030T(-S2/-OS2)	2	12	3-0.025	3	1.2-0.2	МЗ	8

100 W (with Brake)

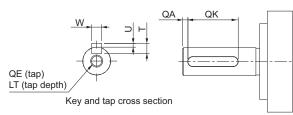
R88M-1M10030S-B(O/S2/OS2) R88M-1M10030T-B(O/S2/OS2)



Model	Dimensions [mm]
Model	LL
R88M-1M10030S-B(S2) R88M-1M10030T-BS2)	126±1
R88M-1M10030S-BO(S2) R88M-1M10030T-BO(S2)	131±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

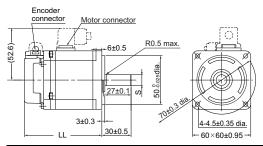
Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]							
Wodel	QA	QK	W	T	U	QE	LT	
R88M- 1M10030S-B(S2/OS2)	2	12	3-0.025	3	1.2.0.2	МЗ	8	
R88M- 1M10030T-B(S2/OS2)	2	12	3-0.025	3	1.2 0	М3	8	

200 W/400 W (without Brake)

R88M-1M20030S(-O/-S2/-OS2)/R88M-1M20030T(-O/-S2/-OS2) R88M-1M40030S(-O/-S2/-OS2)/R88M-1M40030T(-O/-S2/-OS2)

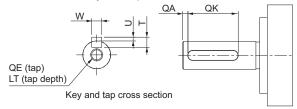


Model	Dimensions [mm]				
Model	S	LL			
R88M-1M20030S(-S2) R88M-1M20030T(-S2)	11 _{-0.011} dia.	79.5±1			
R88M-1M40030S(-S2) R88M-1M40030T(-S2)	14 _{-0.011} dia.	105.5±1			
R88M-1M20030S-O(S2) R88M-1M20030T-O(S2)	11 _{-0.011} dia.	86.5±1			
R88M-1M40030S-O(S2) R88M-1M40030T-O(S2)	14 _{-0.011} dia.	112.5±1			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

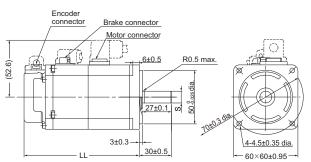
Shaft-end with key and tap



Model	Dimensions [mm]								
Model	QA	QK	W	Т	U	QE	LT		
R88M- 1M20030S(-S2/-OS2)	2	20	4-0.03	4	1.5.0.2	M4	10		
R88M- 1M20030T(-S2/-OS2)	2	20	4-0.03	4	1.5_0	M4	10		
R88M- 1M40030S(-S2/-OS2)	2	20	5-0.03	5	2.0.2	M5	12		
R88M- 1M40030T(-S2/-OS2)	2	20	5-0.03	5	2-0.2	M5	12		

200 W/400 W (with Brake)

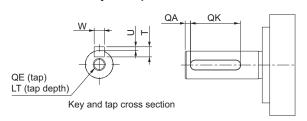
R88M-1M20030S-B(O/S2/OS2)/R88M-1M20030T-B(O/S2/OS2) R88M-1M40030S-B(O/S2/OS2)/R88M-1M40030T-B(O/S2/OS2)



Model	Dimensions [mm]				
Model	S	LL			
R88M-1M20030S-B(S2) R88M-1M20030T-B(S2)	11 _{-0.011} dia.	107.5±1			
R88M-1M40030S-B(S2) R88M-1M40030T-B(S2)	14 _{-0.011} dia.	133.5±1			
R88M-1M20030S-BO(S2) R88M-1M20030T-BO(S2)	11 _{-0.011} dia.	114.5±1			
R88M-1M40030S-BO(S2) R88M-1M40030T-BO(S2)	14 _{-0.011} dia.	140.5±1			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

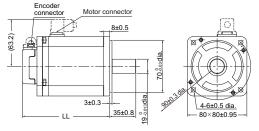
Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]							
Wodei	QA	QK	W	Т	U	QE	LT	
R88M- 1M20030S-B(S2/OS2)	2	20	4-0.03	4	1.5_0.2	M4	10	
R88M- 1M20030T-B(S2/OS2)	2	20	4-0.03	4	1.5_0	M4	10	
R88M- 1M40030S-B(S2/OS2)	2	20	5-0.03	5	2-0.2	M5	12	
R88M- 1M40030T-B(S2/OS2)	2	20	5-0.03	5	2.0.2	M5	12	

750 W (without Brake)

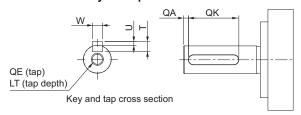
R88M-1M75030T(-O/-S2/-OS2)



Model	Dimensions [mm]
Wiodei	LL
R88M-1M75030T(-S2)	117.3±1
R88M-1M75030T-O(S2)	124.3±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

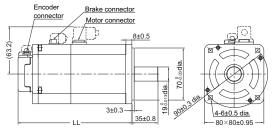
Shaft-end with key and tap



Model	Dimensions [mm]							
wodei	QA	QK	w	Т	U	QE	LT	
R88M- 1M75030T(-S2/-OS2)	3	24	6-0.03	6	2.5 0	M5	12	

750 W (with Brake)

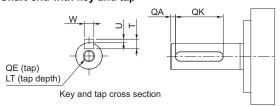
R88M-1M75030T-B(O/S2/OS2)



Model	Dimensions [mm]
Widdel	LL
R88M-1M75030T-B(S2)	153±1
R88M-1M75030T-BO(S2)	160±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

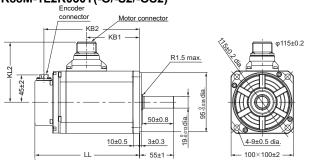
Shaft-end with key and tap



Model	Dimensions [mm]							
WOUGI	QA	QK	w	Т	U	QE	LT	
R88M- 1M75030T-B(S2/OS2)	3	24	6-0.03	6	2.5_0	M5	12	

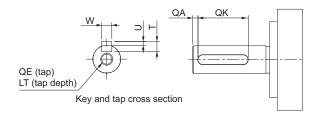
1 kW/1.5 kW/2 kW (without Brake)

R88M-1L1K030T(-O/-S2/-OS2)/R88M-1L1K530T(-O/-S2/-OS2)/ R88M-1L2K030T(-O/-S2/-OS2)



Model	Dimensions [mm]						
Woder	LL	KB1	KB2	KL2			
R88M-1L1K030T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2			
R88M-1L1K530T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2			
R88M-1L2K030T(-O/-S2/-OS2)	179±2	96±1	164±2	102±2			

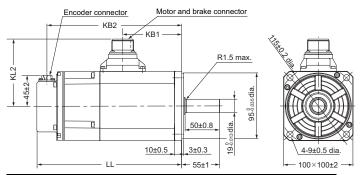
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]							
Woder	QA	QK	W	Т	U	QE	LT	
R88M- 1L1K030T(-S2/-OS2)	3	42	6-0.03	6	2.5_0.2	M5	12	
R88M- 1L1K530T(-S2/-OS2)	3	42	6-0.03	6	2.5_0	M5	12	
R88M- 1L2K030T(-S2/OS2)	3	42	6-0.03	6	2.5 _{-0.2}	M5	12	

1 kW/1.5 kW/2 kW (with Brake)

R88M-1L1K030T-B(O/S2/OS2)/R88M-1L1K530T-B(O/S2/OS2)/R88M-1L2K030T-B(O/S2/OS2)

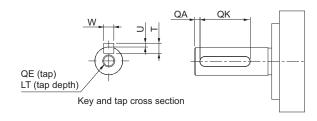


Model	Dimensions [mm]						
Wiodei	LL	KB1	KB2	KL2			
R88M-1L1K030T-B(O/S2/OS2)	209±3	85±1	194±2	97±2			
R88M-1L1K530T-B(O/S2/OS2)	209±3	85±1	194±2	97±2			
R88M-1L2K030T-B(O/S2/OS)	220±3	96±1	205±2	104±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

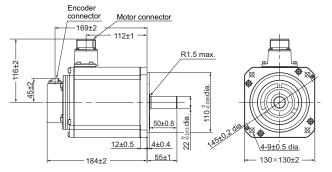
Shaft-end with key and tap



Model	Dimensions [mm]							
Wiodei	QA	QK	W	Т	U	QE	LT	
R88M- 1L1K030T-B(S2/OS2)	3	42	6-0.03	6	2.5_0	M5	12	
R88M- 1L1K530T-B(S2/OS2)	3	42	6-0.03	6	2.5_0	M5	12	
R88M- 1L2K030T-B(S2/OS2)	3	42	6-0.03	6	2.5_0	M5	12	

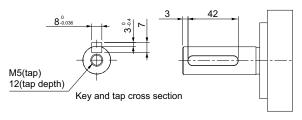
3 kW (without Brake)

R88M-1L3K030T(-O/-S2/-OS2)

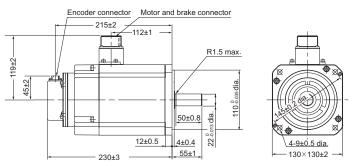


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

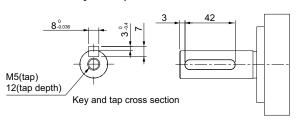
Shaft-end with key and tap



3 kW (with Brake) R88M-1L3K030T-B(O/S2/OS2)



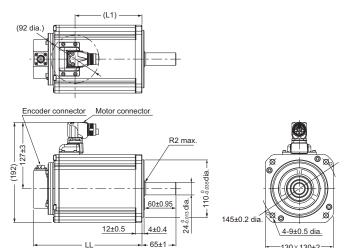
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



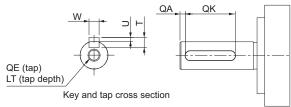
130×130±2

4 kW, 4.7 kW (without Brake)

R88M-1L4K030T(-O/-S2/-OS2) R88M-1L4K730T(-O/-S2/-OS2)



Shaft-end with key and tap



Model	Dimensions [mm]			
Model	LL	L1		
R88M-1L4K030T(-O/-S2/-OS2)	208±3	128		
R88M-1L4K730T(-O/-S2/-OS2)	232±3	152		

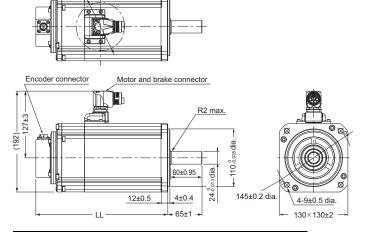
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model		Dimensions [mm]								
Model	QA	QK	W	T	U	QE	LT			
R88M-1L4K030T(-S2/-OS2)	3	52	8-0.036	7	3-0.4	M8	20			
R88M-1L4K730T(-S2/-OS2)	3	52	8-0.036	7	3-0.4	M8	20			

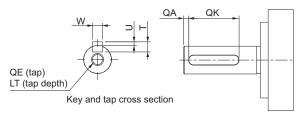
4 kW, 4.7 kW (with Brake)

R88M-1L4K030T-B(O/S2/OS2) R88M-1L4K730T-B(O/S2/OS2)

(92 dia.)



Shaft-end with key and tap



Model	Dimensions [mm]				
Wiodei	LL	L1			
R88M-1L4K030T-B(O/S2/OS2)	251±3	128			
R88M-1L4K730T-B(O/S2/OS2)	275±3	152			

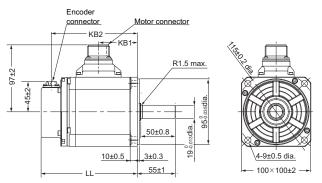
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model		Dimensions [mm]								
Wodel	QA	QK	w	T	U	QE	LT			
R88M-1L4K030T-B(S2/OS2)	3	52	8-0.036	7	3-0.4	M8	20			
R88M-1L4K730T-B(S2/OS2)	3	52	8-0.036	7	3-0.4	M8	20			

3,000-r/min Servomotors (400 V)

750 W/1 kW/1.5 kW/2 kW (without Brake)

R88M-1L75030C(-O/-S2/-OS2)/R88M-1L1K030C(-O/-S2/-OS2) R88M-1L1K530C(-O/-S2/-OS2)/R88M-1L2K030C(-O/-S2/-OS2)

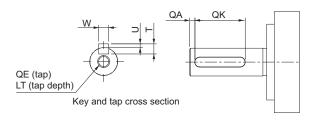


Model	Dimensions [mm]					
Model	LL	KB1	KB			
R88M-1L75030C(-O/-S2/-OS2)	139±2	56±1	124±2			
R88M-1L1K030C(-O/-S2/-OS2)	168±2	85±1	153±2			
R88M-1L1K530C(-O/-S2/-OS2)	168±2	85±1	153±2			
R88M-1L2K030C(-O/-S2/-OS2)	179±2	96±1	164±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

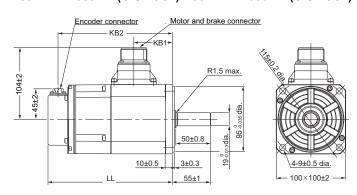
Shaft-end with key and tap



Model	Dimensions [mm]						
Wodel	QA	QA QK W		Т	U	QE	LT
R88M- 1L75030C(-S2/-OS2)	3	42	6-0.03	6	2.5_0.2	M5	12
R88M- 1L1K030C(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M- 1L1K530C(-S2/-OS2)	3	42	6-0.03	6	2.5_0.2	M5	12
R88M- 1L2K030C(-S2/-OS2)	3	42	6-0.03	6	2.5_0.2	M5	12

750 W/1 kW/1.5 kW/2 kW (with Brake)

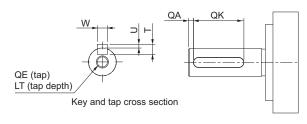
 $R88M-1L75030C-B(O/S2/OS2)/R88M-1L1K030C-B(O/S2/OS2)\\R88M-1L1K530C-B(O/S2/OS2)/R88M-1L2K030C-B(O/S2/OS2)$



Model	Dimensions [mm]					
Wodei	LL	KB1	KB			
R88M-1L75030C-B(O/S2/OS2)	180±2	56±1	165±2			
R88M-1L1K030C-B(O/S2/OS2)	209±3	85±1	194±2			
R88M-1L1K530C-B(O/S2/OS2)	209±3	85±1	194±2			
R88M-1L2K030C-B(O/S2/OS2)	220±3	96±1	205±2			

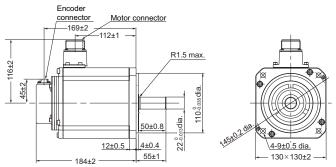
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.



Madal	Dimensions [mm]						
Model	QA	QK W		Т	U	QE	LT
R88M- 1L75030C-B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M- 1L1K030C-B(S2/OS2)	3	42	6-0.03	6	2.5_0	M5	12
R88M- 1L1K530C-B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M- 1L2K030C-B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12

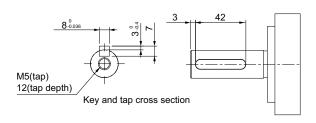
3 kW (without Brake) R88M-1L3K030C(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

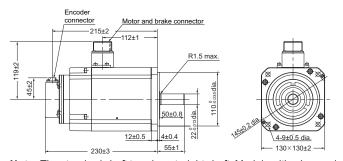
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



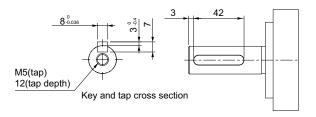
3 kW (with Brake)

R88M-1L3K030C-B(O/S2/OS2)



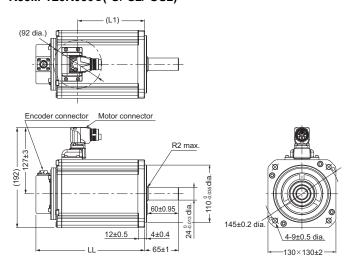
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

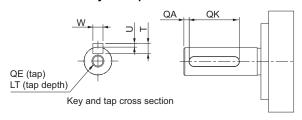


4 kW, 5 kW (without Brake)

R88M-1L4K030C(-O/-S2/-OS2) R88M-1L5K030C(-O/-S2/-OS2)



Shaft-end with key and tap



Model	Dimensions [mm]			
Model	LL	L1		
R88M-1L4K030C(-O/-S2/-OS2)	208±3	128		
R88M-1L5K030C(-O/-S2/-OS2)	232±3	152		

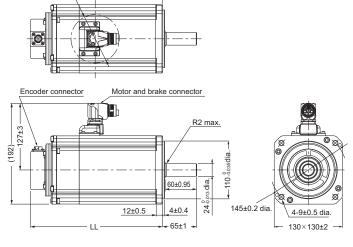
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model	Dimensions [mm]							
Wodel	QA	QK	w	Т	U	QE	LT	
R88M-1L4K030C(-S2/-OS2)	3	52	8-0.036	7	3-0.4	M8	20	
R88M-1L5K030C(-S2/-OS2)	3	52	8-0.036	7	3-0.4	M8	20	

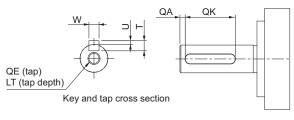
4 kW, 5 kW (with Brake)

R88M-1L4K030C-B(O/S2/OS2)

R88M-1L5K030C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]				
Wodei	LL	L1			
R88M-1L4K030C-B(O/S2/OS2)	251±3	128			
R88M-1L5K030C-B(O/S2/OS2)	275±3	152			

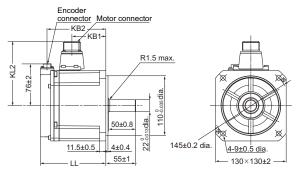
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model		Dimensions [mm]								
Wiodei	QA	QK	w	Т	U	QE	LT			
R88M-1L4K030C-B(S2/OS2)	3	52	8-0.036	7	3-0.4	M8	20			
R88M-1L5K030C-B(S2/OS2)	3	52	8-0.036	7	3-0.4	M8	20			

2,000-r/min Servomotors (200 V)

1 kW/1.5 kW/2 kW (without Brake)

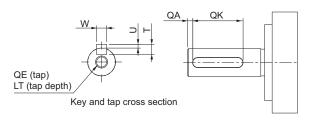
R88M-1M1K020T(-O/-S2/-OS2) R88M-1M1K520T(-O/-S2/-OS2) R88M-1M2K020T(-O/-S2/-OS2)



Model		Dimensio		
Model	LL	KB1	KB2	KL2
R88M- 1M1K020T(-O/-S2/-OS2)	120.5±2	63±1	109±2	118±2
R88M- 1M1K520T(-O/-S2/-OS2)	138±2	79±1	125±2	118±2
R88M- 1M2K020T(-O/-S2/-OS2)	160±2	99±1	147±2	116±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

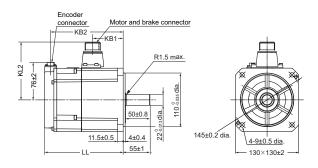
Shaft-end with key and tap



Model	Dimensions [mm]						
Woder	QA	QK	w	Т	U	QE	LT
R88M- 1M1K020T(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M1K520T(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M2K020T(-S2/-OS2)	3	42	8-0.036	7	3-0.4	M5	12

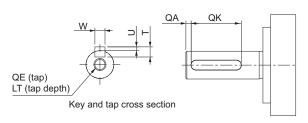
1 kW/1.5 kW/2 kW (with Brake)

R88M-1M1K020T-B (O/S2/OS2) R88M-1M1K520T-B(O/S2/OS2) R88M-1M2K020T-B(O/S2/OS2)



Model	Dimensions [mm]					
Model	LL	KB1	KB2	KL2		
R88M- 1M1K020T-B(O/S2/OS2)	162±2	63±1	149±2	118±2		
R88M- 1M1K520T-B(O/S2/OS2)	179±2	79±1	166±2	118±2		
R88M- 1M2K020T-B(O/S2/OS2)	201±3	99±1	189±2	119±2		

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



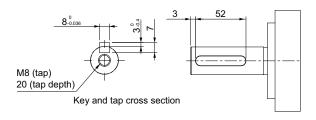
Model		Dimensions [mm]					
Model	QA	QK	w	Т	U	QE	LT
R88M- 1M1K020T-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M1K520T-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M2K020T-B(S2/OS2)	3	42	8-0.036	7	3 -0.4	M5	12

3 kW (without Brake) R88M-1M3K020T(-O/-S2/-OS2)

Encoder connector Motor connector 176±2 119±1 R1.5 max. R1.5 max. G0±0.95 G0 11.5±0.5 4±0.4 R1.5 max. 145±0.2 dia. 130×130±2 130×130±2

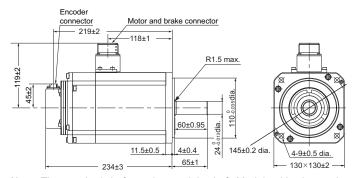
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



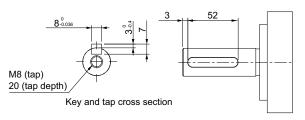
3 kW (with Brake)

R88M-1M3K020T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

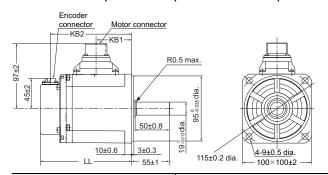
Models with an oil seal are indicated with "O" at the end of the model number.



