1S-series

OMRON

AC Servomotors (Model: R88M-1L□/-1M□)
AC Servo Drives (Model: R88D-1SN□-ECT)

INSTRUCTION MANUAL

Thank you for purchasing this OMRON Product. Please read this Instruction Manual and *User's Manual*, and thoroughly familiarize yourself with the functions and characteristics of the product before use. Be sure you are using the most recent version of the *User's Manual*. Please retain this Instruction Manual and the *User's Manual* for future reference, and be sure they are delivered to the final user of the Servomotor and Servo Drive.

OMRON Corporation

OMRON Corporation 2021 All Rights Reserved

No. 2884903-0D

Trademarks

EtherCAT⊚ is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.

Terms and Conditions Agreement

Warranties.

- (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied.
- (b) Limitations. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE.

Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or otherwise of any intellectual property right.

(c) Buyer Remedy. Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding the Products unless Omron's analysis confirms that the Products were properly handled, stored, installed and maintained and not subject to contamination, abuse, misse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty.

See http://www.omron.com/global/ or contact your Omron representative for published information

Limitation on Liability; Etc.

OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY.

Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.

Suitability of Use.

Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases.

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS

NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCT(S) IS PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

Programmable Products.

Omron Companies shall not be responsible for the user's programming of a programmable Product, or any consequence thereof.

Performance Data.

Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability.

Change in Specifications.

Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the Product may be changed without any notice. When in doubt, special part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.

Errors and Omissions.

Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.

Safety Precautions

 To ensure the safe operation of 1S-series Servomotors and Servo Drives, as well as peripheral devices, read all of this Instruction Manual and the *Us*er's Manual and be sure you understand the products, safely information, and precautions before attempting operation.

 The User's Manual may include illustrations of the products with protective covers removed in order to describe the components of the products in detail. Make sure that these protective covers are on the products before use.

Consult your OMRON representative when using a product after a long period of storage.

■ Definition of Precautionary Information

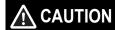
- The precautions indicated here provide important information for safety. Be sure to heed the information provided with the precautions.
- The following signal words are used to indicate and classify precautions in this Instruction Manual.



Indicates an imminently hazardous situation which, if not avoided, is likely to result in serious injury or may result in death. Additionally there may be severe property damage.



Indicates a potentially hazardous situation which, if not avoided, will result in minor or moderate injury, or may result in serious injury or death. Additionally there may be significant property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury or in property damage.

Failure to heed the precautions classified as "Caution" may also lead to serious results. Always heed these precautions.

■ Explanation of Symbols



The triangle symbol indicates precautions and warnings. The specific operation is shown in the triangle and explained in text

This example indicates a precaution for electric shock.



The triangle symbol indicates precautions and warnings. The specific operation is shown in the triangle and explained in text.

This example indicates a general precaution.



The filled circle symbol indicates operations that you must do. The specific operation is shown in the circle and explained in text.

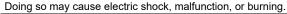
This example indicates a requirement for the ground.

■ Warning and Caution

Transporting and Unpacking

♠ WARNING

Do not damage, pull, or put excessive stress or heavy objects on the cables





Installation, Wiring and Maintenance

WARNING

Install the Servo Drive and Servomotor before wiring. Not doing so may cause electric shock.



Be sure to ground the 100-VAC or 200-VAC input model Servo Drive and Servomotor to 100 Ω or less, and the 400-VAC input model to 10Ω or less.



Not doing so may cause electric shock.

Do not remove the front cover, terminal covers, cables, or peripheral equipment while the power is supplied. Doing so may cause electric shock.



Before carrying out wiring or inspection, turn OFF the main circuit power and wait for at least the following specific time.

Not doing so may cause electric shock or burning.

10 minutes: R88D-1SN06F-ECT, R88D-1SN10F-ECT,

R88D-1SN15F-ECT. R88D-1SN20F-ECT.

R88D-1SN30F-ECT, R88D-1SN55F-ECT, R88D-1SN75F-ECT. R88D-1SN150F-ECT

15 minutes: R88D-1SN01L-ECT. R88D-1SN02L-ECT.

R88D-1SN01H-ECT, R88D-1SN02H-ECT,

R88D-1SN04H-ECT

20 minutes: R88D-1SN04L-ECT, R88D-1SN08H-ECT,

R88D-1SN10H-ECT, R88D-1SN15H-ECT, R88D-1SN20H-ECT, R88D-1SN30H-ECT, R88D-1SN55H-ECT. R88D-1SN75H-ECT.

R88D-1SN150H-ECT



MARNING

Do not damage, pull, or put excessive stress or heavy objects on the cables.