2,000-r/min Servomotors (400 V)

400 W/600 W (without Brake)

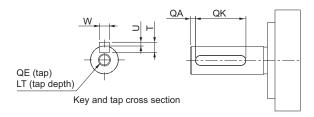
R88M-1M40020C(-O/-S2/-OS2)/R88M-1M60020C(-O/-S2/-OS2)



Model	Dimensions [mm]					
Wodel	LL	KB1	KB2			
R88M-1M40020C(-O/-S2/-OS2)	134.8±1	52±1	120.5±2			
R88M-1M60020C(-O/-S2/-OS2)	151.8±1	137.5±2				

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

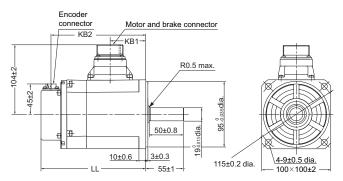
Shaft-end with key and tap



Model		Dimensions [mm]							
Wodei	QA	QK	W	Т	U	QE	LT		
R88M- 1M40020C(-S2/-OS2)	3	42	6-0.03	6	2.5_0	M5	12		
R88M- 1M60020C(-S2/-OS2)	3	42	6-0.03	6	2.5_0	M5	12		

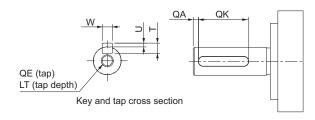
400 W/600 W (with Brake)

R88M-1M40020C-B(O/S2/OS2)/R88M-1M60020C-B(O/S2/OS2)



Model	Dimensions [mm]					
Wiodei	LL	KB1	KB2			
R88M-1M40020C-B(O/S2/OS2)	152.3±1	52±1	138±2			
R88M-1M60020C-B(O/S2/OS2)	169.3±1	69±1	155±2			

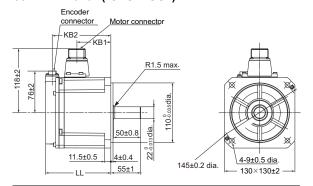
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



Model	Dimensions [mm]								
Wodel	QA	QA QK W		Т	U	QE	LT		
R88M- 1M40020C-B(S2/OS2)	3	42	6-0.03	6	2.5 0	M5	12		
R88M- 1M60020C-B(S2/OS2)	3	42	6-0.03	6	2.5.0	M5	12		

1 kW/1.5 kW/2 kW (without Brake)

R88M-1M1K020C(-O/-S2/-OS2) R88M-1M1K520C(-O/-S2/-OS2) R88M-1M2K020C(-O/-S2/-OS2)

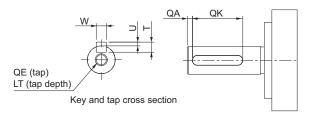


Model	Dimensions [mm]					
Model	LL	KB1	KB2			
R88M- 1M1K020C(-O/-S2/-OS2)	120.5±2	63±1	109±2			
R88M- 1M1K520C(-O/-S2/-OS2)	138±2	79±1	125±2			
R88M- 1M2K020C(-O/-S2/-OS2)	160±2	98±1	148±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

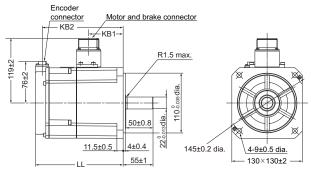


Model	Dimensions [mm]						
Wodei	QA	QK	W	Т	U	QE	LT
R88M- 1M1K020C(-S2/-OS2)	3	42	8-0.036	7	3.0.4	M5	12
R88M- 1M1K520C(-S2/-OS2)	3	42	8-0.036	7	3.0.4	M5	12
R88M- 1M2K020C(-S2/-OS2)	3	42	8-0.036	7	3.0.4	M5	12

1 kW/1.5 kW/2 kW (with Brake)

R88M-1M1K020C-B(O/S2/OS2) R88M-1M1K520C-B(O/S2/OS2)

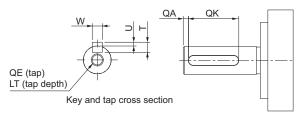
R88M-1M2K020C-B(O/S2/OS2)



Model	Dimensions [mm]					
Wodei	LL	KB1	KB2			
R88M- 1M1K020C-B(O/S2/OS2)	162±2	64±1	150±2			
R88M- 1M1K520C-B(O/S2/OS2)	179±2	81±1	167±2			
R88M- 1M2K020C-B(O/S2/OS2)	201±3	99±1	189±2			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

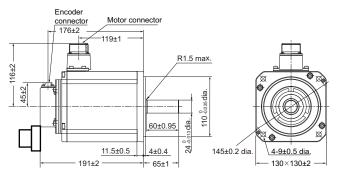
Models with an oil seal are indicated with "O" at the end of the model number.



Model		Dimensions [mm]					
Wodei	QA	QK	W	Т	U	QE	LT
R88M- 1M1K020C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M1K520C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12
R88M- 1M2K020C-B(S2/OS2)	3	42	8-0.036	7	3-0.4	M5	12

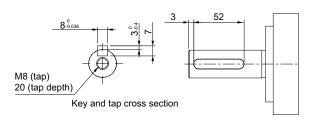
3 kW (without Brake)

R88M-1M3K020C(-O/-S2/-OS2)



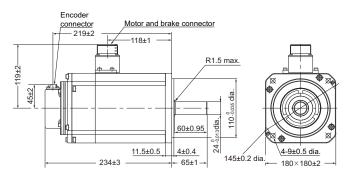
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



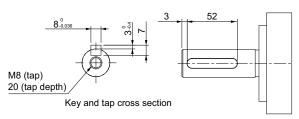
3 kW (with Brake)

R88M-1M3K020C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

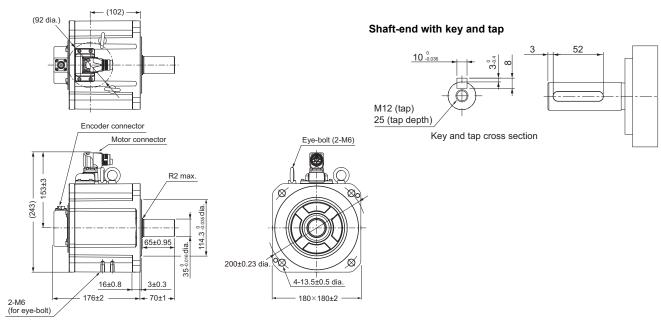
Models with an oil seal are indicated with "O" at the end of the model number.



1,500-r/min Servomotors (200 V)

4 kW (without Brake)

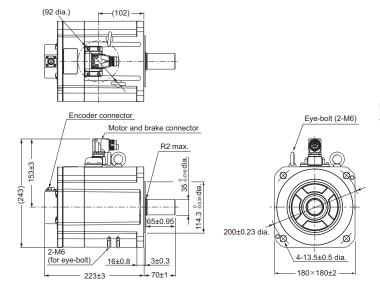
R88M-1M4K015T(-O/-S2/-OS2)



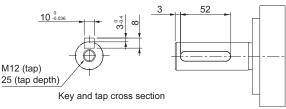
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

4 kW (with Brake)

R88M-1M4K015T-B(O/S2/OS2)

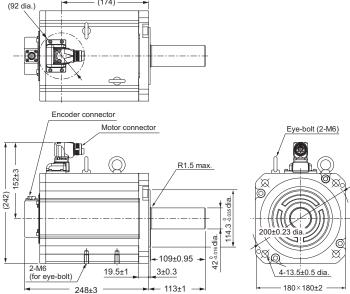


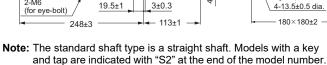
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



5 kW (without Brake)

R88M-1M5K015T(-O/-S2/-OS2)





Models with an oil seal are indicated with "O" at the end of the

12 -0.043 M16 (tap) 32 (tap depth)

Key and tap cross section

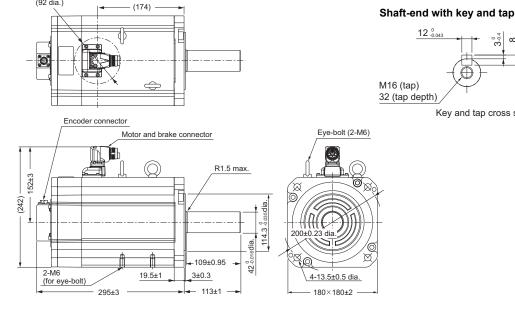
Key and tap cross section

Shaft-end with key and tap

5 kW (with Brake)

R88M-1M5K015T-B(O/S2/OS2)

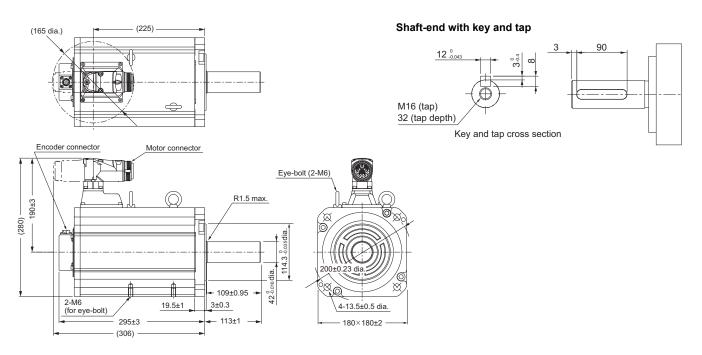
model number.



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

7.5 kW (without Brake)

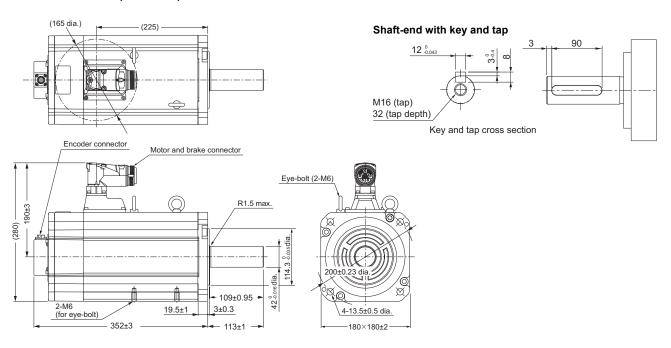
R88M-1M7K515T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

7.5 kW (with Brake)

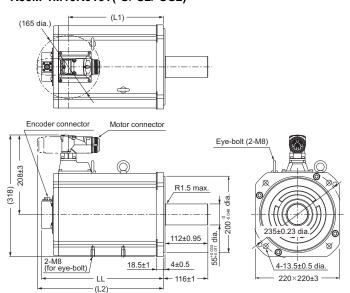
R88M-1M7K515T-B(O/S2/OS2)



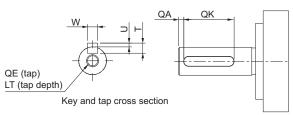
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

11 kW/15 kW (without Brake)

R88M-1M11K015T(-O/-S2/-OS2) R88M-1M15K015T(-O/-S2/-OS2)



Shaft-end with key and tap



Model	D	imensions [mr	n]
Wodel	LL	L1	L2
R88M- 1M11K015T(-O/-S2/-OS2)	319±3	249	330
R88M- 1M15K015T(-O/-S2/-OS2)	397±3	327	408

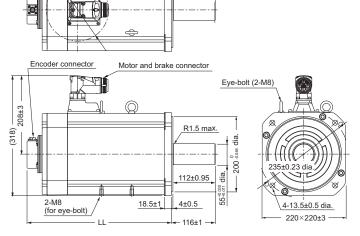
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model	Dimensions [mm]							
Wiodei	QA	QK	W	Т	U	QE	LT	
R88M- 1M11K015T(-S2/-OS2)	3	93	16 -0.043	10	4-0.4	M20	40	
R88M- 1M15K015T(-S2/-OS2)	3	93	16 -0.043	10	4-0.4	M20	40	

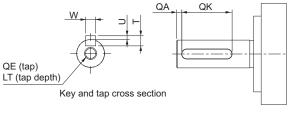
11 kW/15 kW (with Brake)

(165 dia.)

R88M-1M11K015T-B(O/S2/OS2) R88M-1M15K015T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]			
Model	LL	L1		
R88M-1M11K015T-B(O/S2/OS2)	382±3	249		
R88M-1M15K015T-B(O/S2/OS2)	493±3	327		

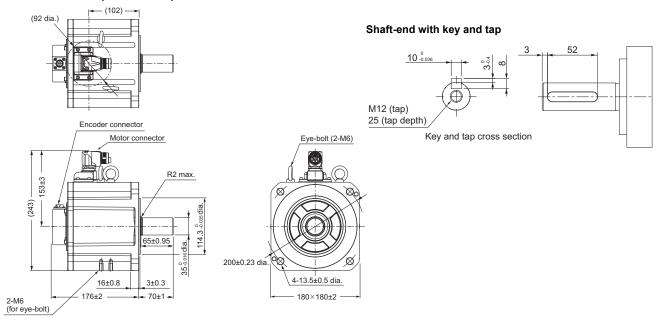
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model	Dimensions [mm]							
wiodei	QA	QK	w	Т	U	QE	LT	
R88M- 1M11K015T-B(S2/OS2)	3	93	16-0.043	10	4 -0.4	M20	40	
R88M- 1M15K015T-B(S2/OS2)	3	93	16-0.043	10	4 -0.4	M20	40	

1,500-r/min Servomotors (400 V)

4 kW (without Brake)

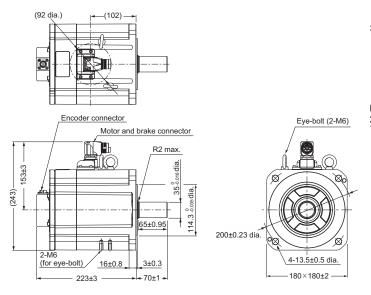
R88M-1M4K015C(-O/-S2/-OS2)



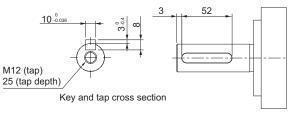
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

4 kW (with Brake)

R88M-1M4K015C-B(O/S2/OS2)

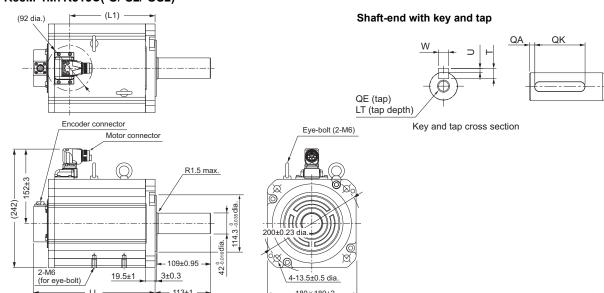


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



5.5 kW/7.5 kW (without Brake)

R88M-1M5K515C(-O/-S2/-OS2) R88M-1M7K515C(-O/-S2/-OS2)



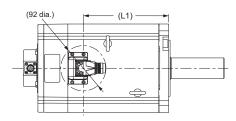
Model	Dimensions [mm]				
Wodel	LL	L1			
R88M-1M5K515C(-O/-S2/-OS2)	248±3	174			
R88M-1M7K515C(-O/-S2/-OS2)	295±3	221			

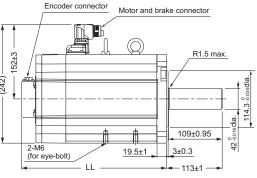
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

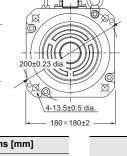
Model	Dimensions [mm]							
wodei	QA	QK	w	Т	U	QE	LT	
R88M-1M5K515C (-S2/-OS2)	3	90	12-0.043	8	3.0.4	M16	32	
R88M-1M7K515C (-S2/-OS2)	3	90	12-0.043	8	3.0.4	M16	32	

5.5 kW/7.5 kW (with Brake)

R88M-1M5K515C-B(O/S2/OS2) R88M-1M7K515C-B(O/S2/OS2)

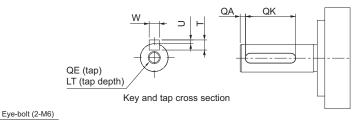






Model	Dimensions [mm]				
Model	LL	L1			
R88M-1M5K515C-B(O/S2/OS2)	295±3	174			
R88M-1M7K515C-B(O/S2/OS2)	352±3	221			
-	•				

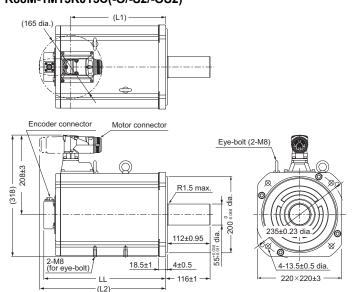
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



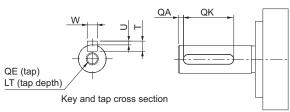
Model	Dimensions [mm]							
Woder	QA	QK	w	Т	U	QE	LT	
R88M-1M5K515C-B (S2/OS2)	3	90	12_0.043	8	3-0.4	M16	32	
R88M-1M7K515C-B (S2/OS2)	3	90	12-0.043	8	3-0.4	M16	32	

11 kW/15 kW (without Brake)

R88M-1M11K015C(-O/-S2/-OS2) R88M-1M15K015C(-O/-S2/-OS2)



Shaft-end with key and tap



Model	Dimensions [mm]					
Wodel	LL	L1	L2			
R88M- 1M11K015C(-O/-S2/-OS2)	319±3	249	330			
R88M- 1M15K015C(-O/-S2/-OS2)	397±3	327	408			

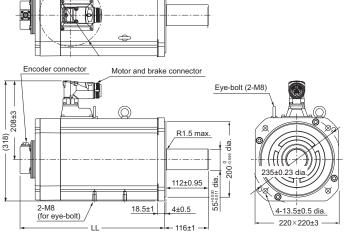
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Model	Dimensions [mm]							
Wodei	QA	QK	w	Т	U	QE	LT	
R88M- 1M11K015C(-S2/-OS2)	3	93	16 -0.043	10	4_0.4	M20	40	
R88M- 1M15K015C(-S2/-OS2)	3	93	16 -0.043	10	4-0.4	M20	40	

11 kW/15 kW (with Brake)

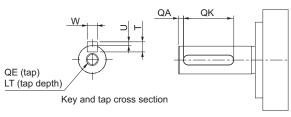
(165 dia.)

R88M-1M11K015C-B(O/S2/OS2) R88M-1M15K015C-B(O/S2/OS2)



Model	Dimensions [mm]				
Model	LL	L1			
R88M-1M11K015C-B(O/S2/OS2)	382±3	249			
R88M-1M15K015C-B(O/S2/OS2)	493±3	327			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

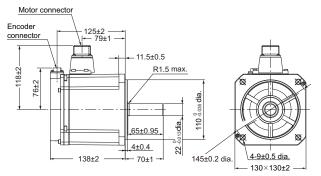


Model	Dimensions [mm]								
Wiodei	QA	QK	w	Т	U	QE	LT		
R88M- 1M11K015C-B(S2/OS2)	3	93	16-0.043	10	4 -0.4	M20	40		
R88M- 1M15K015C-B(S2/OS2)	3	93	16-0.043	10	4 -0.4	M20	40		

1,000-r/min Servomotors (200 V)

900 W (without Brake)

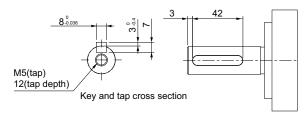
R88M-1M90010T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

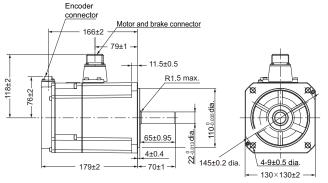
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



900 W (with Brake)

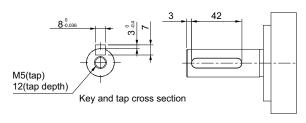
R88M-1M90010T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

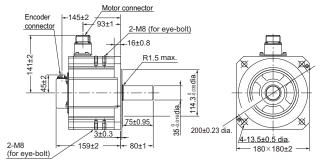
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



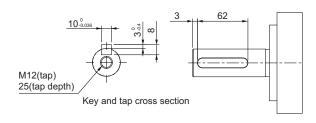
2 kW (without Brake)

R88M-1M2K010T(-O/-S2/-OS2)



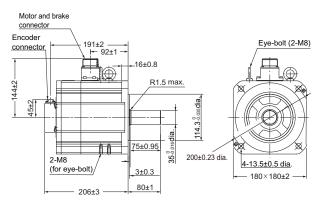
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

Models with an oil seal are indicated with "O" at the end of the model number.

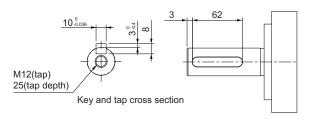


2 kW (with Brake)

R88M-1M2K010T-B(O/S2/OS2)



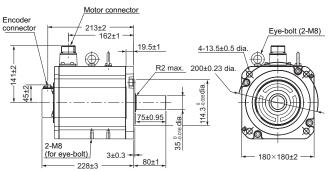
Shaft-end with key and tap



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

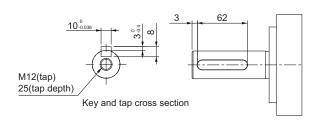
3 kW (without Brake)

R88M-1M3K010T(-O/-S2/-OS2)



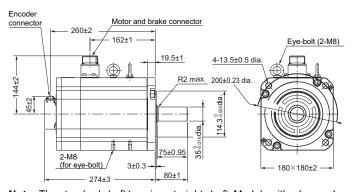
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

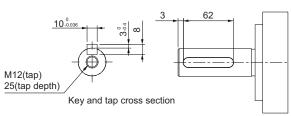


3 kW (with Brake)

R88M-1M3K010T-B(O/S2/OS2)



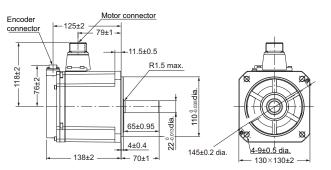
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



1,000-r/min Servomotors (400 V)

900 W (without Brake)

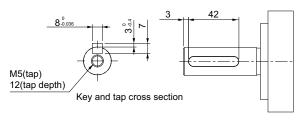
R88M-1M90010C(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

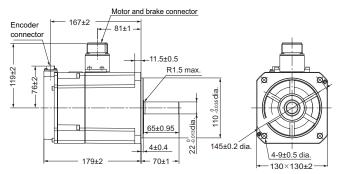
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



900 W (with Brake)

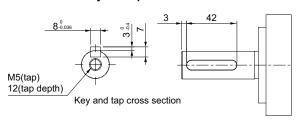
R88M-1M90010C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.

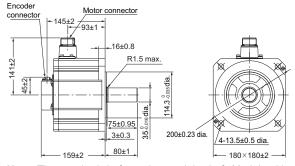
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

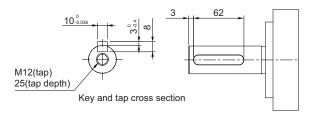


2 kW (without Brake)

R88M-1M2K010C(-O/-S2/-OS2)

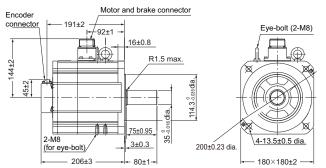


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.



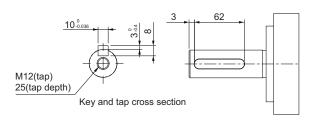
2 kW (with Brake)

R88M-1M2K010C-B(O/S2/OS2)



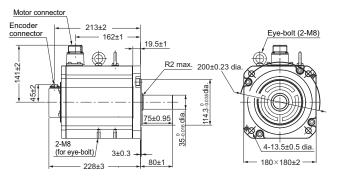
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



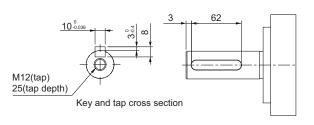
3 kW (without Brake)

R88M-1M3K010C(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

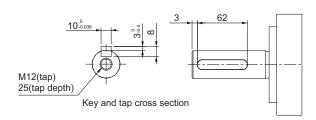


3 kW (with Brake) R88M-1M3K010C-B(O/S2/OS2)

Eve-bolt (2-M8) 144±2 200±0.23 dia 45±2 2-M8 (for eye-bolt) 3±0.3 80±1 180×180±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

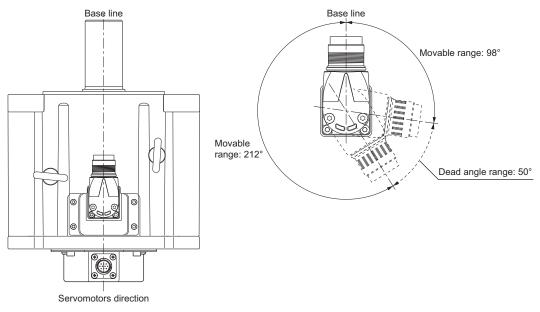
274±3



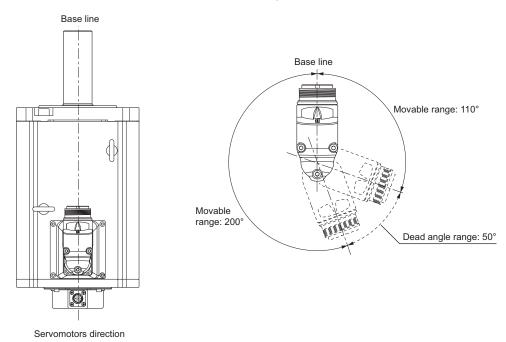
AC Servo System 1S-series with SS1/SLS Safety Sub-Functions Cable Outlet Direction of Connector

The cable outlet direction of the servomotor for connector type M23 or M40 can be selected. The below shows the selectable range. The change of the cable outlet direction shall be up to five times. For a procedure of the change of the cable outlet direction, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat.No.I696).

Cable Outlet Direction of Connector Type M23



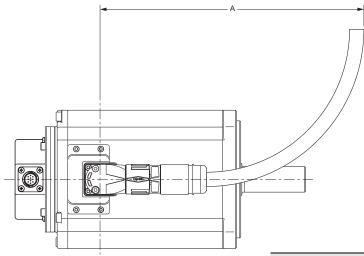
Cable Outlet Direction of Connector Type M40



Cable Wiring Dimension for a Case of Servo Motor Installing

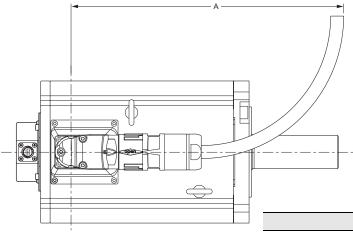
Cable wiring dimensions are shown below the table when you install a Servomotor with connector type M23 or connector type M40. The dimensions from the rotation center of the connector to the cable surrounding are indicated as A.

Servo Motor for Connector Type M23



Model	A (mm)
R88M-1L4K030T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1L4K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1L4K730T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1L5K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M4K015T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	265
R88M-1M4K015C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M5K015T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M5K515C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M7K515C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	

Servo Motor for Connector Type M40



Model	A (mm)
R88M-1M7K515T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M11K015T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M11K015C (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	356
R88M-1M15K015T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M15K015C (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	356

Decelerator AC Servo System [1S-series]

R88G-HPG/VRXF

Contents

- Ordering Information
- Specifications
- External Dimensions





Ordering Information

Refer to the Ordering Information.

Specifications

Backlash: 3 Arcminutes Max.

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10 ⁻⁴ kg·m ²	N	N	kg
50 W (100 V)	1/21	R88G-HPG14A21100B□	142	2.1	62.6	285	8.4	0.05	340	1358	1.0
	1/33	R88G-HPG14A33050B□	90	3.6	68.4	181	13.4	0.044	389	1555	1.0
	1/45	R88G-HPG14A45050B□	66	4.9	68.4	133	18.3	0.044	427	1707	1.0
	1/21	R88G-HPG14A21100B□	142	2.1	62.6	285	9.9	0.05	340	1358	1.0
50 W (200 V)	1/33	R88G-HPG14A33050B□	90	3.6	68.4	181	15.9	0.044	389	1555	1.0
(200 1)	1/45	R88G-HPG14A45050B□	66	4.9	68.4	133	21.7	0.044	427	1707	1.0
	1/5	R88G-HPG11B05100B□	600	1.2	77.0	1200	4.2	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B□	272	2.5	72.1	545	9.0	0.06	280	1119	1.0
100 W (100 V)	1/21	R88G-HPG14A21100B□	142	5.2	77.8	285	17.5	0.05	340	1358	1.0
(100 V)	1/33	R88G-HPG20A33100B□	90	6.8	65.2	181	26.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B□	66	9.8	68.2	133	37.1	0.063	1006	3541	2.4
100 W (200 V)	1/5	R88G-HPG11B05100B□	600	1.2	77.0	1200	4.9	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B□	272	2.5	72.1	545	10.6	0.06	280	1119	1.0
	1/21	R88G-HPG14A21100B□	142	5.2	77.8	285	20.7	0.05	340	1358	1.0
	1/33	R88G-HPG20A33100B□	90	6.8	65.2	181	31.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B□	66	9.8	68.2	133	44.0	0.063	1006	3541	2.4
	1/5	R88G-HPG14A05200B□	600	2.4	75.4	1200	8.3	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B□	272	5.8	82.6	545	18.8	0.197	280	1119	1.1
200 W (100 V)	1/21	R88G-HPG20A21200B□	142	10.2	76.2	285	35.9	0.49	800	2817	2.9
	1/33	R88G-HPG20A33200B□	90	17.0	80.6	181	57.3	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B□	66	23.5	82.1	133	78.5	0.45	1006	3541	2.9
	1/5	R88G-HPG14A05200B□	600	2.4	75.4	1200	9.7	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B□	272	5.8	82.6	545	21.8	0.197	280	1119	1.1
200 W (200 V)	1/21	R88G-HPG20A21200B□	142	10.2	76.2	285	41.7	0.49	800	2817	2.9
	1/33	R88G-HPG20A33200B□	90	17.0	80.6	181	66.5	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B□	66	23.5	82.1	133	91.1	0.45	1006	3541	2.9
400 W (100 V)	1/5	R88G-HPG14A05400B□	600	5.3	84.2	1200	17.1	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B□	272	11.4	81.6	545	38.1	0.57	659	2320	2.9
	1/21	R88G-HPG20A21400B□	142	23.0	86.1	285	74.0	0.49	800	2817	2.9
	1/33	R88G-HPG32A33400B□	90	33.8	80.7	181	114.0	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B□	66	46.6	81.5	133	155.9	0.61	1718	6848	7.5

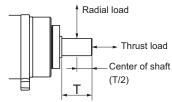
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10 ⁻⁴ kg⋅m ²	N	N	kg
400 W (200 V)	1/5	R88G-HPG14A05400B□	600	5.3	84.2	1200	20.4	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B□	272	11.4	81.6	545	45.5	0.57	659	2320	2.9
	1/21	R88G-HPG20A21400B□	142	23.0	86.1	285	88.1	0.49	800	2817	2.9
	1/33	R88G-HPG32A33400B□	90	33.8	80.7	181	136.2	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B□	66	46.6	81.5	133	186.1	0.61	1718	6848	7.5
	1/5	R88G-HPG20A05750B□	600	9.9	82.9	1200	38.7	0.68	520	1832	2.9
	1/11	R88G-HPG20A11750B□	272	20.0 * 1	87.2	545	86.7	0.6	659	2320	3.1
750 W (200 V)	1/21	R88G-HPG32A21750B□	142	42.1	84.0	285	163.3	3.0	1367	5448	7.8
, ,	1/33	R88G-HPG32A33750B□	90	69.3	87.9	181	259.7	2.7	1565	6240	7.8
	1/45	R88G-HPG32A45750B□	66	94.9	88.3	133	299.0 *2	2.7	1718	6848	7.8
	1/5	R88G-HPG32A052K0B□	600	7.7	64.3	1000	30.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	20.5	78.0	454	70.9	3.4	1126	4488	7.9
750 W (400 V)	1/21	R88G-HPG32A211K5B□	142	42.1	84.0	238	138.3	3.0	1367	5448	7.9
(400 V)	1/33	R88G-HPG32A33600SB□	90	69.3	87.9	151	220.4	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B□	66	92.0	85.5	111	298.0	4.7	4538	15694	19.0
1 kW	1/5	R88G-HPG32A052K0B□	600	11.5	72.2	1000	42.0	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	28.9	82.5	454	96.1	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B□	142	58.1	86.9	238	186.5	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B□	90	90.9	86.7	151	292.7	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B□	66	126.1	88.1	111	401.3	4.7	4538	15694	19.0
	1/5	R88G-HPG32A052K0B□	600	19.1	80.1	1000	64.8	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	45.7	87.0	454	146.3	3.4	1126	4488	7.9
1.5 kW	1/21	R88G-HPG32A211K5B□	142	90.1	90.0	238	282.2	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B□	90	141.3	89.8	151	443.2	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B□	66	194.8	90.8	111	606.5	4.7	4538	15694	19.0
	1/5	R88G-HPG32A052K0B□	600	26.8	84.1	1000	87.9	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	272	62.5	89.3	454	197.0	3.4	1126	4488	7.9
2 kW	1/21	R88G-HPG50A212K0B□	142	119.0	89.0	238	375.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0B□	90	192.0	91.3	151	595.3	4.8	4135	14300	19.0
	1/5	R88G-HPG32A053K0B□	600	42.0	88.1	1000	134.0	3.8	889	3542	7.3
3 kW	1/11	R88G-HPG50A113K0B□	272	93.9	89.3	454	296.1	7.7	2974	10285	19.0
	1/21	R88G-HPG50A213K0B□	142	183.1	91.3	238	569.2	5.8	3611	12486	19.0
	1/5	R88G-HPG32A054K0B□	600	57.2	90.0	1000	179.6	3.8	889	3542	7.9
4 kW	1/11	R88G-HPG50A115K0B□	272	127.1	91.0	454	396.4	8.8	2974	10285	19.1
4.7 kW	1/5	R88G-HPG50A055K0B□	600	65.6	87.4	1000	222.5	12.0	2347	8118	18.6
	1/11	R88G-HPG50A115K0B□	272	151.4	91.8	454	496.7	8.8	2974	10285	19.1
	1/5	R88G-HPG50A055K0B□	600	69.9	87.9	1000	222.5	12.0	2347	8118	18.6
5 kW	1/11	R88G-HPG50A115K0B	272	160.9	92.0	454	496.7	8.8	2974	10285	19.1
14 71		wable continuous output to								10200	10.1

*1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

*2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

- The protective structure rating of the Servomotor with the Decelerator is IP44.
 The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- **4.** The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the model number.
- **5.** Take care so that the surface temperature of the Decelerator does not exceed 70°C.

● For 2,000-r/min Servomotors

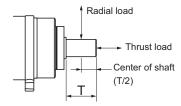
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N·m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG32A052K0B□	400	6.5	68.4	600	24.9	3.8	889	3542	7.4
400 W	1/11	R88G-HPG32A112K0B□	181	16.8	79.9	272	57.1	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B□	95	34.0	84.9	142	111.1	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB□	60	55.6	88.2	90	176.6	2.7	1565	6240	7.9
	1/45	R88G-HPG32A45400SB□	44	76.0	88.5	66	241.1	2.7	1718	6848	7.9
	1/5	R88G-HPG32A052K0B□	400	11.1	77.6	600	38.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B□	181	26.8	85.3	272	87.3	3.4	1126	4488	7.9
600 W	1/21	R88G-HPG32A211K5B□	95	53.2	88.6	142	168.7	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB□	60	85.7	90.8	90	267.2	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B□	44	115.1	89.4	66	362.6	4.7	4538	15694	19.0
1 kW	1/5	R88G-HPG32A053K0B□	400	20.3	85.0	600	66.0	3.8	889	3542	7.3
	1/11	R88G-HPG32A112K0SB□	181	47.0	89.6	272	147.6	3.4	1126	4488	7.8
	1/21	R88G-HPG32A211K0SB□	95	91.7	91.5	142	283.8	2.9	1367	5448	7.8
	1/33	R88G-HPG50A332K0SB□	60	143.9	91.4	90	445.8	4.7	4135	14300	19.0
	1/45	R88G-HPG50A451K0SB□	44	197.6	92.1	66	609.3	4.7	4538	15694	19.0
	1/5	R88G-HPG32A053K0B□	400	31.7	88.7	600	100.6	3.8	889	3542	7.3
1.5 kW	1/11	R88G-HPG32A112K0SB□	181	72.2	91.7	272	223.7	3.4	1126	4488	7.8
1.5 KVV	1/21	R88G-HPG50A213K0B□	95	137.6	91.5	142	426.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB□	60	219.6	92.9	90	673.9	4.7	4135	14300	19.0
	1/5	R88G-HPG32A053K0B□	400	43.2	90.5	600	135.1	3.8	889	3542	7.3
2 kW	1/11	R88G-HPG32A112K0SB□	181	97.5	92.8	272	299.7	3.4	1126	4488	7.8
Z RVV	1/21	R88G-HPG50A213K0B□	95	185.8	92.7	142	571.9	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB□	60	270.0 *1	93.5	90	849.0 *2	4.7	4135	14300	19.0
3 kW	1/5	R88G-HPG32A054K0B□	400	66.0	92.3	600	203.8	3.8	889	3542	7.9
	1/11	R88G-HPG50A115K0B□	181	146.1	92.9	272	449.2	8.8	2974	10285	19.1
JAW	1/21	R88G-HPG50A213K0SB□	95	260.0 *1	93.6	142	849.0 *2	6.9	3611	12486	19.1
	1/25	R88G-HPG65A253K0SB	80	322.9	90.3	120	1011.7	14	7846	28654	52.0

*1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

*2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

- 2. The protective structure rating of the Servomotor with the Decelerator is IP44.
- 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).

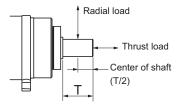


- **4.** The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at \square of the model number.
- 5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

● For 1,500-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG50A055K0SB□	300	119.0	93.4	600	356.6	11	2347	8118	22.0
4 kW	1/11	R88G-HPG50A115K0SB□	136	217.9 *	94.3	272	788.2	8.4	2974	10285	23.5
4 KVV	1/20	R88G-HPG65A205K0SB□	75	474.9	93.1	150	1425.3	14	7338	26799	55.4
	1/25	R88G-HPG65A255K0SB□	60	596.0	93.5	120	1784.0	14	7846	28654	55.4
	1/5	R88G-HPG50A054K5TB□	300	149.3	93.9	600	452.6	12	2347	8118	22.0
5 kW	1/12	R88G-HPG65A127K5SB□	125	354.1	92.8	250	1082.2	66	6295	22991	52.0
	1/20	R88G-HPG65A204K5TB□	75	595.9	93.7	150	1809.3	53	7338	26799	52.0
	1/5	R88G-HPG50A054K5TB□	300	164.6	94.1	600	452.6	12	2347	8118	22.0
5.5 kW	1/12	R88G-HPG65A127K5SB□	125	391.0	93.1	250	1082.2	66	6295	22991	52.0
	1/20	R88G-HPG65A204K5TB□	75	657.3	93.9	150	1809.3	53	7338	26799	52.0

- *The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.
- Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.
 - 2. The protective structure rating of the Servomotor with the Decelerator is IP44.
 - 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).

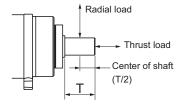


- **4.** The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the model number.
- 5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

● For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N·m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-HPG32A05900TB□	200	39.8	92.6	400	91.2	3.8	889	3542	7.9
900 W	1/11	R88G-HPG32A11900TB□	90	88.7	93.9	181	201.8	3.4	1126	4488	8.4
900 W	1/21	R88G-HPG50A21900TB□	47	169.2	93.8	95	385.1	7.0	3611	12486	19.1
	1/33	R88G-HPG50A33900TB□	30	267.5	94.4	60	606.8	5.9	4135	14300	19.1
	1/5	R88G-HPG32A052K0TB□	200	90.2	94.5	400	227.5	5.2	889	3542	8.90
2 kW	1/11	R88G-HPG50A112K0TB□	90	198.9	94.7	181	500.9	8.4	2974	10285	20.1
Z KVV	1/21	R88G-HPG50A212K0TB□	47	320.1 *1	94.8	95	849.0 *2	6.5	3611	12486	20.1
	1/25	R88G-HPG65A255K0SB□	40	446.7	93.6	80	1133.1	14	7846	28654	55.4
	1/5	R88G-HPG50A055K0SB□	200	135.4	94.4	400	341.8	11	2347	8118	22.0
3 kW	1/11	R88G-HPG50A115K0SB□	90	246.2 *1	94.9	181	754.4	8.4	2974	10285	23.5
3 KVV	1/20	R88G-HPG65A205K0SB□	50	540.4	94.2	100	1366.0	14	7338	26799	55.4
	1/25	R88G-HPG65A255K0SB□	40	677.1	94.4	80	1709.1	14	7846	28654	55.4

- *1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.
- *2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.
- Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.
 - 2. The protective structure rating of the Servomotor with the Decelerator is IP44.
 - 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- 4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the model number.
- 5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

Backlash: 15 Arcminutes Max.