Use appropriate tools to wire terminals and connectors.

Doing so may cause electric shock, malfunction, or burning.

Check that there is no short-circuit before use. Not doing so may cause electric shock.



Connect the frame ground wire in the motor cable securely to the or FG of the Servo Drive. Not doing so may cause electric shock.



Provide safety measures, such as a fuse, to protect against short circuiting of external wiring and failure of the Servo Drive.



Not doing so may cause a fire.

Install the Servomotor, Servo Drive, and peripheral equipment on non-flammable materials such as metals



Not doing so may cause a fire.

Keep conductive or flammable foreign objects such as screws, metal pieces, and oil out of the Servo Drive and connectors. Pay particular attention to the connector on the top part of Servo Drive. Not doing so may cause a fire or electric shock.



Design the configuration to cut off the main circuit power supply when the ERR signal (normally close contact) of the control output function is output (open).



Do not bundle the motor cables. Doing so may cause fire.



Lock the power cable and extension cable connectors.



Not doing so may cause fire.



When you connect more than one Servo Drive to one noise filter, ensure that the size of wires used for the input side of the noise filter and the size of wires used between the noise filter and the relay terminal blocks are thick enough to pass at least the rated current of the noise filter.



Not doing so may cause a fire or electric shock.

Operation Check

∕N WARNING

Use the Servomotor, Servo Drive and motor cable in a specified combination

Not doing so may cause fire or equipment damage.



Usage

⚠ WARNING

Do not enter the operating area during operation. Doing so may cause injury.



Do not touch the Servo Drive radiator, Regeneration Resistor, or Servomotor while the power is supplied or for a while after the power is turned OFF because they get hot. Doing so may cause fire or a burn injury.



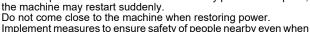
Take appropriate measures to ensure that the specified power with the rated voltage is supplied.

Be particularly careful in locations where the power supply is unstable



Not doing so may cause failure.

When the power is restored after a momentary power interruption,





the machine is restarted. Doing so may cause injury.

Use appropriate tools to wire terminals and connectors. Check that there is no short-circuit before use.



Not doing so may cause electric shock.

Be sure to observe the radiator plate installation conditions that are specified in the manual.



Not doing so may cause the Servo Drive or Servomotor to burn.



If the load that exceeds the allowable range is installed, it may cause the dynamic brake to be damaged. Be sure to use the appropriate load.



Not doing so may cause the Servo Drive to be damaged.



⚠ WARNING

The dynamic brake is intended for the stop at the time of an error and therefore it has a short-time rating.

If the dynamic brake is activated, provide an interval of 3 minutes or more before the next activation to prevent a circuit failure and burning of the Dynamic Brake Resistor.



Make a design of equipment with consideration of a distance until a Servomotor stops while safety monitoring functions are used. Not doing so may cause injury and equipment damage.



Do not place flammable materials near the Servomotor, Servo Drive, or peripheral equipment. Doing so may cause a fire.



If the Servo Drive fails, cut off the power supply to the Servo Drive at the power supply. Not doing so may cause a fire.





Use an appropriate External Regeneration Resistor. Install an external protective device such as temperature sensor to ensure safety when using the External Regeneration Resistor. Not doing so run the risk of burnout.



Use an appropriate External Dynamic Resistor. Not doing so may cause fire, crash or equipment damage.



Use the extension cables in a specified combination. Not doing so may cause fire, equipment damage.



Before operating the Servo Drive in an actual environment, check if it operates correctly based on the newly set parameters. Not doing so may cause equipment damage.



When constructing a system that includes safety functions, be sure you understand the relevant safety standards and all related information in user documentation, and design the system to comply with the standards



Not doing so may cause injury, equipment damage.



An External Regeneration Resistor or an External Regeneration Resistor Unit may become hot. In order to ensure safety, install an external protection such as a guard so as not to touch them easily. Not doing so may cause a burn injury.



Transporting and Unpacking

⚠ CAUTION

When transporting the Servo Drive, do not hold it by the cables, shield clamp, connectors or motor shaft. Injury or failure may result.



Do not step on the Servo Drive or place heavy articles on it. Injury or failure may result.



Do not overload the product. Injury or failure may result.



Be sure to observe the specified amount when piling up products. Injury or failure may result.



Wiring

A CAUTION

Be careful about sharp parts such as the corner of the equipment when handling the Servo Drive and Servomotor. Injury may result.



Wire the cables correctly and securely. Damage to Servo Drive or fire may result.