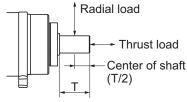
● For 3,000-r/min Servomotors

Servomotor rated output	Reduc- tion ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N⋅m	%	r/min	N·m	× 10 ⁻⁴ kg·m ²	N	N	kg
	1/5	R88G-VRXF05B100CJ	600	0.65	82	1200	1.97	0.060	392	196	0.55
50 W	1/9	R88G-VRXF09B100CJ	333	1.17	82	667	3.54	0.050	441	220	0.55
(100 V)	1/15	R88G-VRXF15B100CJ	200	1.84	77	400	5.54	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	3.06	77	240	9.24	0.051	686	343	0.70
	1/5	R88G-VRXF05B100CJ	600	0.65	82	1200	2.30	0.060	392	196	0.55
50 W	1/9	R88G-VRXF09B100CJ	333	1.17	82	667	4.13	0.050	441	220	0.55
(200 V)	1/15	R88G-VRXF15B100CJ	200	1.84	77	400	6.47	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	3.06	77	240	10.78	0.051	686	343	0.70
	1/5	R88G-VRXF05B100CJ	600	1.43	90	1200	4.28	0.060	392	196	0.55
100 W	1/9	R88G-VRXF09B100CJ	333	2.58	90	667	7.70	0.050	441	220	0.55
(100 V)	1/15	R88G-VRXF15B100CJ	200	4.10	86	400	12.26	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	6.84	86	240	20.43	0.051	686	343	0.70
	1/5	R88G-VRXF05B100CJ	600	1.43	90	1200	5.00	0.060	392	196	0.55
100 W	1/9	R88G-VRXF09B100CJ	333	2.58	90	667	8.23 *	0.050	441	220	0.55
(200 V)	1/15	R88G-VRXF15B100CJ	200	4.10	86	400	14.10 *	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	6.84	86	240	21.90 *	0.051	686	343	0.70
	1/5	R88G-VRXF05B200CJ	600	2.93	92	1200	8.79	0.147	392	196	0.72
200 W	1/9	R88G-VRXF09C200CJ	333	4.76	83	667	14.27	0.273	931	465	1.70
(100 V)	1/15	R88G-VRXF15C200CJ	200	8.22	86	400	24.64	0.302	1176	588	2.10
	1/25	R88G-VRXF25C200CJ	120	13.70	86	240	41.07	0.293	1323	661	2.10
	1/5	R88G-VRXF05B200CJ	600	2.93	92	1200	9.94 *	0.147	392	196	0.72
200 W	1/9	R88G-VRXF09C200CJ	333	4.76	83	667	16.43	0.273	931	465	1.70
(200 V)	1/15	R88G-VRXF15C200CJ	200	8.22	86	400	28.38	0.302	1176	588	2.10
	1/25	R88G-VRXF25C200CJ	120	13.70	86	240	47.30	0.293	1323	661	2.10
	1/5	R88G-VRXF05C400CJ	600	5.59	88	1200	16.72	0.370	784	392	1.70
400 W	1/9	R88G-VRXF09C400CJ	333	10.06	88	667	30.10	0.273	931	465	1.70
(100 V)	1/15	R88G-VRXF15C400CJ	200	16.95	89	400	50.73	0.302	1176	588	2.10
	1/25	R88G-VRXF25C400CJ	120	28.26	89	240	84.55	0.293	1323	661	2.10
	1/5	R88G-VRXF05C400CJ	600	5.59	88	1200	19.80	0.370	784	392	1.70
400 W	1/9	R88G-VRXF09C400CJ	333	10.06	88	667	34.00 *	0.273	931	465	1.70
(200 V)	1/15	R88G-VRXF15C400CJ	200	16.95	89	400	56.70 *	0.302	1176	588	2.10
	1/25	R88G-VRXF25C400CJ	120	28.26	89	240	92.40 *	0.293	1323	661	2.10
	1/5	R88G-VRXF05C750CJ	600	10.99	92	1200	38.64	0.817	784	392	2.10
750 W	1/9	R88G-VRXF09D750CJ	333	19.57	91	667	63.70 *	0.755	1176	588	3.40
(200 V)	1/15	R88G-VRXF15D750CJ	200	31.91	89	400	106.00 *	0.685	1372	686	3.80
ete The average of	1/25	R88G-VRXF25D750CJ	120	53.18	89	240	177.00 *	0.658	1617	808	3.80

*The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

- 2. The protective structure rating of the Servomotor combined with the Decelerator is IP44. (Excluding decelerator and servo motor connecting parts.)
- 3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



- **4.** The standard shaft type is a shaft with key and tap. (The key is temporarily assembled to the shaft.)
- 5. Take care so that the surface temperature of the Decelerator does not exceed 90°C.

External Dimensions (Unit: mm)

Backlash: 3 Arcminutes Max.

● For 3,000-r/min Servomotors (50 to 200 W)

									Dimen	sions [mm]					
Servomotor rated output	Reduction ratio	Model	Outline drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *2	E	F1	F2
	1/21	R88G-HPG14A21100B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
50 W	1/33	R88G-HPG14A33050B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
	1/45	R88G-HPG14A45050B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
	1/5	R88G-HPG11B05100B□	1 *1	39.5	42	40	40 × 40	46	46	40	39.5	29		27	2.2	15
	1/11	R88G-HPG14A11100B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
100 W	1/21	R88G-HPG14A21100B□	1	64.0	58	60	60 × 60	70	46	56	55.5	40		37	2.5	21
	1/33	R88G-HPG20A33100B□	2	66.5	80	90	55 dia.	105	46	85	84	59	89	53	7.5	27
	1/45	R88G-HPG20A45100B□	2	66.5	80	90	55 dia.	105	46	85	84	59	89	53	7.5	27
	1/5	R88G-HPG14A05200B□	1	64.0	58	60	60 × 60	70	70	56	55.5	40		37	2.5	21
	1/11	R88G-HPG14A11200B□	1	64.0	58	60	60 × 60	70	70	56	55.5	40		37	2.5	21
200 W	1/21	R88G-HPG20A21200B□	2	71.0	80	90	89 dia.	105	70	85	84	59		53	7.5	27
	1/33	R88G-HPG20A33200B□	2	71.0	80	90	89 dia.	105	70	85	84	59		53	7.5	27
	1/45	R88G-HPG20A45200B□	2	71.0	80	90	89 dia.	105	70	85	84	59		53	7.5	27

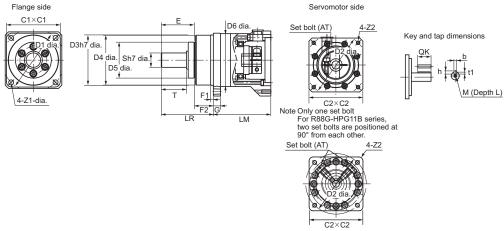
							D	imension	s [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z1	Z 2	AT *3		K	ey		Ta	ар
ratea output	iuuo		G	3	'	21	22	AI #3	QK	b	h	t1	М	L
	1/21	R88G-HPG14A21100B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8
50 W	1/33	R88G-HPG14A33050B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8
	1/45	R88G-HPG14A45050B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8
	1/5	R88G-HPG11B05100B□	5	8	20	3.4	M4 × 9	М3	15	3	3	1.8	М3	6
	1/11	R88G-HPG14A11100B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8
100 W	1/21	R88G-HPG14A21100B□	8	16	28	5.5	M4 × 10	М3	25	5	5	3	M4	8
	1/33	R88G-HPG20A33100B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/45	R88G-HPG20A45100B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/5	R88G-HPG14A05200B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/11	R88G-HPG14A11200B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
200 W	1/21	R88G-HPG20A21200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
200 99	1/33	R88G-HPG20A33200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/45	R88G-HPG20A45200B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12

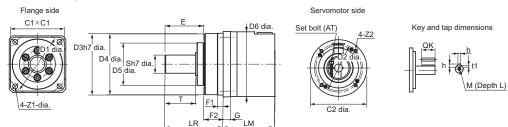
^{*1.} Two set bolts are positioned at 90° from each other.

- **Note: 1.** The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG11B05100BJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - $\textbf{4.} \ \ \textbf{You cannot use this type of Decelerator for the Servomotor with key}.$
 - 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

^{*2.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.*3. Indicates set bolt.

Outline Drawing 1





For 3,000-r/min Servomotors (400 to 750 W)

Servomotor	Reduction	Model	Outline						Dimen	sions [mm]					
rated output	ratio	Woder	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *1	Е	F1	F2
	1/5	R88G-HPG14A05400B□	1	64	58	60	60 × 60	70	70	56	55.5	40		37	2.5	21
	1/11	R88G-HPG20A11400B□	2	71	80	90	89 dia.	105	70	85	84	59		53	7.5	27
400 W	1/21	R88G-HPG20A21400B□	2	71	80	90	89 dia.	105	70	85	84	59		53	7.5	27
	1/33	R88G-HPG32A33400B□	2	104	133	120	122 dia.	135	70	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45400B□	2	104	133	120	122 dia.	135	70	115	114	84		98	12.5	35
	1/5	R88G-HPG20A05750B□	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
750 14/	1/11	R88G-HPG20A11750B□	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
750 W (200 V)	1/21	R88G-HPG32A21750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
(====,	1/33	R88G-HPG32A33750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45750B□	2	104	133	120	122 dia.	135	90	115	114	84		98	12.5	35
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
750 14/	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
750 W (400 V)	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(.50 0)	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53

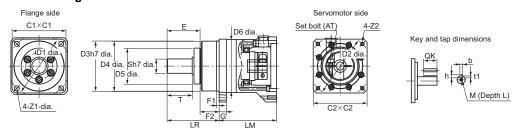
							D	imension	ıs [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z2	AT *2		K	ey		Ta	ар
ratea output	Tutto		G	3	'	21	22	AI #Z	QK	b	h	t1	M	L
	1/5	R88G-HPG14A05400B□	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/11	R88G-HPG20A11400B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
400 W	1/21	R88G-HPG20A21400B□	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/33	R88G-HPG32A33400B□	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400B□	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
	1/5	R88G-HPG20A05750B□	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
	1/11	R88G-HPG20A11750B□	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
750 W (200 V)	1/21	R88G-HPG32A21750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
(200 0)	1/33	R88G-HPG32A33750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45750B□	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
750 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
(-100 4)	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20

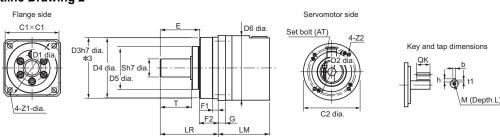
*1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine. *2. Indicates set bolt.

Note: 1. The standard shaft type is a straight shaft.

- 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG14A05400BJ)
- The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
- You cannot use this type of Decelerator for the Servomotor with key.
 The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1





***3.** The tolerance is "h8" for R88G-HPG50□.

● For 3,000-r/min Servomotors (1 to 5 kW)

Servomotor	Reduction	Model	Outline						Dimens	ions [r	nm]					
rated output	ratio	wodei	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *1	Е	F1	F2
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
1 kW	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
1.5 kW	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
2 KVV	1/21	R88G-HPG50A212K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
3 kW	1/11	R88G-HPG50A113K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
4 kW	1/5	R88G-HPG32A054K0B□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
4 KVV	1/11	R88G-HPG50A115K0B□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
4.7 kW	1/5	R88G-HPG50A055K0B□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
5 kW	1/11	R88G-HPG50A115K0B□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53

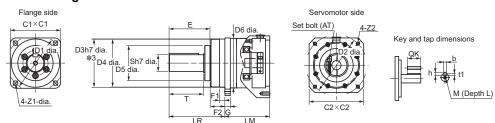
							D	imensior	ıs [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z2	AT *2		K	ey		Ta	ар
ratea output	Tutto		G	3	'	21		AI #Z	QK	b	h	t1	M	L
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
1 kW	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
1.5 kW	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
2 kW	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
2 RVV	1/21	R88G-HPG50A212K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
3 kW	1/11	R88G-HPG50A113K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
4 1-38/	1/5	R88G-HPG32A054K0B□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
4 kW	1/11	R88G-HPG50A115K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
4.7 kW	1/5	R88G-HPG50A055K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
5 kW	1/11	R88G-HPG50A115K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20

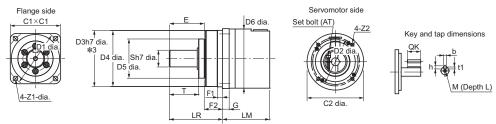
^{*1.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
*2. Indicates set bolt.

Note: 1. The standard shaft type is a straight shaft.

- 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A052K0BJ)
- 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
- 4. You cannot use this type of Decelerator for the Servomotor with key.
- 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1





***3.** The tolerance is "h8" for R88G-HPG50 \square .

● For 2,000-r/min Servomotors (400 W to 1 kW)

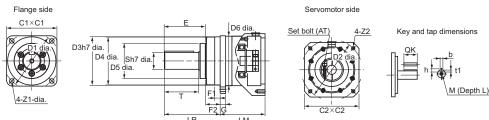
Servomotor	Reduction	Model	Outline						Dimens	sions [r	nm]					
rated output	ratio	Wodei	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *1	Е	F1	F2
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
400 144	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
400 W (400 V)	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(400 1)	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG32A45400SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/5	R88G-HPG32A052K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
600 W	1/11	R88G-HPG32A112K0B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(400 V)	1/21	R88G-HPG32A211K5B□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
(400 1)	1/33	R88G-HPG32A33600SB□	2	110	133	120	135 dia.	135	115	115	114	84		98	12.5	35
	1/45	R88G-HPG50A451K5B□	2	123	156	170	170 dia.	190	115	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1 kW	1/21	R88G-HPG32A211K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/45	R88G-HPG50A451K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53

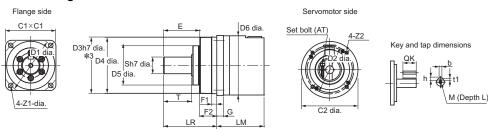
							D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	-	Z1	Z 2	AT *2		K	ey		Ta	ар
ratea output	Tutto		"	3	•	21		AI 4Z	QK	b	h	t1	M	L
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
400 144	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
400 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
(400 1)	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/5	R88G-HPG32A052K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
000 14/	1/11	R88G-HPG32A112K0B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
600 W (400 V)	1/21	R88G-HPG32A211K5B□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
(400 1)	1/33	R88G-HPG32A33600SB□	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B□	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1 kW	1/21	R88G-HPG32A211K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20

^{*1.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine. *2. Indicates set bolt.

- Note: 1. The standard shaft type is a straight shaft.
 - A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A053K0BJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. You cannot use this type of Decelerator for the Servomotor with key.
 - 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1





***3.** The tolerance is "h8" for R88G-HPG50□.

● For 2,000-r/min Servomotors (1.5 to 3 kW)

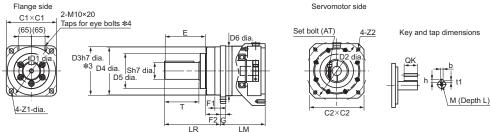
Servomotor	Reduction	Model	Outline					C	imensi	ons [m	m]					
rated output	ratio	wiodei	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *1	Е	F1	F2
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1.5 kW	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
1.5 KVV	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84		98	12.5	35
2 NVV	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122		103	12	53
	1/5	R88G-HPG32A054K0B□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
3 kW	1/11	R88G-HPG50A115K0B□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
3 KVV	1/21	R88G-HPG50A213K0SB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/25	R88G-HPG65A253K0SB□	1	231	222	230	130 × 130	260	145	220	214	168	220	165	12	57

							D	imensior	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z2	AT *2		K	ey		Ta	ар
ratou output	Tutto		G	3	'	21		AI 42	QK	b	h	t1	M	L
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1.5 kW	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
1.5 KW	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
2 kW	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
2 RVV	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A054K0B□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
3 kW	1/11	R88G-HPG50A115K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
3 KVV	1/21	R88G-HPG50A213K0SB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A253K0SB□	25	80	130	18	M8 × 25	M8	110	22	14	9	M16	35

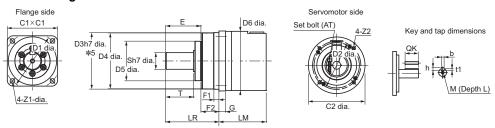
^{*1.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
*2. Indicates set bolt.

- Note: 1. The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A05900TBJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. You cannot use this type of Decelerator for the Servomotor with key.
 - 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



- **★3.** The tolerance is "h8" for R88G-HPG50□ and R88G-HPG65□.
- ***4.** The model R88G-HPG65□ has the taps for eye bolts.



***5.** The tolerance is "h8" for R88G-HPG50□.

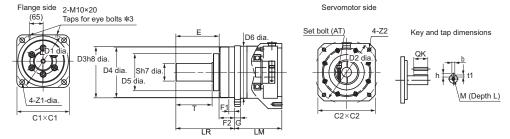
● For 1,500-r/min Servomotors (4 kW to 5.5 kW)

Servomotor	Reduction		Outline					D	imensi	ons [m	m]					
rated output	ratio	Model	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 * 1	Е	F1	F2
	1/5	R88G-HPG50A055K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
4 kW	1/11	R88G-HPG50A115K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
4 KVV	1/21	R88G-HPG65A205K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/33	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
E 1-34/	1/5	R88G-HPG50A054K5TB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
5 kW 5.5 kW	1/12	R88G-HPG65A127K5SB□	1	254.5	222	230	180 × 180	260	200	220	214	168	220	165	12	57
0.0 KW	1/20	R88G-HPG65A204K5TB□	1	254.5	222	230	180 × 180	260	200	220	214	168	220	165	12	57

	5.1.6						Di	mensio	ns [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	_	Z1	Z2	AT		K	ey		Ta	ар
ratea output	Tutto		"	3		21	22	*2	QK	b	h	t1	M	L
	1/5	R88G-HPG50A055K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
4 kW	1/11	R88G-HPG50A115K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
4 KVV	1/21	R88G-HPG65A205K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/33	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
- 1114	1/5	R88G-HPG50A054K5TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
5 kW 5.5 kW	1/12	R88G-HPG65A127K5SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
0.0 KW	1/20	R88G-HPG65A204K5TB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35

^{*1.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.*2. Indicates set bolt.

- Note: 1. The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG11B05100BJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. You cannot use this type of Decelerator for the Servomotor with key.
 - 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.



***3.** The model R88G-HPG65 \square has the taps for eye bolts.

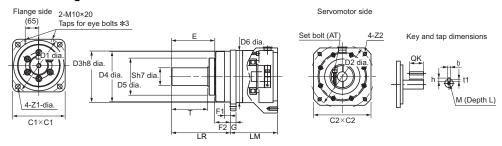
● For 1,000-r/min Servomotors (900 W to 3 kW)

Servomotor	Reduction	Model	Outline						imensi	ions [m	ım]					
rated output	ratio	Wodei	drawing	LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 *1	Е	F1	F2
	1/5	R88G-HPG32A05900TB□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
900 W	1/11	R88G-HPG32A11900TB□	1	129	133	120	130 × 130	135	145	115	114	84		98	12.5	35
900 W	1/21	R88G-HPG50A21900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/33	R88G-HPG50A33900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/5	R88G-HPG32A052K0TB□	1	129	133	120	180 × 180	135	200	115	114	84		98	12.5	35
2 kW	1/11	R88G-HPG50A112K0TB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
Z RVV	1/21	R88G-HPG50A212K0TB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/5	R88G-HPG50A055K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
3 kW	1/11	R88G-HPG50A115K0SB□	1	149	156	170	180 × 180	190	200	165	163	122		103	12	53
3 KVV	1/20	R88G-HPG65A205K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57

							D	imensior	ıs [mm]					
Servomotor rated output	Reduction ratio	Model	G	s	т	Z 1	Z2	AT *2		K	ey		Ta	р
ratou output	iuuo		G	3	'	21		AI 42	QK	b	h	t1	M	L
	1/5	R88G-HPG32A05900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
900 W	1/11	R88G-HPG32A11900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
900 W	1/21	R88G-HPG50A21900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A33900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/5	R88G-HPG32A052K0TB□	13	40	82	11	M12 × 25	M6	70	12	8	5	M10	20
2 kW	1/11	R88G-HPG50A112K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
2 KVV	1/21	R88G-HPG50A212K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/5	R88G-HPG50A055K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
3 kW	1/11	R88G-HPG50A115K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
3 KVV	1/20	R88G-HPG65A205K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35

^{*1.} D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
*2. Indicates set bolt.

- Note: 1. The standard shaft type is a straight shaft.
 - 2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG32A05900TBJ)
 - 3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
 - 4. You cannot use this type of Decelerator for the Servomotor with key.
 - 5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.



- ***3.** The tolerance is "h8" for R88G-HPG50 \square and R88G-HPG65 \square .
- ***4.** The model R88G-HPG65 \square has the taps for eye bolts.

Backlash: 15 Arcminutes Max.

● For 3,000-r/min Servomotors

		# = al = l					Dim	ensions [mm]				
	ľ	Model	LM	LR	C1	C2	D1	D2	D3	F	G	S	Т
	1/5	R88G-VRXF05B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
50 W	1/9	R88G-VRXF09B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
OU W	1/15	R88G-VRXF15B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/25	R88G-VRXF25B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/5	R88G-VRXF05B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
100 W	1/9	R88G-VRXF09B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
100 W	1/15	R88G-VRXF15B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/25	R88G-VRXF25B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/5	R88G-VRXF05B200CJ	72.5	32	60	52	70	60	50	3	10	12	20
200 W	1/9	R88G-VRXF09C200CJ	89.5	50	60	78	70	90	70	3	8	19	30
200 W	1/15	R88G-VRXF15C200CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/25	R88G-VRXF25C200CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/5	R88G-VRXF05C400CJ	89.5	50	60	78	70	90	70	3	8	19	30
400 W	1/9	R88G-VRXF09C400CJ	89.5	50	60	78	70	90	70	3	8	19	30
400 W	1/15	R88G-VRXF15C400CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/25	R88G-VRXF25C400CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/5	R88G-VRXF05C750CJ	93.5	50	80	78	90	90	70	3	10	19	30
750 W	1/9	R88G-VRXF09D750CJ	97.5	61	80	98	90	115	90	5	10	24	40
(200 V)	1/15	R88G-VRXF15D750CJ	110.0	61	80	98	90	115	90	5	10	24	40
	1/25	R88G-VRXF25D750CJ	110.0	61	80	98	90	115	90	5	10	24	40

							Dimensi	ons [mm]				
	ı	Model	Z1	Z2	AT*			K	еу		Ta	ар
			21	22	AI T	L	QK	b	h	t1	m	I
	1/5	R88G-VRXF05B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
50 W	1/9	R88G-VRXF09B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
50 VV	1/15	R88G-VRXF15B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/25	R88G-VRXF25B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/5	R88G-VRXF05B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
100 W	1/9	R88G-VRXF09B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
100 W	1/15	R88G-VRXF15B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/25	R88G-VRXF25B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/5	R88G-VRXF05B200CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
200 W	1/9	R88G-VRXF09C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
200 W	1/15	R88G-VRXF15C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/25	R88G-VRXF25C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/5	R88G-VRXF05C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
400 W	1/9	R88G-VRXF09C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
400 99	1/15	R88G-VRXF15C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/25	R88G-VRXF25C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/5	R88G-VRXF05C750CJ	M5	M6	M6	20	22	6	6	3.5	M6	12
750 W	1/9	R88G-VRXF09D750CJ	M5	M8	M6	20	30	8	7	4	M8	16
(200 V)	1/15	R88G-VRXF15D750CJ	M5	M8	M6	20	30	8	7	4	M8	16
	1/25	R88G-VRXF25D750CJ	M5	M8	M6	20	30	8	7	4	M8	16

* Indicates set bolt.

Note: 1. The standard shaft type is a shaft with key and tap.

^{2.} The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.

You cannot use this type of Decelerator for the Servomotor with key.
 The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Flange side Servomotor side Key and tap dimensions 4-Z2 (Available depth L) Output Description Set bolt (AT) Output Description Output Description

ME	MO

Ordering Information

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Interpreting Model Numbers

AC Servo Drives with Built-in EtherCAT Communications and SS1/SLS Safety Sub-Functions

AC Servomotor

R88D-1S N 01 H -ECT-51

(2) (3)

\ (4\) (5\) (_
(4) (5)	(6)

No	Item	Symbol	Specifications
(1)	1S-series Servo Dri	ve	
(2)	Servo Drive Type	N	Standard / Communication type
		01	100 W
		02	200 W
		04	400 W
		06	600 W
		08	750 W
(2)	Applicable Servomotor	10	1 kW
(3)	rated output	15	1.5 kW
		20	2 kW
		30	3 kW
		55	5.5 kW
		75	7.5 kW
		150	15 kW
		L	100 VAC
(4)	Power Supply Voltage	Н	200 VAC
	Voltage	F	400 VAC
(5)	Communications type	ECT	EtherCAT Communications
(6)	Derived type	51	Model with SS1/SLS safety functions added

R88M-1 M 100 30 S -BOS2

(3)

(4) (5)

No	Item	Symbol	Specifications
(1)	1S-series Servomo	tor	
(2)	Santamatar Tuna	L	Standard / Low-inertia type
(2)	Servomotor Type	M	Standard / Middle-inertia type
		050	50 W
		100	100 W
		200	200 W
		400	400 W
		600	600 W
		750	750 W
		900	900 W
		1K0	1 kW
(0)	D	1K5	1.5 kW
(3)	Rated output	2K0	2 kW
		3K0	3 kW
		4K0	4 kW
		4K7	4.7 kW
		5K0	5 kW
		5K5	5.5 kW
		7K0	7.5 kW
		11K0	11 kW
		15K0	15 kW
		10	1,000 r/min
(4)	Rated rotation	15	1,500 r/min
(4)	speed	20	2,000 r/min
		30	3,000 r/min
	Servo Drive main	S	100 VAC absolute encoder
(5)	power supply voltage and	Т	200 VAC absolute encoder
	encoder type	С	400 VAC absolute encoder
	Options		
	Desire	None	Without brake
	Brake	В	With 24-VDC brake
(6)	0:11	None	Without oil seal
	Oil seal	0	With oil seal
	14	None	Straight shaft
	Key and tap	S2	With key and tap

Decelerator

Backlash: 3 Arcminutes Max.

R88G-HPG 14A 05 100 S B J

(2)

(3)

(4) (5) (6) (7)

Backlash: 15 Arcminutes Max.

R88G-VRXF 09 B 100 C J

(2) (3) (4) (5) (6)

No	Item	Symbol	Specifications
(1)		_	cklash: 3 Arcminutes max.
(· /	2000,010,010,101	11B	40 × 40
		14A	60 × 60
	Elongo oizo	20A	90 × 90
(2)	Flange size number	32A	120 × 120
		50A	170 × 170
		65A	230 × 230
		05	1/5
		11	1/11
		12	1/12
		20	1/20
(3)	Reduction ratio	21	1/21
		25	1/25
		33	1/33
		45	1/45
		050	50 W
		100	100 W
		200	200 W
		400	400 W
		600	600 W
		750	750 W
	Applicable	900	900 W
(4)	Applicable Servomotor rated	1K0	1 kW
` ,	output *	1K5	1.5 kW
		2K0	2 kW
		3K0	3 kW
		4K0	4 kW
		4K5	4.5 kW
		5K0	5 kW
		7K5	7.5 kW
		None	3,000-r/min Servomotors
(5)	Servomotor type *	S	2,000-r/min Servomotors
		Т	1,000-r/min Servomotors
(6)	Backlash	В	Backlash: 3 Arcminutes max.
(7)	Ontion	None	Straight shaft
(7)	Option	J	With key and tap

^{*} This is a standard model number of servo motor; this model number structure can be applied to other motors. Confirm decelerator and servomotor combination table when you select a Servomotor.

No	Item	Symbol	Specifications			
(1)	Decelerator for Servomotor Backlash: 15 Arcminutes max.					
		05	1/5			
(2)	Gear Ratio	09	1/9			
(2)	Gear Railo	15	1/15			
		25	1/25			
		В	□52			
(3)	Flange Size Number	С	□78			
	Number	D	□98			
		100	50 W, 100 W			
(4)	Applicable Servomotor	200	200 W			
(4)	rated output	400	400 W			
		750	750 W			
(5)	Backlash	С	Backlash: 15 Arcminutes Max			
(6)	Option	J	With key and tap			

AC Servo System 1S-series with SS1/SLS Safety Sub-Functions Table of AC Servomotor Variations

R88M-1 □				- 🗌		
(2)	(3)	(4)	(5)	(6)	(7)	(8)

(2)	(3)	(4)			(5)		(6	(6)		7)	3)	3)
				Power su	ipply spec	ifications						
T	Rated	B-4-4:	Model	ABS ABS ABS		ABS	Brake		Oil seal		Shaft	type
Туре	output	Rotation speed		400	200	100						
				С	Т	S	None	В	None	0	None	S2
	50 W		R88M-1M05030		✓	✓	✓	✓	✓	✓	✓	✓
	100 W		R88M-1M10030		✓	✓	✓	✓	✓	✓	✓	✓
M	200 W		R88M-1M20030		✓	✓	✓	✓	✓	✓	✓	✓
	400 W		R88M-1M40030		✓	✓	✓	✓	✓	✓	✓	✓
	750 W		R88M-1M75030		✓		✓	✓	✓	✓	✓	✓
	750 W		R88M-1L75030	✓			✓	✓	✓	✓	✓	✓
	1 kW	3,000 r/min	R88M-1L1K030	✓	✓		✓	✓	✓	✓	✓	✓
	1.5 kW		R88M-1L1K530	✓	✓		✓	✓	✓	✓	✓	✓
	2 kW		R88M-1L2K030	✓	✓		✓	✓	✓	✓	✓	✓
L	3 kW		R88M-1L3K030	✓	✓		✓	✓	✓	✓	✓	✓
	4 kW		R88M-1L4K030	✓	✓		✓	✓	✓	✓	✓	✓
	4.7 kW		R88M-1L4K730		✓							
	5 kW		R88M-1L5K030	✓			✓	✓	✓	✓	✓	✓
	400 W		R88M-1M40020	✓			✓	✓	✓	✓	✓	✓
	600 W		R88M-1M60020	✓			✓	✓	✓	✓	✓	✓
	1 kW	0.000 / :	R88M-1M1K020	✓	✓		✓	✓	✓	✓	✓	✓
М	1.5 kW	2,000 r/min	R88M-1M1K520	✓	✓		✓	✓	✓	✓	✓	✓
	2 kW		R88M-1M2K020	✓	✓		✓	✓	✓	✓	✓	✓
	3 kW		R88M-1M3K020	✓	✓		✓	✓	✓	✓	✓	✓
	4 kW		R88M-1M4K015	✓	✓		✓	✓	✓	✓	✓	✓
	5 kW		R88M-1M5K015		✓							
	5.5 kW	4.500 / :	R88M-1M5K515	✓			✓	✓	✓	✓	✓	✓
М	7.5 kW	1,500 r/min	R88M-1M7K515	✓	✓		✓	✓	✓	✓	✓	✓
	11 kW		R88M-1M11K015	✓	✓		✓	✓	✓	✓	✓	✓
	15 kW		R88M-1M15K015	✓	✓		✓	✓	✓	✓	✓	✓
	900 W		R88M-1M90010	✓	✓		✓	✓	✓	✓	✓	✓
M 2	2 kW	1,000 r/min	R88M-1M2K010	✓	✓		✓	✓	✓	✓	✓	✓
	3 kW	1	R88M-1M3K010	✓	✓		✓	✓	✓	✓	✓	✓
Middle inertia .ow inertia	100: 100 W 1K0: 1 kW 3K0: 3 kW	10: 1,000 r/min 15: 1,500 r/min 20: 2,000 r/min 30: 3,000 r/min		T: 200 VA encode S: 100 VA	AC (with aber) ABS/INC AC (with aber) ABS/INC AC (with aber) ABS/INC	 solute solute	None: Without B: With 24- brake		None: Woil seal O: With oil		None: Straight S2: With key	

Ordering Information

AC Servo Drives with Built-in EtherCAT Communications and SS1/SLS Safety Sub-Functions

Power supply voltage	Rated output	Model
	100 W	R88D-1SN01L-ECT-51
Single-phase 100 VAC	200 W	R88D-1SN02L-ECT-51
	400 W	R88D-1SN04L-ECT-51
	100 W	R88D-1SN01H-ECT-51
	200 W	R88D-1SN02H-ECT-51
Single-phase/3-phase 200 VAC	400 W	R88D-1SN04H-ECT-51
	750 W	R88D-1SN08H-ECT-51
	1.5 kW	R88D-1SN15H-ECT-51
	1 kW	R88D-1SN10H-ECT-51
	2 kW	R88D-1SN20H-ECT-51
3-phase 200 VAC	3 kW	R88D-1SN30H-ECT-51
3-phase 200 VAC	5.5 kW	R88D-1SN55H-ECT-51
	7.5 kW	R88D-1SN75H-ECT-51
	15 kW	R88D-1SN150H-ECT-51
	600 W	R88D-1SN06F-ECT-51
	1 kW	R88D-1SN10F-ECT-51
	1.5 kW	R88D-1SN15F-ECT-51
3-phase 400 VAC	2 kW	R88D-1SN20F-ECT-51
3-phase 400 VAC	3 kW	R88D-1SN30F-ECT-51
	5.5 kW	R88D-1SN55F-ECT-51
	7.5 kW	R88D-1SN75F-ECT-51
	15 kW	R88D-1SN150F-ECT-51

AC Servomotors

● 3,000-r/min Servomotors

				Model		
Sį	ecifications		Without oil seal			
			Straight shaft	With key and tap		
		50 W	R88M-1M05030S	R88M-1M05030S-S2		
	100 VAC	100 W	R88M-1M10030S	R88M-1M10030S-S2		
	100 VAC	200 W	R88M-1M20030S	R88M-1M20030S-S2		
		400 W	R88M-1M40030S	R88M-1M40030S-S2		
		50 W	R88M-1M05030T	R88M-1M05030T-S2		
		100 W	R88M-1M10030T	R88M-1M10030T-S2		
		200 W	R88M-1M20030T	R88M-1M20030T-S2		
		400 W	R88M-1M40030T	R88M-1M40030T-S2		
		750 W	R88M-1M75030T	R88M-1M75030T-S2		
	200 VAC	1 kW	R88M-1L1K030T	R88M-1L1K030T-S2		
Without brake		1.5 kW	R88M-1L1K530T	R88M-1L1K530T-S2		
		2 kW	R88M-1L2K030T	R88M-1L2K030T-S2		
		3 kW	R88M-1L3K030T	R88M-1L3K030T-S2		
		4 kW	R88M-1L4K030T	R88M-1L4K030T-S2		
		4.7 kW	R88M-1L4K730T	R88M-1L4K730T-S2		
	400.7/4.0	750 W	R88M-1L75030C	R88M-1L75030C-S2		
		1 kW	R88M-1L1K030C	R88M-1L1K030C-S2		
		1.5 kW	R88M-1L1K530C	R88M-1L1K530C-S2		
	400 VAC	2 kW	R88M-1L2K030C	R88M-1L2K030C-S2		
		3 kW 4 kW	R88M-1L3K030C R88M-1L4K030C	R88M-1L3K030C-S2 R88M-1L4K030C-S2		
		5 kW	R88M-1L5K030C	R88M-1L5K030C-S2		
		50 W	R88M-1M05030S-B	R88M-1M05030S-BS2		
	100 VAC	100 W	R88M-1M10030S-B	R88M-1M10030S-BS2		
		200 W	R88M-1M20030S-B	R88M-1M20030S-BS2		
		400 W	R88M-1M40030S-B	R88M-1M40030S-BS2		
		50 W	R88M-1M05030T-B	R88M-1M05030T-BS2		
		100 W	R88M-1M10030T-B	R88M-1M10030T-BS2		
		200 W	R88M-1M20030T-B	R88M-1M20030T-BS2		
		400 W	R88M-1M40030T-B	R88M-1M40030T-BS2		
		750 W	R88M-1M75030T-B	R88M-1M75030T-BS2		
	200 VAC	1 kW	R88M-1L1K030T-B	R88M-1L1K030T-BS2		
\A/:41- 1 1		1.5 kW	R88M-1L1K530T-B	R88M-1L1K530T-BS2		
With brake		2 kW	R88M-1L2K030T-B	R88M-1L2K030T-BS2		
		3 kW	R88M-1L3K030T-B	R88M-1L3K030T-BS2		
		4 kW	R88M-1L4K030T-B	R88M-1L4K030T-BS2		
		4.7 kW	R88M-1L4K730T-B	R88M-1L4K730T-BS2		
		750 W	R88M-1L75030C-B	R88M-1L75030C-BS2		
		1 kW	R88M-1L1K030C-B	R88M-1L1K030C-BS2		
		1.5 kW	R88M-1L1K530C-B	R88M-1L1K530C-BS2		
	400 VAC	2 kW	R88M-1L2K030C-B	R88M-1L2K030C-BS2		
		3 kW	R88M-1L3K030C-B	R88M-1L3K030C-BS2		
		4 kW	R88M-1L4K030C-B	R88M-1L4K030C-BS2		
		5 kW	R88M-1L5K030C-B	R88M-1L5K030C-BS2		

			Мо	del		
Sp	ecifications		With oil seal			
			Straight shaft	With key and tap		
		50 W	R88M-1M05030S-O	R88M-1M05030S-OS2		
	100 VAC	100 W	R88M-1M10030S-O	R88M-1M10030S-OS2		
	100 VAC	200 W	R88M-1M20030S-O	R88M-1M20030S-OS2		
		400 W	R88M-1M40030S-O	R88M-1M40030S-OS2		
		50 W	R88M-1M05030T-O	R88M-1M05030T-OS2		
		100 W	R88M-1M10030T-O	R88M-1M10030T-OS2		
		200 W	R88M-1M20030T-O	R88M-1M20030T-OS2		
		400 W	R88M-1M40030T-O	R88M-1M40030T-OS2		
		750 W	R88M-1M75030T-O	R88M-1M75030T-OS2		
	200 VAC	1 kW	R88M-1L1K030T-O	R88M-1L1K030T-OS2		
\A/;4b 4 b 1		1.5 kW	R88M-1L1K530T-O	R88M-1L1K530T-OS2		
Without brake		2 kW	R88M-1L2K030T-O	R88M-1L2K030T-OS2		
		3 kW	R88M-1L3K030T-O	R88M-1L3K030T-OS2		
		4 kW	R88M-1L4K030T-O	R88M-1L4K030T-OS2		
		4.7 kW	R88M-1L4K730T-O	R88M-1L4K730T-OS2		
	400 VAC	750 W	R88M-1L75030C-O	R88M-1L75030C-OS2		
		1 kW	R88M-1L1K030C-O	R88M-1L1K030C-OS2		
		1.5 kW	R88M-1L1K530C-O	R88M-1L1K530C-OS2		
		2 kW	R88M-1L2K030C-O	R88M-1L2K030C-OS2		
		3 kW	R88M-1L3K030C-O	R88M-1L3K030C-OS2		
		4 kW	R88M-1L4K030C-O	R88M-1L4K030C-OS2		
		5 kW	R88M-1L5K030C-O	R88M-1L5K030C-OS2		
		50 W	R88M-1M05030S-BO	R88M-1M05030S-BOS2		
		100 W	R88M-1M10030S-BO	R88M-1M10030S-BOS2		
	100 VAC	200 W	R88M-1M20030S-BO	R88M-1M20030S-BOS2		
		400 W	R88M-1M40030S-BO	R88M-1M40030S-BOS2		
		50 W	R88M-1M05030T-BO	R88M-1M05030T-BOS2		
		100 W	R88M-1M10030T-BO	R88M-1M10030T-BOS2		
		200W	R88M-1M20030T-BO	R88M-1M20030T-BOS2		
		400 W	R88M-1M40030T-BO	R88M-1M40030T-BOS2		
		750 W	R88M-1M75030T-BO	R88M-1M75030T-BOS2		
	200 VAC	1 kW	R88M-1L1K030T-BO	R88M-1L1K030T-BOS2		
		1.5 kW	R88M-1L1K530T-BO	R88M-1L1K530T-BOS2		
With brake		2 kW	R88M-1L2K030T-BO	R88M-1L2K030T-BOS2		
		3 kW	R88M-1L3K030T-BO	R88M-1L3K030T-BOS2		
		4 kW	R88M-1L4K030T-BO	R88M-1L4K030T-BOS2		
		4.7 kW	R88M-1L4K730T-BO	R88M-1L4K730T-BOS2		
		750 W	R88M-1L75030C-BO	R88M-1L75030C-BOS2		
		1 kW	R88M-1L1K030C-BO	R88M-1L1K030C-BOS2		
		1.5 kW	R88M-1L1K530C-BO	R88M-1L1K530C-BOS2		
	400 VAC	2 kW	R88M-1L2K030C-BO	R88M-1L2K030C-BOS2		
		3 kW	R88M-1L3K030C-BO	R88M-1L3K030C-BOS2		
		4 kW	R88M-1L4K030C-BO	R88M-1L4K030C-BOS2		
		5 kW	R88M-1L5K030C-BO	R88M-1L5K030C-BOS2		

• 2,000-r/min Servomotors

			Model			
Sp	ecifications		Wit	thout oil seal		
			Straight shaft	With key and tap		
		1 kW	R88M-1M1K020T	R88M-1M1K020T-S2		
	200 VAC	1.5 kW	R88M-1M1K520T	R88M-1M1K520T-S2		
	200 VAC	2 kW	R88M-1M2K020T	R88M-1M2K020T-S2		
		3 kW	R88M-1M3K020T	R88M-1M3K020T-S2		
Without brake		400 W	R88M-1M40020C	R88M-1M40020C-S2		
williout brake		600 W	R88M-1M60020C	R88M-1M60020C-S2		
	400 VAC	1 kW	R88M-1M1K020C	R88M-1M1K020C-S2		
		1.5 kW	R88M-1M1K520C	R88M-1M1K520C-S2		
		2 kW	R88M-1M2K020C	R88M-1M2K020C-S2		
		3 kW	R88M-1M3K020C	R88M-1M3K020C-S2		
		1 kW	R88M-1M1K020T-B	R88M-1M1K020T-BS2		
	200 VAC	1.5 kW	R88M-1M1K520T-B	R88M-1M1K520T-BS2		
	200 VAC	2 kW	R88M-1M2K020T-B	R88M-1M2K020T-BS2		
		3 kW	R88M-1M3K020T-B	R88M-1M3K020T-BS2		
With brake		400 W	R88M-1M40020C-B	R88M-1M40020C-BS2		
vviui brake		600 W	R88M-1M60020C-B	R88M-1M60020C-BS2		
	400 \/AC	1 kW	R88M-1M1K020C-B	R88M-1M1K020C-BS2		
	400 VAC	1.5 kW	R88M-1M1K520C-B	R88M-1M1K520C-BS2		
		2 kW	R88M-1M2K020C-B	R88M-1M2K020C-BS2		
		3 kW	R88M-1M3K020C-B	R88M-1M3K020C-BS2		

Specifications				Model		
			With oil seal			
			Straight shaft	With key and tap		
		1 kW	R88M-1M1K020T-O	R88M-1M1K020T-OS2		
	200 VAC	1.5 kW	R88M-1M1K520T-O	R88M-1M1K520T-OS2		
	200 VAC	2 kW	R88M-1M2K020T-O	R88M-1M2K020T-OS2		
		3 kW	R88M-1M3K020T-O	R88M-1M3K020T-OS2		
Without brake		400 W	R88M-1M40020C-O	R88M-1M40020C-OS2		
without brake		600 W	R88M-1M60020C-O	R88M-1M60020C-OS2		
	400 VAC	1 kW	R88M-1M1K020C-O	R88M-1M1K020C-OS2		
		1.5 kW	R88M-1M1K520C-O	R88M-1M1K520C-OS2		
		2 kW	R88M-1M2K020C-O	R88M-1M2K020C-OS2		
		3 kW	R88M-1M3K020C-O	R88M-1M3K020C-OS2		
		1 kW	R88M-1M1K020T-BO	R88M-1M1K020T-BOS2		
	200 VAC	1.5 kW	R88M-1M1K520T-BO	R88M-1M1K520T-BOS2		
	200 VAC	2 kW	R88M-1M2K020T-BO	R88M-1M2K020T-BOS2		
		3 kW	R88M-1M3K020T-BO	R88M-1M3K020T-BOS2		
With brake		400 W	R88M-1M40020C-BO	R88M-1M40020C-BOS2		
with brake		600 W	R88M-1M60020C-BO	R88M-1M60020C-BOS2		
	400 \/40	1 kW	R88M-1M1K020C-BO	R88M-1M1K020C-BOS2		
	400 VAC	1.5 kW	R88M-1M1K520C-BO	R88M-1M1K520C-BOS2		
		2 kW	R88M-1M2K020C-BO	R88M-1M2K020C-BOS2		
		3 kW	R88M-1M3K020C-BO	R88M-1M3K020C-BOS2		