Precautions for Safe Use

- Do not store or install the Servo Drive in the following locations. Electric shock, fire, equipment damage, or malfunction may result.
 - · Locations subject to direct sunlight
 - Locations subject to temperatures outside the range specified in the specifications
 - · Locations subject to humidity outside the range specified in the specifications
 - · Locations subject to condensation as the result of severe changes in temperature
 - · Locations subject to corrosive or flammable gases
 - Locations subject to dust (especially iron dust) or salts
 - Locations subject to exposure to water, oil, or chemicals
- Locations subject to shock or vibration
- Medical electronics such as cardiac pacemakers may malfunction or injury may result.
- If an error occurs, remove the cause of the error and ensure safety, and then perform the
 error reset and restart the operation.
 Injury, equipment damage, or burning may result.
- Use a robot cable for the wiring to separately install the Servo Drive and Servomotor to moving and fixed parts of the equipment.
 Equipment damage may result.
- Connect the Servo Drive to the Servomotor without a contactor, etc.
 Malfunction or equipment damage may result.
- Do not move a power connector of a Servomotor with 4 kW or more over 5 times.
- Electric shock, equipment damage, or burning may result.
- Be sure to observe the installation conditions. Burning or failure may result.
- Take appropriate and sufficient countermeasures to provide shielding when installing systems in the following locations. Failure may result.
 - · Locations subject to static electricity or other forms of noise
 - Locations subject to strong electromagnetic fields
 - Locations subject to possible exposure to radioactivity
 - · Locations close to power lines
- Wire the cables correctly and securely.
 - Runaway motor, unintended operation of a brake, injury, or failure may result.
- Be careful when you lock the lever of a connector. You may get your finger caught in that.

Precautions for Correct Use

- When unpacking, transporting, or installing the products, observe the following instructions.
 Injury or failure may result.
 - · When lifting the products, do not drop the products.
 - · Do not grasp a plastic part of the product.
 - When lifting a Servomotor, always lift the product by grasping a metal part other than the shaft.
 - When lifting the products at 20 kg or more, always have two people lift the products. Relevant Servomotor models: R88M-1M2K010T-B□, R88M-1M3K010T-□, R88M-1M2K010C-B□, R88M-1M4K015T-□, R88M-1M5K015T-□, R88M-1M4K015C-□, R88M-1M5K515C-□, R88M-1M7K515T-□, R88M-1M7K515C-□, R88M-1M1K015T-□, R88M-1M1K015C-□ R88M-1M15K015C-□ Relevant motor power cable models: R88A-CA1E050S, R88A-CA1E040B, R88A-CA1E050B, R88A-CA1F040SF, R88A-CA1F050SF, R88A-CA1F050B, R88A-CA1F040BF, R88A-CA1F050BF
 - When lifting a Servo Drive with the following the product model, always have two people lift the product by grasping a terminal block at the upper/bottom side of Servo Drive. Do not grasp a plastic part and a connector. Relevant model: R88D-1SN150H-ECT
 - When lifting a Servo Drive with the following the product model, always have two people lift the product by holding grips at the upper/bottom side of a Servo Drives. Do not grasp a plastic part and a connector.

Relevant model: R88D-1SN150F-ECT

- Check that the eye bolts are not loose after replacing them.
 - If they are loose, the screws can come off and the Servomotor may fall during the transportation by the use of eye bolts.
- Do not put the human body under the Servomotor during the transportation.
- Be sure to observe the mounting direction. Failure may result.
- Provide the specified clearance between the Servo Drive and the inner surface of the control
 panel or other equipment.

Fire or failure may result.

- Do not apply strong impact on the motor shaft, connectors or Servo Drive.
 Failure may result.
- Do not touch the key grooves with bare hands if the Servomotor with shaft-end key grooves is used.

Injury may result.

- Use non-magnetic mounting screws. Note also that the depth of any mounted screw does not reach the effective thread length.
 Equipment damage may result.
- Be sure to observe the allowable axial load for the Servomotor.
 Equipment damage may result.
- Install equipment to prevent crash and reduce shock. Do not run the Servomotor outside the
 operable range by the use of the drive prohibition function such as overtravel.
 Crash against the stroke edge may occur depending on stopping distance and equipment
 damage may result.
- Do not block the intake or exhaust openings.
 Do not allow foreign objects to enter the Servo Drive.
 Fire may result.