● 1500-r/min Servomotors

			Model		
Specifications			V	Vithout oil seal	
			Straight shaft	With key and tap	
		4 kW	R88M-1M4K015T	R88M-1M4K015T-S2	
		5 kW	R88M-1M5K015T	R88M-1M5K015T-S2	
	200 VAC	7.5 kW	R88M-1M7K515T	R88M-1M7K515T-S2	
		11 kW	R88M-1M11K015T	R88M-1M11K015T-S2	
Vithout brake		15 kW	R88M-1M15K015T	R88M-1M15K015T-S2	
villiout brake		4 kW	R88M-1M4K015C	R88M-1M4K015C-S2	
	AC400V	5.5 kW	R88M-1M5K515C	R88M-1M5K515C-S2	
		7.5 kW	R88M-1M7K515C	R88M-1M7K515C-S2	
		11 kW	R88M-1M11K015C	R88M-1M11K015C-S2	
		15 kW	R88M-1M15K015C	R88M-1M15K015C-S2	
		4 kW	R88M-1M4K015T-B	R88M-1M4K015T-BS2	
		5 kW	R88M-1M5K015T-B	R88M-1M5K015T-BS2	
	200 VAC	7.5 kW	R88M-1M7K515T-B	R88M-1M7K515T-BS2	
		11 kW	R88M-1M11K015T-B	R88M-1M11K015T-BS2	
With brake		15 kW	R88M-1M15K015T-B	R88M-1M15K015T-BS2	
will blake		4 kW	R88M-1M4K015C-B	R88M-1M4K015C-BS2	
		5.5 kW	R88M-1M5K515C-B	R88M-1M5K515C-BS2	
	AC400V	7.5 kW	R88M-1M7K515C-B	R88M-1M7K515C-BS2	
		11 kW	R88M-1M11K015C-B	R88M-1M11K015C-BS2	
		15 kW	R88M-1M15K015C-B	R88M-1M15K015C-BS2	

			Model		
Sp	ecifications			With oil seal	
			Straight shaft	With key and tap	
		4 kW	R88M-1M4K015T-O	R88M-1M4K015T-OS2	
		5 kW	R88M-1M5K015T-O	R88M-1M5K015T-OS2	
	200 VAC	7.5 kW	R88M-1M7K515T-O	R88M-1M7K515T-OS2	
		11 kW	R88M-1M11K015T-O	R88M-1M11K015T-OS2	
Without brake		15 kW	R88M-1M15K015T-O	R88M-1M15K015T-OS2	
without brake		4 kW	R88M-1M4K015C-O	R88M-1M4K015C-OS2	
	AC400V	5.5 kW	R88M-1M5K515C-O	R88M-1M5K515C-OS2	
		7.5 kW	R88M-1M7K515C-O	R88M-1M7K515C-OS2	
		11 kW	R88M-1M11K015C-O	R88M-1M11K015C-OS2	
		15 kW	R88M-1M15K015C-O	R88M-1M15K015C-OS2	
		4 kW	R88M-1M4K015T-BO	R88M-1M4K015T-BOS2	
		5 kW	R88M-1M5K015T-BO	R88M-1M5K015T-BOS2	
	200 VAC	7.5 kW	R88M-1M7K515T-BO	R88M-1M7K515T-BOS2	
		11 kW	R88M-1M11K015T-BO	R88M-1M11K015T-BOS2	
With brake		15 kW	R88M-1M15K015T-BO	R88M-1M15K015T-BOS2	
vvitn brake		4 kW	R88M-1M4K015C-BO	R88M-1M4K015C-BOS2	
		5.5 kW	R88M-1M5K515C-BO	R88M-1M5K515C-BOS2	
	AC400V	7.5 kW	R88M-1M7K515C-BO	R88M-1M7K515C-BOS2	
		11 kW	R88M-1M11K015C-BO	R88M-1M11K015C-BOS2	
		15 kW	R88M-1M15K015C-BO	R88M-1M15K015C-BOS2	

• 1,000-r/min Servomotors

			Model			
Specifications			Without oil seal			
			Straight shaft	With key and tap		
		900 W	R88M-1M90010T	R88M-1M90010T-S2		
	200 VAC	2 kW	R88M-1M2K010T	R88M-1M2K010T-S2		
Without brake		3 kW	R88M-1M3K010T	R88M-1M3K010T-S2		
without brake	400 VAC	900 W	R88M-1M90010C	R88M-1M90010C-S2		
		2 kW	R88M-1M2K010C	R88M-1M2K010C-S2		
		3 kW	R88M-1M3K010C	R88M-1M3K010C-S2		
		900 W	R88M-1M90010T-B	R88M-1M90010T-BS2		
	200 VAC	2 kW	R88M-1M2K010T-B	R88M-1M2K010T-BS2		
With brake		3 kW	R88M-1M3K010T-B	R88M-1M3K010T-BS2		
vviiii prake		900 W	R88M-1M90010C-B	R88M-1M90010C-BS2		
	400 VAC	2 kW	R88M-1M2K010C-B	R88M-1M2K010C-BS2		
		3 kW	R88M-1M3K010C-B	R88M-1M3K010C-BS2		

			Model		
Specifications			With oil seal		
			Straight shaft	With key and tap	
		900 W	R88M-1M90010T-O	R88M-1M90010T-OS2	
	200 VAC	2 kW	R88M-1M2K010T-O	R88M-1M2K010T-OS2	
\A/:4b 4 b l		3 kW	R88M-1M3K010T-O	R88M-1M3K010T-OS2	
Without brake	400 VAC	900 W	R88M-1M90010C-O	R88M-1M90010C-OS2	
		2 kW	R88M-1M2K010C-O	R88M-1M2K010C-OS2	
		3 kW	R88M-1M3K010C-O	R88M-1M3K010C-OS2	
	200 VAC	900 W	R88M-1M90010T-BO	R88M-1M90010T-BOS2	
		2 kW	R88M-1M2K010T-BO	R88M-1M2K010T-BOS2	
VACAL- II		3 kW	R88M-1M3K010T-BO	R88M-1M3K010T-BOS2	
With brake		900 W	R88M-1M90010C-BO	R88M-1M90010C-BOS2	
	400 VAC	2 kW	R88M-1M2K010C-BO	R88M-1M2K010C-BOS2	
		3 kW	R88M-1M3K010C-BO	R88M-1M3K010C-BOS2	

Decelerator (Backlash: 3 Arcminutes Max.)

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/21	R88G-HPG14A21100B□
50 W	1/33	R88G-HPG14A33050B□
	1/45	R88G-HPG14A45050B□
	1/5	R88G-HPG11B05100B□
	1/11	R88G-HPG14A11100B□
100 W	1/21	R88G-HPG14A21100B□
	1/33	R88G-HPG20A33100B□
	1/45	R88G-HPG20A45100B□
-	1/5	R88G-HPG14A05200B□
	1/11	R88G-HPG14A11200B□
200 W	1/21	R88G-HPG20A21200B□
	1/33	R88G-HPG20A33200B□
	1/45	R88G-HPG20A45200B□
	1/5	R88G-HPG14A05400B□
	1/11	R88G-HPG20A11400B□
400 W	1/21	R88G-HPG20A21400B□
	1/33	R88G-HPG32A33400B□
	1/45	R88G-HPG32A45400B□
	1/5	R88G-HPG20A05750B□
	1/11	R88G-HPG20A11750B□
750 W	1/21	R88G-HPG32A21750B□
(200 V)	1/33	R88G-HPG32A33750B□
	1/45	R88G-HPG32A45750B□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
750 W	1/33 R88G-HPG32A33750B□ 1/45 R88G-HPG32A45750B□ 1/5 R88G-HPG32A052K0B□ 1/11 R88G-HPG32A112K0B□ 1/21 R88G-HPG32A211K5B□	R88G-HPG32A211K5B□
(400 V)	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG50A451K5B
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
1 kW	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
1.5 kW	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
2 kW	1/21	R88G-HPG50A212K0B□
	1/33	R88G-HPG50A332K0B□
	1/5	R88G-HPG32A053K0B□
3 kW	1/11	R88G-HPG50A113K0B□
	1/21	R88G-HPG50A213K0B□
	1/5	R88G-HPG32A054K0B□
4 kW	1/11	R88G-HPG50A115K0B□
4.7 kW	1/5	R88G-HPG50A055K0B□

^{*}The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

● For 2,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
400 W	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG32A45400SB□
	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
600 W	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG50A451K5B□
	1/5	R88G-HPG32A053K0B□
	1/11	R88G-HPG32A112K0SB□
1 kW	1/21	R88G-HPG32A211K0SB□
	1/33	R88G-HPG50A332K0SB□
	1/45	R88G-HPG50A451K0SB□
	1/5	R88G-HPG32A053K0B□
1.5 kW	1/11	R88G-HPG32A112K0SB□
1.5 KVV	1/21	R88G-HPG50A213K0B□
	1/33	R88G-HPG50A332K0SB□
	1/5	R88G-HPG32A053K0B□
2 kW	1/11	R88G-HPG32A112K0SB□
∠ KVV	1/21	R88G-HPG50A213K0B□
	1/33	R88G-HPG50A332K0SB□
	1/5	R88G-HPG32A054K0B□
3 kW	1/11	R88G-HPG50A115K0B□
O KVV	1/21	R88G-HPG50A213K0SB□
	1/25	R88G-HPG65A253K0SB□

^{*} The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

● For 1,500-r/min Servomotors

•		
Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/5	R88G-HPG50A055K0SB□
4 kW	1/11	R88G-HPG50A115K0SB□
4 KVV	1/21	R88G-HPG65A205K0SB□
	1/25	1/5 R88G-HPG50A055K0SB□ 1/11 R88G-HPG50A115K0SB□ 1/21 R88G-HPG65A205K0SB□ 1/25 R88G-HPG65A255K0SB□ 1/5 R88G-HPG50A054K5TB□ 1/12 R88G-HPG65A127K5SB□
= 1347	1/5	R88G-HPG50A054K5TB□
5 kW 5.5 kW	1/12	R88G-HPG65A127K5SB□
J.J KVV	1/20	R88G-HPG65A204K5TB□

^{*} The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

● For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) *
	1/5	R88G-HPG32A05900TB□
900 W	1/11	R88G-HPG32A11900TB□
900 W	1/21	R88G-HPG50A21900TB□
	1/33	R88G-HPG50A33900TB□
	1/5	R88G-HPG32A052K0TB□
2 kW	1/11	R88G-HPG50A112K0TB□
Z KVV	1/21	R88G-HPG50A212K0TB□
	1/25	R88G-HPG65A255K0SB□
	1/5	R88G-HPG50A055K0SB□
3 kW	1/11	R88G-HPG50A115K0SB□
3 KVV	1/20	R88G-HPG65A205K0SB□
	1/25	R88G-HPG65A255K0SB□

[★] The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at
☐ of the Decelerator model number. e.g. R88G-HPG11B05100BJ

Decelerator (Backlash: 15 Arcminutes Max.)

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model		
	1/5	R88G-VRXF05B100CJ		
50 W	1/9	R88G-VRXF09B100CJ		
50 VV	1/15	R88G-VRXF15B100CJ		
	1/25	R88G-VRXF25B100CJ		
	1/5	R88G-VRXF05B100CJ		
100 W	1/9	R88G-VRXF09B100CJ		
100 VV	1/15	R88G-VRXF15B100CJ		
	1/25	R88G-VRXF25B100CJ		
	1/5	R88G-VRXF05B200CJ		
200 W	1/9	R88G-VRXF09C200CJ		
200 VV	1/15	R88G-VRXF15C200CJ		
	1/25	R88G-VRXF25C200CJ		
	1/5	R88G-VRXF05C400CJ		
400 W	1/9	R88G-VRXF09C400CJ		
400 W	1/15	R88G-VRXF15C400CJ		
	1/25	R88G-VRXF25C400CJ		
	1/5	R88G-VRXF05C750CJ		
750 W	1/9	R88G-VRXF09D750CJ		
(200 V)	1/15	R88G-VRXF15D750CJ		
	1/25	R88G-VRXF25D750CJ		

Cables and Peripheral Devices

Some motor power cables have two cable versions: version 1.0 and version 1.1.

The cable version can be checked on the model number label.

Version 1.0: There is no version indicated on the model number label.

Version 1.1: "Ver. 1.1" is indicated on the model number label.

To use the SLS function, use a motor power cable of the latest version.

Using a motor power cable of the older version may result in a false detection of Safety Present Motor Velocity Error 2 (Error No. 71.01) or SLS Monitoring Limit Exceeded (Error No. 72.00) during velocity monitoring with the SLS function.

Also, using a cable longer than 20 m that is not listed may result in a false detection of Safety Present Motor Velocity Error 2 (Error No. 71.01) or SLS Monitoring Limit Exceeded (Error No. 72.00) during velocity monitoring with the SLS function.

Refer to 8-4 Safely-limited Speed (SLS) Function in the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696) for details.

Encoder Cables (Standard Cable)

	Applicable Servomotor		Model
	3,000-r/min Servomotors of	3 m	R88A-CR1A003C
400.14		5 m	R88A-CR1A005C
100 V 200 V	50W, 100 W, 200 W, 400 W,	10 m	R88A-CR1A010C
200 .	and 750 W	15 m	R88A-CR1A015C
		20 m	R88A-CR1A020C
	200 V: 3000-r/min Servomotors of	3 m	R88A-CR1B003N
	1 to 3 kW 2000-r/min Servomotors	5 m	R88A-CR1B005N
200 V 400 V	1000-r/min Servomotors 400 V:	10 m	R88A-CR1B010N
	3000-r/min Servomotors of 3 kW or less	15 m	R88A-CR1B015N
	2000-r/min Servomotors 1000-r/min Servomotors	20 m	R88A-CR1B020N
		3 m	R88A-CR1B003V
00011	3000-r/min Servomotors of	5 m	R88A-CR1B005V
200 V 400 V	4 kW or more	10 m	R88A-CR1B010V
.55 v	1500-r/min Servomotors	15 m	R88A-CR1B015V
		20 m	R88A-CR1B020V

Brake Cables (Standard Cable)

	Applicable Servomotor		Model
		3 m	R88A-CA1A003B
	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W ❖	5 m	R88A-CA1A005B
100 V 200 V		10 m	R88A-CA1A010B
200 V		15 m	R88A-CA1A015B
		20 m	R88A-CA1A020B

^{*}The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

Motor Power Cables (Standard Cable)

Appliaghla Contemptor			Without brake wire	With brake wire
	Applicable Servomotor		Model	Model
-		3 m	R88A-CA1A003S	
		5 m	R88A-CA1A005S	
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W. 400 W. and 750 W *	10 m	R88A-CA1A010S	
200 V	200 11, 400 11, and 100 11 4	15 m	R88A-CA1A015S	
		20 m	R88A-CA1A020S	
		3 m	R88A-CA1B003S	R88A-CA1B003B
	3,000-r/min Servomotors of 1 kW	5 m	R88A-CA1B005S	R88A-CA1B005B
200 V	2,000-r/min Servomotors of 1 kW	10 m	R88A-CA1B010S	R88A-CA1B010B
	1,000-r/min Servomotors of 900 W	15 m	R88A-CA1B015S	R88A-CA1B015B
		20 m	R88A-CA1B020S	R88A-CA1B020B
		3 m	R88A-CA1C003S	R88A-CA1C003B
	3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	5 m	R88A-CA1C005S	R88A-CA1C005B
200 V		10 m	R88A-CA1C010S	R88A-CA1C010B
	2,000 1/11111 COLVOINGLOID OF 1.0 KVV	15 m	R88A-CA1C015S	R88A-CA1C015B
		5 m 10 m 15 m 20 m 3 m 5 m 10 m 15 m 20 m 3 m 5 m	R88A-CA1C020S	R88A-CA1C020B
	3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1C003S	R88A-CA1E003B
		5 m	R88A-CA1C005S	R88A-CA1E005B
400 V		10 m	R88A-CA1C010S	R88A-CA1E010B
		15 m	R88A-CA1C015S	R88A-CA1E015B
	1,000-i/iiiii dei voiniolois di 900 vv	20 m	R88A-CA1C020S	R88A-CA1E020B
	3.000-r/min Servomotors of 2 kW	3 m	R88A-CA1E003S	R88A-CA1E003B
	(200 V) and 3 kW (200 V/400 V)	5 m	R88A-CA1E005S	R88A-CA1E005B
200 V 400 V	2,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V)	10 m	R88A-CA1E010S	R88A-CA1E010B
100 \$	1,000-r/min Servomotors of 2 kW	15 m	R88A-CA1E015S	R88A-CA1E015B
	(200 V/400 V) and 3 kW (400 V)	20 m	R88A-CA1E020S	R88A-CA1E020B
		3 m	R88A-CA1F003S	R88A-CA1F003B
		5 m	R88A-CA1F005S	R88A-CA1F005B
200 V	1,000-r/min Servomotors of 3 kW	10 m	R88A-CA1F010S	R88A-CA1F010B
		15 m	R88A-CA1F015S	R88A-CA1F015B
		20 m	R88A-CA1F020S	R88A-CA1F020B

^{*}The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

Encoder Cables (Flexible Cable)

	Applicable Servomotor		Model
	3,000-r/min Servomotors of	3 m	R88A-CR1A003CF
400.14		5 m	R88A-CR1A005CF
100 V 200 V	50W, 100 W, 200 W, 400 W,	10 m	R88A-CR1A010CF
200 .	and 750 W	15 m	R88A-CR1A015CF
		20 m	R88A-CR1A020CF
	200 V: 3000-r/min Servomotors of	3 m	R88A-CR1B003NF
	0 V 400V: 10 m 3000-r/min Servomotors of 3 kW or less 15 m	5 m	R88A-CR1B005NF
200 V 400 V		10 m	R88A-CR1B010NF
		R88A-CR1B015NF	
	2000-r/min Servomotors 1000-r/min Servomotors	20 m	R88A-CR1B020NF
		3 m	R88A-CR1B003VF
00011	3000-r/min Servomotors of	5 m	R88A-CR1B005VF
200 V 400 V	4 kW or more	10 m	R88A-CR1B010VF
.55 •	1500-r/min Servomotors	15 m	R88A-CR1B015VF
-		20 m	R88A-CR1B020VF

Brake Cables (Flexible Cable)

	Applicable Servomotor		Model
		3 m	R88A-CA1A003BF
	100 V 3,000-r/min Servomotors of 100 PW, 200 W, 200 W, 400 W, and 750 W	5 m	R88A-CA1A005BF
		10 m	R88A-CA1A010BF
200 V		15 m	R88A-CA1A015BF
		20 m	R88A-CA1A020BF

[★]The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

Motor Power Cables (Flexible Cable)

	Applicable Servomotor	Without brake wire	With brake wire	
	Applicable Servomotor	Model	Model	
		3 m	R88A-CA1A003SF	
400 \ /		5 m	R88A-CA1A005SF	
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W *	10 m	R88A-CA1A010SF	
-00 .	1.00 11, and 1.00 11	15 m	R88A-CA1A015SF	
		20 m	R88A-CA1A020SF	
		3 m	R88A-CA1B003SF	R88A-CA1B003BF
	3,000-r/min Servomotors of 1 kW	5 m	R88A-CA1B005SF	R88A-CA1B005BF
200 V	2,000-r/min Servomotors of 1 kW	10 m	R88A-CA1B010SF	R88A-CA1B010BF
	1,000-r/min Servomotors of 900 W	15 m	R88A-CA1B015SF	R88A-CA1B015BF
		20 m	Model	R88A-CA1B020BF
		3 m	R88A-CA1C003SF	R88A-CA1C003BF
	0.000 / : 0	5 m	R88A-CA1C005SF	R88A-CA1C005BF
200 V	3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	10 m	R88A-CA1C010SF	R88A-CA1C010BF
	1	15 m	R88A-CA1C015SF	R88A-CA1C015BF
		20 m	R88A-CA1C020SF	R88A-CA1C020BF
	3,000-r/min Servomotors of 750 W, 1 kW,	3 m	R88A-CA1C003SF	R88A-CA1E003BF
	1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W,	5 m	R88A-CA1C005SF	R88A-CA1E005BF
400 V		10 m	R88A-CA1C010SF	R88A-CA1E010BF
	1 kW, 1.5 kW, and 2 kW 1.000-r/min Servomotors of 900 W	15 m	R88A-CA1C015SF	R88A-CA1E015BF
	1,000 1,11111 0011011010 01 000 11	20 m	R88A-CA1C020SF	R88A-CA1E020BF
	3,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 2,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 1,000-r/min Servomotors of 2 kW (200 V/400 V)	3 m	R88A-CA1E003SF	R88A-CA1E003BF
		5 m	R88A-CA1E005SF	R88A-CA1E005BF
200 V 400 V		10 m	R88A-CA1E010SF	R88A-CA1E010BF
		15 m	R88A-CA1E015SF	R88A-CA1E015BF
	and 3 kW (400 V)	20 m	R88A-CA1A003SF R88A-CA1A005SF R88A-CA1A010SF R88A-CA1A010SF R88A-CA1A015SF R88A-CA1A020SF R88A-CA1B003SF R88A-CA1B005SF R88A-CA1B005SF R88A-CA1B010SF R88A-CA1B020SF R88A-CA1C003SF R88A-CA1C003SF R88A-CA1C005SF R88A-CA1C005SF R88A-CA1C010SF R88A-CA1C010SF R88A-CA1C010SF R88A-CA1C010SF R88A-CA1C005SF R88A-CA1C010SF R88A-CA1C005SF	R88A-CA1E020BF
		3 m	R88A-CA1F003SF	R88A-CA1F003BF
	The Servomotors of 50 W are exempt from	5 m	R88A-CA1F005SF	R88A-CA1F005BF
200 V	the applicable Servomotors. Use these	10 m	R88A-CA1F010SF	R88A-CA1F010BF
	combination	15 m	R88A-CA1F015SF	R88A-CA1F015BF
		20 m	R88A-CA1F020SF	R88A-CA1F020BF
	200 V:	3 m	R88A-CA1H003SF	R88A-CA1H003BF
	3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW	5 m	R88A-CA1H005SF	R88A-CA1H005BF
200 V 400 V	400 V:	10 m	R88A-CA1H010SF	R88A-CA1H010BF
+00 V	3000 r/min Servomotors of 4 kW, 5 kW	15 m		R88A-CA1H015BF
	1500 r/min Servomotors of 4 kW, 5.5 kW, 7.5 kW	20 m		R88A-CA1H020BF
		3 m		R88A-CA1J003BF
		5 m		R88A-CA1J005BF
400 V	1500 r/min Servomotors of 11 kW, 15 kW	10 m		R88A-CA1J010BF
700 V	1000 I/IIIII OGIVOINOLOIS OI 11 KVV, 13 KVV	15 m		R88A-CA1J015BF
		20 m		R88A-CA1J020BF
		3 m		R88A-CA1K003BF
		5 m		R88A-CA1K005BF
200 V	1500 r/min Servomotors of 7.5 kW, 11 kW,	10 m		
200 V	15 kW	10 m		R88A-CA1K010BF R88A-CA1K015BF
				_
		20 m	100A-CA 110203F	R88A-CA1K020BF

^{*}The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

Brake Cables (Non-load side, Flexible Cable)

When you use the brake cable with cable on non-load side such as R88A-CA1A BFR, use it in combination with the motor power cable with cable on non-load side such as R88A-CA1A SFR.