- Tighten the mounting screws, terminal block screws, cable screws and shield clamp bracket screws for the Servo Drive, Servomotor, and peripheral equipment to the specified torque.
 Failure may result.
- Use crimp terminals to wire screw type terminal blocks.
 Do not connect bare stranded wires directly to terminals blocks.
 - Always use the power supply voltage specified in this document. Burning may result.
 - Do not apply a commercial power supply directly to the Servomotor.
 Fire or failure may result.
 - Disconnect all connections to the Servo Drive and Servomotor before attempting a megger test (insulation resistance measurement) on the Servo Drive and Servomotor.
 - Not doing so may result in Servo Drive and Servomotor failure. Do not perform a dielectric strength test on the Servo Drive and Servomotor.
 - Internal elements may be damaged.Carefully perform the wiring and assembling.

Fire may result.

- Carefully perform the wiring and assembling Injury may result.
- Wear the protective equipment when installing or removing the main circuit connector, main circuit connector A, main circuit connector B, main circuit connector E, control power supply connector, or motor connector.

Do not apply a force after the protrusion of the connector opener reaches the bottom dead center. (As a guide, do not apply a force of 100 N or more.)

- Do not hammer or apply any impact on connectors. Damage may result.
- Be sure to attach a shield clamp by the specified method. Electric shock may result.
- Be sure to install surge suppressors when you connect a load with an induction coil such as a relay to the control output terminal. Malfunction or equipment damage may result.
- Install an immediate stop device externally to the machine so that the operation can be stopped and the power supply is cut off immediately. Injury may result.
- Do not adjust or set parameters to extreme values, because it will make the operation unstable.
 Injury may result.
- Secure a sufficient rigidity when you install a Servomotor into equipment.
 Equipment damage or malfunction may result.
- If a problem occurs in serial communications or the computer during a test operation, you
 have no means to stop the Servomotor.
 - Connect an externally installed emergency stop switch, etc. to the Error Stop Input of the general-purpose input so that the Servomotor can be stopped without fail.
- When using the Servomotor with key, run the Servomotor in a state in which the key cannot jump out of the shaft.
 Not doing so may result in hurting people around the equipment due to the jumping key.
- Do not drive the Servomotor by the use of an external drive source.
- Do not drive the Servomotor by the use of an external drive source.
 Fire may result.
- Install a stopping device on the machine to ensure safety.
 The holding brake is not a stopping device to ensure safety.
 - Injury may result.
- Conduct a test operation after confirming that the equipment is not affected.
 Equipment damage may result.
- Do not use the built-in brake of the Servomotor for normal braking operation.
 Failure may result.
- After an earthquake, be sure to conduct safety checks.
 Electric shock, injury, or fire may result.
- Connect an emergency stop (immediate stop) relay in series with the brake interlock output. Injury or failure may result.
- Do not use the cable when it is laying in oil or water.
 Electric shock, injury, or fire may result.

- Install safety devices to prevent idling or locking of the electromagnetic brake or the gear head, or leakage of grease from the gear head.
 Injury, damage, or taint damage result.
- Be sure to turn OFF the power supply when not using the Servo Drive for a prolonged period of time.
 Injury or malfunction may result.
- If the Servomotor is not controlled, it may not be possible to maintain the stop. To ensure safety, install a stop device.
 Equipment damage or injury may result.
- Periodically run the Servomotor approximately one rotation when the oscillation operation continues at a small angle of 45° or smaller.
 Servomotor failure may result.
- When a difference between a position indicated by the Servo Drive before the power supply OFF and a position after the power supply ON is one rotation or more, check that devices are placed in appropriate areas.
- Immediately stop the operation and cut off the power supply when unusual smell, noise, smoking, abnormal heat generation, or vibration occurs.
 The Servo Drive or Servomotor may be damaged or burn.
- Fully check the shaft when you reset a brake interlock from PC tool.
- After replacing the Servo Drive, transfer to the new Servo Drive all data needed to resume operation, before restarting operation.
 Equipment damage may result.
- Do not repair the Servo Drive by disassembling it. Electric shock or injury may result.

General Specifications for Servo Drives

		Item	Specifications	
Oper	ating a	ambient temperature and humidity	0 to 55°C, 90% max. (with no condensation)	
Stora	Storage ambient temperature and humidity		-20 to 65°C, 90% max. (with no condensation)	
Oper	ating a	and storage atmosphere	No corrosive gases	
Oper	ating a	altitude	1,000 m max.	
Vibra	ition re	esistance	10 to 60 Hz and at an acceleration of 5.88 m/s ² or less (Not to be run continuously at the resonance frequency)	
Insula	Insulation resistance		Between power supply terminals/power terminals and PE terminals: $0.5~M\Omega$ min. (at 500 VDC)	
Diele	ctric s	trength	Between power supply terminals/power terminals and PE terminals: 1,500 VAC for 1 min at 50/60 Hz	
Prote	ctive s	structure	IP20 (Built into IP54 panel)	
5	SS	EMC Directives	EN 61800-3 second environment, C3 category	
da	ţį.	Low Voltage Directive	EN 61800-5-1	
International Standard SO C EU Directives		Machinery Directive	EN ISO 13849-1(Cat.3) EN 61508 EN 62061 EN 61800-5-2	
Шa	UL st	andards	UL61800-5-1	
Inte	CSA	standards	CSA C22.2 No.274	

Note: 1. The above items reflect individual evaluation testing.