Applicable Servomotor			Model
		3 m	R88A-CA1A003BFR
	100 V 3000-r/min Servomotors of 50 W, 200 W, 200 V 400 W, 750 W *	5 m	R88A-CA1A005BFR
		10 m	R88A-CA1A010BFR
		15 m	R88A-CA1A015BFR
		20 m	R88A-CA1A020BFR

^{*}The Servomotors of 100 W are exempt from the applicable Servomotors. Use these combinations with caution.

Motor Power Cables (Non-load side, Flexible Cable)

When you use the motor power cable with cable on non-load side such as R88A-CA1A SFR and the brake cable together, use the brake cable with cable on non-load side such as R88A-CA1A SFR.

	Applicable Servomotor	Without brake wire	With brake wire	
Applicable Servomotor		Model	Model	
100 V 200 V	3000-r/min Servomotors of 50 W, 200 W, 400 W, 750 W *	3 m	R88A-CA1A003SFR	
		5 m	R88A-CA1A005SFR	
		10 m	R88A-CA1A010SFR	
		15 m	R88A-CA1A015SFR	
		20 m	R88A-CA1A020SFR	

^{*}The Servomotors of 100 W are exempt from the applicable Servomotors. Use these combinations with caution.

Recommended EtherCAT Communications Cable

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length [m]	Model
			0.3	XS6W-6PUR8SS30CM-YF
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS6W-6PUR8SS50CM-YF
Standard RJ45 plugs type * 1 Wire gauge and number of pairs: AWG26, 4-pair cable		OMRON	1	XS6W-6PUR8SS100CM-YF
Cable sheath material: PUR		OWRON	2	XS6W-6PUR8SS200CM-YF
Cable color: Yellow *2	4		3	XS6W-6PUR8SS300CM-YF
			5	XS6W-6PUR8SS500CM-YF
	-	OMRON	0.3	XS5W-T421-AMD-K
Cable with Connectors on Both Ends (RJ45/RJ45)			0.5	XS5W-T421-BMD-K
Rugged RJ45 plugs type *1	100		1	XS5W-T421-CMD-K
Wire gauge and number of pairs: AWG22, 2-pair cable	* 0		2	XS5W-T421-DMD-K
Cable color: Light blue			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
Cable with Connectors on Both Ends	00	OMRON	0.5	XS5W-T421-BMC-SS
(M12 Straight/RJ45)			1	XS5W-T421-CMC-SS
Shield Strengthening Connector cable *3			2	XS5W-T421-DMC-SS
M12/Smartclick Connectors Rugged RJ45 plugs type			3	XS5W-T421-EMC-SS
Wire Gauge and Number of Pairs: AWG22, 2-pair cable			5	XS5W-T421-GMC-SS
Cable color: Black			10	XS5W-T421-JMC-SS

^{*1.} Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available. Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available. For details, refer to Cat.No.G019.

Cables/Connectors

Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables		Kuramo Electric Co.	KETH-SB *
RJ45 Connectors		Panduit Corporation	MPS588-C *

^{*}We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables		Kuramo Electric Co.	KETH-PSB-OMR *
Cables		JMACS Japan Co., Ltd.	PNET/B *
RJ45 Assembly Connector		OMRON	XS6G-T421-1 *

^{*} We recommend you to use above cable and connector together.

^{*2.} Cables colors are available in blue, yellow, or Green.

^{*3.} For details, contact your OMRON representative.

Peripheral Connector Servo Drive Side Connectors

One of each of servo drive side connectors (except the encoder connector) are included with the R88D-1SN□-ECT-51 AC Servo Drive. All connecters are also available separately for maintenance.

Name and applications	Model
Main circuit connector (CNA) \$1 For R88D-1SN01L-ECT-51/-1SN02L-ECT-51/-1SN04L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51/-1SN04H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN08H-ECT-51/-1SN09H-ECT	R88A-CN102P *4
Main circuit connector A (CNA) *2 For R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51/-1SN20F-ECT-51/-1SN30F-E	R88A-CN103P *4
Main circuit connector A (CNA) *2 For R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51	R88A-CN106P
Main circuit connector A (CNA) For R88D-1SN150F-ECT-51	R88A-CN108P
Main circuit connector B (CNB) *2 For R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51/-1SN20F-ECT-51/-1SN30F-E	R88A-CN104P *4
Main circuit connector B (CNB) *2 For R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51	R88A-CN107P
Main circuit connector B (CNB) For R88D-1SN150H-ECT-51/-1SN150F-ECT-51	R88A-CN101E
Motor connector (CNC) For R88D-1SN01L-ECT-51/-1SN02L-ECT-51/-1SN04L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51/-1SN04H-ECT-51/-1SN08H-ECT-51/-1SN04	R88A-CN101A *4
Motor connector (CNC) For R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51	R88A-CN102A *4
Motor connector (CNC) For R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51/-1SN150F-ECT-51	R88A-CN103A
Control power supply connector (CND) For R88D-1SN15H-ECT-51/-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/ -1SN20F-ECT-51/-1SN30F-ECT-51	R88A-CN101P *4
Control power supply connector (CND) For R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN150H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51/-1SN150F-ECT-51	R88A-CN105P
Main circuit connector E (CNE) *2 For R88D-1SN55H-ECT-51/-1SN75H-ECT-51/-1SN150H-ECT-51/-1SN55F-ECT-51/-1SN75F-ECT-51/-1SN150F-ECT-51	R88A-CN101D
Control I/O connector (CN1) *3	R88A-CN101C
Encoder connector (CN2)	R88A-CN101R
Brake interlock connector (CN12)	R88A-CN101B

- *1. Two short-circuit wires are connected to the connector.
- ***2.** One short-circuit wire is connected to the connector.
- ***3.** Four short-circuit wires are connected to the connector.
- ***4.** One opener is included.

Servomotor Side Connector

Applicable Servo Drive and Power Cables			Model
	100 V, 200 V	For 3,000 r/min (50 to 750 W)	R88A-CNK02R
Encoder connector	200 V	For 3000 r/min (1 kW to 3 kW), 2000 r/min, 1000 r/min	D004 0N404D
Encoder connector	400 V	For 3000 r/min (750 kW to 3 kW), 2000 r/min, 1000 r/min	R88A-CN104R
	200 V, 400 V	For 3000 r/min (4 kW to 5 kW), 1500 r/min	R88A-CN105R
Power connector (For 750 W max.) *		R88A-CN111A	
Brake connector (For 750 W max.)		R88A-CN111B	

^{*}This connector is used for power cables with cable on load side such as R88A-CA1A□□□S and R88A-CA1A□SF. This connector cannot be used for power cables with cable on non-load side such as R88A-CA1A□SFR.

External Regeneration Resistance Unit Connector

Name and applications	Model
External Regeneration Resistance Unit Connector For R88A-RR550□	R88A-CN101E *

^{*}Same connector as main circuit connector B (CNB) for R88D-1SN150H-ECT-51/-1SN150F-ECT-51.

Shield Clamp Bracket

A shield clamp is used for fixing a power cable and connecting a shield wire of the power cable with FG in Servo Drives. The shield clamp consists of the shield clamp bracket and shield clamp plate.

Name	Applicable Servo Dri	Model	
	R88D-1SN55□-ECT-51 R88D-1SN75F-ECT-51	R88A-CA1H□□□□F	
Shield Clamp Bracket	R88D-1SN150F-ECT-51	R88A-CA1J□□□□F	R88A-SC10CA
	R88D-1SN75H-ECT-51 R88D-1SN150H-ECT-51	R88A-CA1K□□□□F	

Note: An applicable power cable comes with a shield clamp bracket.

External Regeneration Resistors

Applicable Servo Drive	Specifications	Model
R88D-1SN01L-ECT-51/-1SN02L-ECT-51	Regeneration process capacity: 24 W, 15 Ω	R88A-RR12015
R88D-1SN01H-ECT-51/-1SN02H-ECT-51	Regeneration process capacity: 24 W, 25 Ω	R88A-RR12025
R88D-1SN150H-ECT-51	Regeneration process capacity: 60 W, 2.5 Ω	R88A-RR30002R5
R88D-1SN75H-ECT-51	Regeneration process capacity: 60 W, 4 Ω	R88A-RR30004
R88D-1SN55H-ECT-51	Regeneration process capacity: 60 W, 5.4 Ω	R88A-RR30005R4
R88D-1SN20H-ECT-51/-1SN30H-ECT-51/-1SN150F-ECT-51	Regeneration process capacity: 60 W, 10 Ω	R88A-RR30010
R88D-1SN01L-ECT-51/-1SN02L-ECT-51	Regeneration process capacity: 60 W, 15 Ω	R88A-RR30015
R88D-1SN55F-ECT-51/-1SN75F-ECT-51	Regeneration process capacity: 60 W, 16 Ω	R88A-RR30016
R88D-1SN15H-ECT-51	Regeneration process capacity: 60 W, 17 Ω	R88A-RR30017
R88D-1SN04L-ECT-51/-1SN08H-ECT-51/-1SN10H-ECT-51/ -1SN20F-ECT-51 */-1SN30F-ECT-51 *	Regeneration process capacity: 60 W, 20 Ω	R88A-RR30020
R88D-1SN01H-ECT-51/-1SN02H-ECT-51/-1SN04H-ECT-51	Regeneration process capacity: 60 W, 25 Ω	R88A-RR30025
R88D-1SN06F-ECT-51 */-1SN10F-ECT-51 */ -1SN15F-ECT-51 *	Regeneration process capacity: 60 W, 33 Ω	R88A-RR30033

^{*}Use two series-connected External Regeneration Resistors for this model.

External Regeneration Resistance Unit

Applicable Servo Drive	Specifications	Model
R88D-1SN150H-ECT-51	Regeneration process capacity: 120 W, 2.5 Ω	R88A-RR55002R5
R88D-1SN75H-ECT-51	Regeneration process capacity: 120W, 4 Ω	R88A-RR55004
R88D-1SN55H-ECT-51	Regeneration process capacity: 120W, 5.4 Ω	R88A-RR55005R4
R88D-1SN150F-ECT-51	Regeneration process capacity: 120W, 10 Ω	R88A-RR55010
R88D-1SN55F-ECT-51/-1SN75F-ECT-51	Regeneration process capacity: 120W, 16 Ω	R88A-RR55016
R88D-1SN150H-ECT-51	Regeneration process capacity: 640W, 2.5 Ω (with fan)	R88A-RR1K602R5
R88D-1SN75H-ECT-51	Regeneration process capacity: 640W, 4 Ω (with fan)	R88A-RR1K604
R88D-1SN55H-ECT-51	Regeneration process capacity: 640W, 5.4 Ω (with fan)	R88A-RR1K605R4
R88D-1SN20H-ECT-51/-1SN30H-ECT-51	Regeneration process capacity: 640 W, 10 Ω (with fan)	R88A-RR1K610
R88D-1SN55F-ECT-51/-1SN75F-ECT-51/-1SN150F-ECT-51	Regeneration process capacity: 640 W, 16 Ω (with fan)	R88A-RR1K616
R88D-1SN15H-ECT-51	Regeneration process capacity: 640 W, 17 Ω (with fan)	R88A-RR1K617
R88D-1SN08H-ECT-51/-1SN10H-ECT-51/ -1SN20F-ECT-51 */-1SN30F-ECT-51 */-1SN55F-ECT-51 *	Regeneration process capacity: 640 W, 20 Ω (with fan)	R88A-RR1K620
R88D-1SN20F-ECT-51/-1SN30F-ECT-51	Regeneration process capacity: 640 W, 40 Ω (with fan)	R88A-RR1K640
R88D-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51	Regeneration process capacity: 640 W, 66 Ω (with fan)	R88A-RR1K666

 $[\]ensuremath{\bigstar} \mbox{Use two series-connected External Regeneration Resistance Units for this model.}$

External Dynamic Brake Resistors

Applicable Servomotor	Specifications	Model
R88D-1SN150H-ECT	Resistance value: 1.25 Ω	R88A-DBR30001R2
R88D-1SN55H-ECT/-1SN75H-ECT	Resistance value: 1.5 Ω	R88A-DBR30001R5
R88D-1SN55F-ECT/-1SN75F-ECT	Resistance value: 4 Ω	R88A-DBR30004
R88D-1SN150F-ECT	Resistance value: 5 Ω	R88A-DBR30005

DC Reactor

For a recommended reactor for applicable Servomotor at 5.5 kW or more, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696).

Applicable Servomotor	Model
R88D-1SN01L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51	R88A-PD2002
R88D-1SN02L-ECT-51/-1SN04H-ECT-51	R88A-PD2004
R88D-1SN04L-ECT-51/-1SN08H-ECT-51	R88A-PD2007
R88D-1SN10H-ECT-51/-1SN15H-ECT-51	R88A-PD2015
R88D-1SN20H-ECT-51	R88A-PD2022
R88D-1SN30H-ECT-51	R88A-PD2037
R88D-1SN06F-ECT-51	R88A-PD4007
R88D-1SN10F-ECT-51/-1SN15F-ECT-51	R88A-PD4015
R88D-1SN20F-ECT-51	R88A-PD4022
R88D-1SN30F-ECT-51	R88A-PD4037

Footprint-type Noise Filter

For a recommended noise filter for applicable Servomotor at 5.5 kW or more, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696).

Applicable Servo Drive	Model
R88D-1SN01L-ECT-51/-1SN01H-ECT-51/-1SN02H-ECT-51 (Single-phase input)	R88A-FI1S103
R88D-1SN02L-ECT-51/-1SN04H-ECT-51 (Single-phase input)	R88A-FI1S105
R88D-1SN04L-ECT-51/-1SN08H-ECT-51 (Single-phase input)	R88A-FI1S109
R88D-1SN15H-ECT-51 (Single-phase input)	R88A-FI1S116
D00D 40N0411 F0T F4/ 40N0011 F0T F4 /0 1 1 1 1	R88A-FI1S202
R88D-1SN01H-ECT-51/-1SN02H-ECT-51 (3-phase input)	R88A-FI1S203
R88D-1SN04H-ECT-51 (3-phase input)	R88A-FI1S203
R88D-1SN08H-ECT-51 (3-phase input)/-1SN10H-ECT-51	R88A-FI1S208
R88D-1SN15H-ECT-51 (3-phase input)/-1SN20H-ECT-51/-1SN30H-ECT-51	R88A-FI1S216
R88D-1SN06F-ECT-51/-1SN10F-ECT-51/-1SN15F-ECT-51/-1SN20F-ECT-51/-1SN30F-ECT-51	R88A-FI1S309

Software

Automation Software Sysmac Studio

The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI.

For details, refer to your local OMRON website and Sysmac Studio Catalog (Cat. No. P138).

Note: The 1S-series Servo Drive with SS1/SLS Safety Function R88D-1SN□-ECT-51 is supported by Sysmac Studio version 1.59 or higher.

Collections of software functional components

Sysmac Library

Sysmac Library is POU Libraries (Function Block and Function) provided for NJ/NX-series Controller.

Please download it from following URL and install to Sysmac Studio.

http://www.ia.omron.com/sysmac_library/

Product	Features	Model
EtherCAT 1S Series Library	The EtherCAT 1S Series Library is used to initialize the absolute encoder, back up and restore the parameters for an OMRON 1S-series Servo Drive with built-in EtherCAT communications. You can use this library to reduce manpower of programming when implementing the processing for a Servo Drive.	SYSMAC-XR011

Combination table

Servo Drive and Servomotor Combinations

The following tables show the possible combinations of 1S-series Servo Drives and Servomotors.

The Servomotors and Servo Drives can only be used in the listed combinations. "
"at the end of the motor model number is for options, such as the shaft type and brake.

3,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive	
Single-phase 100 VAC	50 W	R88M-1M05030S-□	R88D-1SN01L-ECT-51	
	100 W	R88M-1M10030S-□	R88D-1SN01L-ECT-51	
	200 W	R88M-1M20030S-□	R88D-1SN02L-ECT-51	
	400 W	R88M-1M40030S-□	R88D-1SN04L-ECT-51	
	50 W	R88M-1M05030T-□	R88D-1SN01H-ECT-51	
	100 W	R88M-1M10030T-□	R88D-1SN01H-ECT-51	
Single-phase/3-phase 200 VAC	200 W	R88M-1M20030T-□	R88D-1SN02H-ECT-51	
Single-phase/3-phase 200 VAC	400 W	R88M-1M40030T-□	R88D-1SN04H-ECT-51	
	750 W	R88M-1M75030T-□	R88D-1SN08H-ECT-51	
	1.5 kW	R88M-1L1K530T-□	R88D-1SN15H-ECT-51	
	1 kW	R88M-1L1K030T-□	R88D-1SN10H-ECT-51	
	2 kW	R88M-1L2K030T-□	R88D-1SN20H-ECT-51	
3-phase 200 VAC	3 kW	R88M-1L3K030T-□	R88D-1SN30H-ECT-51	
	4 kW	R88M-1L4K030T-□	R88D-1SN55H-ECT-51	
	4.7 kW	R88M-1L4K730T-□		
3-phase 400 VAC	750 W	R88M-1L75030C-□	R88D-1SN10F-ECT-51	
	1 kW	R88M-1L1K030C-□	R88D-1SN10F-ECT-51	
	1.5 kW	R88M-1L1K530C-□	R88D-1SN15F-ECT-51	
	2 kW	R88M-1L2K030C-□	R88D-1SN20F-ECT-51	
	3 kW	R88M-1L3K030C-□	R88D-1SN30F-ECT-51	
	4 kW	R88M-1L4K030C-□	DOOD ACNEEL LOT 54	
	5 kW	R88M-1L5K030C-□	R88D-1SN55F-ECT-51	

2,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
Single-phase/3-phase 200 VAC	1.5 kW	R88M-1M1K520T-□	R88D-1SN15H-ECT-51
3-phase 200 VAC	1 kW	R88M-1M1K020T-□	R88D-1SN10H-ECT-51
	2 kW	R88M-1M2K020T-□	R88D-1SN20H-ECT-51
	3 kW	R88M-1M3K020T-□	R88D-1SN30H-ECT-51
3-phase 400 VAC	400 W	R88M-1M40020C-□	R88D-1SN06F-ECT-51
	600 W	R88M-1M60020C-□	R88D-1SN06F-ECT-51
	1 kW	R88M-1M1K020C-□	R88D-1SN10F-ECT-51
	1.5 kW	R88M-1M1K520C-□	R88D-1SN15F-ECT-51
	2 kW	R88M-1M2K020C-□	R88D-1SN20F-ECT-51
	3 kW	R88M-1M3K020C-□	R88D-1SN30F-ECT-51

1,500-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
3-phase 200 VAC	4 kW	R88M-1M4K015T-□	R88D-1SN55H-ECT-51
	5 kW	R88M-1M5K015T-□	100D-13N33H-EC1-31
	7.5 kW	R88M-1M7K515T-□	R88D-1SN75H-ECT-51
	11 kW	R88M-1M11K015T-□	R88D-1SN150H-ECT-51
	15 kW	R88M-1M15K015T-□	- NOOD-13N13011-EC1-31
3-phase 400 VAC	4 kW	R88M-1M4K015C-□	R88D-1SN55F-ECT-51
	5.5 kW	R88M-1M5K515C-□	- KOOD-13N33F-EC1-31
	7.5 kW	R88M-1M7K515C-□	R88D-1SN75F-ECT-51
	11 kW	R88M-1M11K015C-□	R88D-1SN150F-ECT-51
	15 kW	R88M-1M15K015C-□	100D-13N 130F-ECT-31

1,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
3-phase 200 VAC	900 W	R88M-1M90010T-□	R88D-1SN10H-ECT-51
	2 kW	R88M-1M2K010T-□	R88D-1SN20H-ECT-51
	3 kW	R88M-1M3K010T-□	R88D-1SN30H-ECT-51
3-phase 400 VAC	900 W	R88M-1M90010C-□	R88D-1SN10F-ECT-51
	2 kW	R88M-1M2K010C-□	R88D-1SN20F-ECT-51
	3 kW	R88M-1M3K010C-□	R88D-1SN30F-ECT-51

Servomotor and Decelerator Combinations

Backlash: 3 Arcminutes Max.

3,000-r/min Servomotors and Decelerators

Servomotor models *		Reduction ratio						
Servomotor moders &	1/5	1/11	1/21	1/33	1/45			
R88M-1M05030□			R88G-HPG	R88G-HPG 14A33050B□	R88G-HPG 14A45050B□			
R88M-1M10030□	R88G-HPG 11B05100B□	R88G-HPG 14A11100B□			R88G-HPG 20A45100B□			
R88M-1M20030□	R88G-HPG 14A05200B□	R88G-HPG 14A11200B□	R88G-HPG 20A21200B□	R88G-HPG 20A33200B□	R88G-HPG 20A45200B□			
R88M-1M40030□	R88G-HPG 14A05400B□	R88G-HPG 20A11400B□	R88G-HPG 20A21400B□	R88G-HPG 32A33400B□	R88G-HPG 32A45400B□			
R88M-1M75030□ (200 VAC)	R88G-HPG 20A05750B□	R88G-HPG 20A11750B□	R88G-HPG 32A21750B□	R88G-HPG 32A33750B□	R88G-HPG 32A45750B□			
R88M-1L75030□ (400 VAC)		R88G-HPG	R88G-HPG 32A211K5B□	R88G-HPG 32A33600SB□	- R88G-HPG 50A451K5B□			
R88M-1L1K030□	R88G-HPG			R88G-HPG				
R88M-1L1K530□	32A052K0B□	32A112K0B□						
R88M-1L2K030□			R88G-HPG 50A212K0B□	50A332K0B□				
R88M-1L3K030□	R88G-HPG 32A053K0B□	R88G-HPG 50A113K0B□	R88G-HPG 50A213K0B□					
R88M-1L4K030□	R88G-HPG 32A054K0B□	R88G-HPG						
R88M-1L4K730□ R88M-1L5K030□	R88G-HPG 32A054K0B□	50A115K0B□						

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

2,000-r/min Servomotors and Decelerators

Servomotor models *			Reduction ratio					
Servomotor models *	1/5	1/11	1/21	1/25	1/33	1/45		
R88M-1M40020□ (400 VAC)	R88G-HPG R88G-HPG		R88G-HPG		R88G-HPG	R88G-HPG 32A45400SB□		
R88M-1M60020□ (400 VAC)	32A052K0B□	32A112K0B□	32A211K5B□		32A33600SB□	R88G-HPG 50A451K5B□		
R88M-1M1K020□	R88G-HPG	R88G-HPG R88G-HPG 32A053K0B 32A112K0SB	R88G-HPG 32A211K0SB□		R88G-HPG	R88G-HPG 50A451K0SB□		
R88M-1M1K520□	0040501/0000				R88G-HPG		50A332K0SB□	
R88M-1M2K020□			50A213K0B□					
R88M-1M3K020□	R88G-HPG 32A054K0B□	R88G-HPG 50A115K0B□	R88G-HPG 50A213K0SB□	R88G-HPG 65A253K0SB□				

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

1,500-r/min Servomotors and Decelerators

Servomotor models *	Reduction ratio					
Servomotor moders &	1/5	1/11	1/12	1/21	1/25	
R88M-1M4K015□	R88G-HPG 50A055K0SB□	R88G-HPG 50A115K0SB□		R88G-HPG 65A205K0SB□	R88G-HPG 65A255K0SB□	
R88M-1M5K□15□	R88G-HPG 50A054K5TB□		R88G-HPG 65A127K5SB□	R88G-HPG 65A204K5TB□		

1,000-r/min Servomotors and Decelerators

Servomotor models *	Reduction ratio					
Servomotor moders &	1/5	1/11	1/21	1/25	1/33	1/45
R88M-1M90010□	R88G-HPG 32A05900TB□	R88G-HPG 32A11900TB□		R88G-HPG 50A21900TB□		R88G-HPG 50A33900TB□
R88M-1M2K010□	R88G-HPG 32A052K0TB□	R88G-HPG 50A112K0TB□		R88G-HPG 50A212K0TB□	R88G-HPG	
R88M-1M3K020□	R88G-HPG 50A055K0SB□	R88G-HPG 50A115K0SB□	R88G-HPG 65A205K0SB□		65A255K0SB□	

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

Backlash:15 Arcminutes Max.

3,000-r/min Servomotors and Decelerators

Servomotor models *	Reduction ratio					
Servoinotor moders &	1/5	1/9	1/15	1/25		
R88M-1M05030□	- R88G-VRXF05B100CJ	R88G-VRXF09B100CJ	R88G-VRXF15B100CJ	R88G-VRXF25B100CJ		
R88M-1M10030□	ROOG-VRAFUOD IUUCJ		KOOG-VKAF ISB IUUCJ			
R88M-1M20030□	R88G-VRXF05B200CJ	R88G-VRXF09C200CJ	R88G-VRXF15C200CJ	R88G-VRXF25C200CJ		
R88M-1M40030□	R88G-VRXF05C400CJ	R88G-VRXF09C400CJ	R88G-VRXF15C400CJ	R88G-VRXF25C400CJ		
R88M-1M75030□ (200 VAC)	R88G-VRXF05C750CJ	R88G-VRXF09D750CJ	R88G-VRXF15D750CJ	R88G-VRXF25D750CJ		

^{*}You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

Cable Connection Configuration

- Select an appropriate cable for the Servomotor.
- · Some motor power cables have two cable versions: version 1.0 and version 1.1.

The cable version can be checked on the model number label.

Version 1.0: There is no version indicated on the model number label.

Version 1.1: "Ver. 1.1" is indicated on the model number label.

To use the SLS function, use a motor power cable of the latest version. Using a motor power cable of the older version may result in a false
detection of Safety Present Motor Velocity Error 2 (Error No. 71.01) or SLS Monitoring Limit Exceeded (Error No. 72.00) during velocity
monitoring with the SLS function.

Also, using a cable longer than 20 m that is not listed may result in a false detection of Safety Present Motor Velocity Error 2 (Error No. 71.01) or SLS Monitoring Limit Exceeded (Error No. 72.00) during velocity monitoring with the SLS function.

Refer to 8-4 Safely-limited Speed (SLS) Function in the manual listed below.

The following table shows the product lineup by model.

	Power (Cables		
Power Cable model (R88A-)	Cable length	Cable version		
Power Cable Illouer (RooA-)	Cable length	Ver.1.0	Ver.1.1	
CA1A□□□S CA1A□□□SF CA1A□□□SFR CA1A□□□B CA1A□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	
CA1BOOS CA1BOOSF CA1BOOB CA1BOOBF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	
CA1COOS CA1COOSF CA1COOB CA1COOBF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	
CA1E□□□S CA1E□□□SF CA1E□□□B CA1E□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	
CA1F□□□S CA1F□□□SF CA1F□□□B CA1F□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		
CA1H0□□SF CA1H0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		
CA1J0□□SF CA1J0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		
CA1K0□□SF CA1K0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696) for details.

Precautions for Correct Use

The regulations for cables differ according to the country in use. (The regulations can also be different in the same country according to the region or where the Servomotors are installed.) Therefore, be sure to check to the respective certificate institution for a cable that conforms to the regulations of each country.

Encoder Cables

Connected to	Model	Connec	tion configuration and external dimension	ns [mm]
100 V and 200 V: 3,000-r/min Servomotors of 50 W, 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CR1A□□□C The empty boxes in the model number are for the cable length. (5.3 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 (Japan Aviation Electronics) Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1 kW to 3 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors of 3 kW or less, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Standard Cable R88A-CR1B□□□N The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)
200 V and 400 V: 3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	Standard Cable R88A-CR1B□□□V The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2VDS10SL1 (Japan Aviation Electronics) Contact model JN2V-22-22S-10000 (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 50 W, 100 W, 200 W, 400 W and 750 W	Flexible Cable R88A-CR1A□□□CF The empty boxes in the model number are for the cable length. (5.3 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1 kW to 3 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors of 3 kW or less, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Flexible Cable R88A-CR1B□□□NF The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)
200 V and 400 V: 3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	Flexible Cable R88A-CR1B□□□VF The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2VDS10SL1 (Japan Aviation Electronics) Contact model JN2V-22-22S-10000 (Japan Aviation Electronics)

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Power Cables without Brake Wire

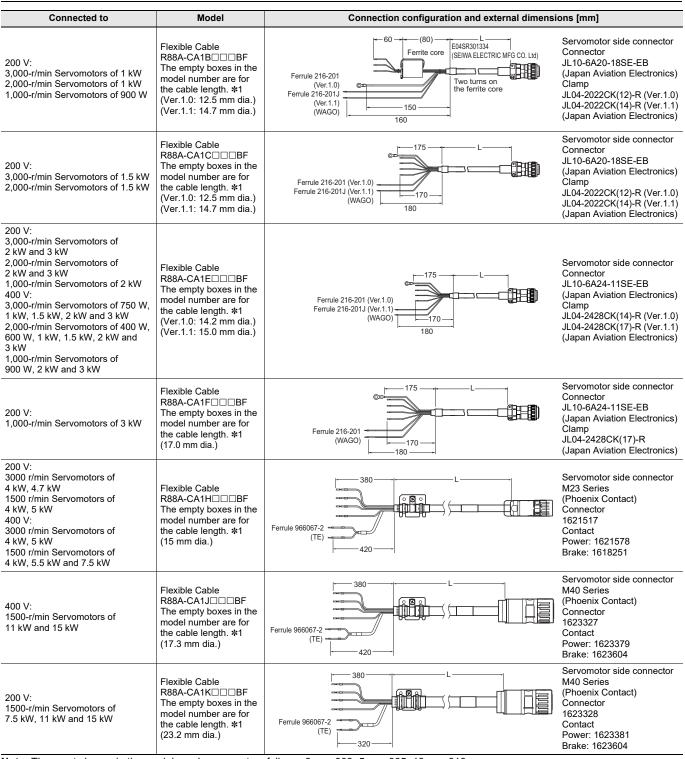
Power Cables without B	Model	Connection configuration and external dim	ensions [mm]
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□S The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 6.8 mm dia.) (Ver.1.1: 7.2 mm dia.)	Ferrite core E04SR301334 (SEIWA ELECTRIC MFG CO. Ltd) Two turns on the core	Note: 1. Use the R88A-CN111A Power Connector/Socket Contact (Omron) for this cable. Note: 2. This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696).
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors of 1 kW, and 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□□S The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 13.3 mm dia.)	60 (80) E04SR301334 (SEIWA ELECTRIC MFG CO. Ltd) Two turns on the core	Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW and 2,000-r/min Servomotors of 1.5 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1C□□□S The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 13.3 mm dia.)	175	Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Standard Cable R88A-CA1E□□□S The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 12.0 mm dia.) (Ver.1.1: 15.0 mm dia.)	175	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Standard Cable R88A-CA1F□□□S The empty boxes in the model number are for the cable length. *1 (14.5 mm dia.)	175	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(14)-R (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Flexible Cable R88A-CA1A□□SF The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 6.8 mm dia.) (Ver.1.1: 7.2 mm dia.)	Ferrite core E04SR301334 (SEIWA ELECTRIC MFG CO. Ltd) Two turns on the core	Note: 1. Use the R88A-CN111A Power Connector/Socket Contact (Omron) for this cable. Note: 2. This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub- Functions User's Manual (Cat. No. 1696).
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors of 1 kW, and 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1B□□□SF The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 15.3 mm dia.)	60 (80) E04SR301334 (SEIWA Ferrite core ELECTRIC MFG CO. Ltd) Two turns on the ferrite core	Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1C□□□SF The empty boxes in the model number are for the cable length. \$1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 15.3 mm dia.)	175	Servomotor side connector Connector JJL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)

Connected to	Model	Connection configuration and external dir	mensions [mm]
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Flexible Cable R88A-CA1E□□□SF The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 12.0 mm dia.) (Ver.1.1: 15.5 mm dia.)	175	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Flexible Cable R88A-CA1F□□□SF The empty boxes in the model number are for the cable length. *1 (14.5 mm dia.)	175 ©n	Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(14)-R (Japan Aviation Electronics)
200V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW and 7.5 kW	Flexible Cable R88A-CA1H□□□SF The empty boxes in the model number are for the cable length. *1 (15 mm dia.)	380	Servomotor side connector M23 Series (Phoenix Contact) Connector 1621517 Contact Power: 1621578
400 V: 1500-r/min Servomotors of 11 kW and 15 kW	Flexible Cable R88A-CA1J□□□SF The empty boxes in the model number are for the cable length. *1 (17.3 mm dia.)	380 L	Servomotor side connector M40 Series (Phoenix Contact) Connector 1623327 Contact Power: 1623379
200 V: 1500-r/min Servomotors of 7.5 kW,11 kW and 15 kW	Flexible Cable R88A-CA1K□□□SF The empty boxes in the model number are for the cable length. *1 (23.2 mm dia.)	380	Servomotor side connector M40 Series (Phoenix Contact) Connector 1623328 Contact Power: 1623381

Note: The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010. ***1.** Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

Power Cables with Brake Wire

Connected to	Model	Connection configuration and external dimens	sions [mm]
200 V: 3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□B The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 13.3 mm dia.)	Ferrule 216-201 (Ver.1.1) (WAGO) (80) E04SR301334 (SEWA ELECTRIC MFG CO. Ltd) Two turns on the ferrite core	Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	Standard Cable R88A-CA1C□□□B The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 13.3 mm dia.)	Ferrule 216-201 (Ver.1.0) Ferrule 216-201J (Ver.1.1) (WAGO) 170 180	Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, 2 kW and 3 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, 2 kW and 3 kW 1,000-r/min Servomotors of 900 W, 2 kW and 3 kW	Standard Cable R88A-CA1E□□□B The empty boxes in the model number are for the cable length. *1 (Ver.1.0: 14.0 mm dia.) (Ver.1.1: 15.0 mm dia.)	Ferrule 216-201 (Ver.1.0) Ferrule 216-2013 (War.1.1) (WAGO) 175 170 180	Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Ver.1.0) JL04-2428CK(17)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Standard Cable R88A-CA1F□□□B The empty boxes in the model number are for the cable length. *1 (17.0 mm dia.)	Ferrule 216-201 (WAGO) 170 180	Servomotor side connector Connector JN6FS05SJ2 (Japan Aviation Electronics) Socket contact ST-JN5-S-C1B-2500 (Japan Aviation Electronics)



Note: The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

***1.** Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

Brake Cables

Connected to	Model	Connection configuration and external dimension	ons [mm]
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□B The empty boxes in the model number are for the cable length. (5.0 mm dia.)	Ferrule 216-201 (WAGO)	Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics) Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Flexible Cable R88A-CA1A□□□BF The empty boxes in the model number are for the cable length. (5.0 mm dia.)	Ferrule 216-201 (WAGO)	Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics) Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics)

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Power Cables without Brake Wire (Non-load side, Flexible Cable)

Connected to	Model	Connection configuration and external dimensions [mm]
100 V, 200 V: 3,000-r/min Servomotors of 50 W, 200 W, 400 W and 750 W	Non-load side, Flexible Cable R88A-CA1A□□□SFR The empty boxes in the model number are for the cable length. (Ver. 1.0: 6.8 mm dia.) (Ver. 1.1: 7.2 mm dia.)	Servomotor side connector Connector Connector JN6FS05SJ1 (Japan Aviation Electronics) Socket contact ST-JN6-S-C1B-2500 (Japan Aviation Electronics)

Note: 1. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

2. This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and SS1/SLS Safety Sub-Functions User's Manual (Cat. No. 1696).

Brake Cables (Non-load side, Flexible Cable)

Connected to	Model	Connection configuration and external dimensions [mm]	
100 V, 200 V: 3,000-r/min Servomotors of 50 W,	Non-load side, Flexible Cable R88A-CA1A□□□BFR The empty boxes in the model number are for the cable length. (5.0 mm dia.)	Ferrule 216-201 (WAGO) Ferrule 216-201 (WAGO) Non-load side display label Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics	

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Related Manuals

English Man.No.	Japanese Man.No.	Model	Manual name	
1696	SBCE-541	R88M-1□/R88D-1SN□-ECT-51	AC Servomotors/Servo Drives 1S-Series with EtherCAT Communications and SS1/SLS Safety Sub-Functions User's Manual	
W535	SBCA-418	NX701-□□□□	NX-series CPU Unit User's Manual (Hardware)	
W629	SBCA-497	NX502-□□□	NX-series NX502 CPU Unit Hardware User's Manual	
W593	SBCA-462	NX102-□□□	NX-series NX102 CPU Unit Hardware User's Manual	
W578	SBCA-448	NX1P2-□□□□□□	NX-series NX1P2 CPU Unit User's Manual (Hardware)	
W500	SBCA-466	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series CPU Unit User's Manual (Hardware)	
W501	SBCA-467	NX701-□□□□ NX502-□□□□ NX102-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Software)	
W507	SBCE-433	NX701-□□□□ NX502-□□□□ NX102-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Motion Control)	
W556	SBCA-434	NY512-□□□□	NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual	
W557	SBCA-435	NY532-□□□	NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual	
W558	SBCA-436	NY532-□□□□ NY512-□□□□	NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Software User's Manual	
W559	SBCE-379	NY532-□□□□ NY512-□□□□	NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Motion Control User's Manual	
Z930	SGFM-710	NX-SLODDD NX-SIDDDD NX-SODDDD	NX-series Safety Control Unit User's Manual	
Z931	SGFM-711	NX-SL□□□□	NX-series Safety Control Unit Instructions Reference Manual	
W504	SBCA-470	SYSMAC-SE2□□□	Sysmac Studio Version 1 Operation Manual	
1589	SBCE-401	SYSMAC-SE2□□□	Sysmac Studio Drive Function Operation Manual	
Z922	SJLB-306	G9SP-N10S G9SP-N10D G9SP-N20S	G9SP Series Safety Controller Operation Manual	

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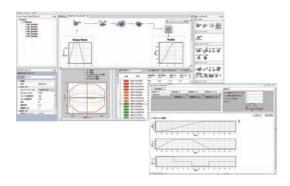
Sizing Tool for AC Servo Motors

AC Servo motors selection for the entire machine

- User can size all axes in one project with the corresponded Sysmac controller.
- Pre-defined system can be used for common applications.
- Selection of optimized drive, motor and gearbox combination.
- Multiple views are not required: design, adjust and validate at a glance.
- Import sizing file directly to Sysmac Studio for reducing the machine development time.

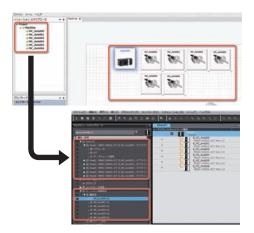
Quick sizing and selection of AC servo motors

- · High variety of mechanical system
- Import CAM from Sysmac Studio
- Kinematics chain architecture includes motor, reducer, loads and motion profile.
- Adjustments can be done in one view and results autorefreshed.



Re-use work done during design phase

- · Export sizing file result.
- · Import sizing file result in Sysmac Studio.
- EtherCAT configuration, axes settings and drives parameters will be created automatically



Compatible models

1S series	EtherCAT Communications and Safety Functionality	R88D-1SAN□-ECT
1S series	EtherCAT Communications	R88D-1SN□-ECT
G5 series	EtherCAT Communications for Position Control	R88D-KN□-ECT
G5 series	EtherCAT Communications (Linear Motor Type)	R88D-KN□-ECT-L
G5 series	MECHATROLINK-II Communications	R88D-KN□-ML2
G5 series	General-purpose Pulse Train or Analog Inputs	R88D-KT

Terms and Conditions Agreement

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Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

Suitability of Use.

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

Programmable Products.

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

Performance Data.

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

Errors and Omissions.

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

Note: Do not use this document to operate the Unit.

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CSM_2_1

Cat. No. 1928-E1-02 0325 (0724)