The results may differ under compound conditions.

2. Disconnect all connections to the Servo Drive before attempting a megger test (insulation resistance measurement) on a Servo Drive. Not doing so may result in the Servo Drive failure. Do not perform a dielectric strength test on the Servo Drive. Internal elements may be damaged.

■ Servo Drive Rating

100-VAC Input Model: R88D-1SN□□L-ECT

Item	Unit	Model (R88D-1SN)			
item	Oilit	01L-ECT	02L-ECT	04L-ECT	
Rated voltage	VAC	100 to 120 (85 to	132)*1		
Nated voltage	VAC	Single-phase			
Power supply frequency H:		50/60 (47.5 to 63)) *1		
Rated input current	Arms	2.9	4.9	8.4	
Rated output	W	100	200	400	
Rated output current (FLA)	Arms	1.5	2.5	4.8	
Weight	kg	1.2	1.5	1.9	
External dimensions (W×H×D)	mm	40×180×185	55×180×185	65×180×215	

*1. The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

● 200-VAC Input Model: R88D-1SN□□H-ECT

Item		Unit		Model (R	(R88D-1SN)		
•	leili	Oilit	01H-ECT	02H-ECT	04H-ECT	08H-ECT	
Rated voltage		VAC	200 to 240 (1	200 to 240 (170 to 252)*1			
Nateu voitage	•	VAC		Single-phase/3-phase			
Power supply frequency		Hz	50/60 (47.5 to 63) *1				
Rated input	Single-phase	Arms	1.8	2.7	4.6	7.3	
current	3-phase	Arms	1.0	1.5	2.7	4.0	
Rated output		W	100	200	400	750	
Rated output	current (FLA)	Arms	0.8	1.5	2.5	4.6	
Weight		kg	1.2	1.2	1.5	2.0	
External dimensions (W×H×D)		mm	40×180×185		55×180×185	65×180×215	

Item		I Imit		88D-1SN)		
		Unit	10H-ECT	15H-ECT	20H-ECT	30H-ECT
			200 to 240 (1	70 to 252)*1		
Rated voltage		VAC	3-phase	Single- phase/3- phase	3-phase	
Power supply	frequency	Hz	50/60 (47.5 to 63) *1			
Rated input	Single-phase	Arms		15.7		
current	3-phase	Arms	5.8	9.0	13.0	15.9
Rated output		W	1k	1.5k	2k	3k
Rated output current (FLA)		Arms	7.7	9.7	16.2	22.3
Weight		kg	2.0	3.4	3.4	3.4
External dimensions (W×H×D)		mm	65×180×215	90×180×225		

Item	Unit	Model (R88D-1SN)			
item	Oilit	55H-ECT	75H-ECT	150H-ECT	
Rated voltage	VAC	200 to 240 (170 to	o 252) ^{*1}		
Nated Voltage	VAC	3-phase	3-phase		
Power supply frequency	Hz	50/60 (47.5 to 63) *1			
Rated input current	Arms	27.0	38.0	77.0	
Rated output	W	5.5k	7.5k	15k	
Rated output current (FLA)	Arms	28.6	42.0	70.0	
Weight	kg	9.4	9.4	21.0	
External dimensions (W×H×D) mm		200×180×235		220×400×250	

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

400-VAC Input Model: R88D-1SN□□F-ECT Use a neutral grounded 400 VAC 3-phase power supply for the 400 VAC input models.

Item	Unit	Model (R88D-1SN)					
iteiii	Oilit	06F-ECT	10F-ECT	15F-ECT	20F-ECT	30F-ECT	
Rated voltage	VAC	380 to 480	(323 to 504)	*1			
Raled vollage	VAC	3-phase					
Power supply frequency	Hz	50/60 (47.5	to 63) *1				
Rated input current	Arms	2.4	3.1	4.3	6.5	8.4	
Rated output	W	600	1k	1.5k	2k	3k	
Rated output current (FLA)	Arms	1.8	4.1	4.7	7.8	11.3	
Weight	kg	3.4	3.4	3.4	3.4	3.4	
External dimensions (W×H×D)	mm	90×180×22	5		•		

Item	Unit	Model (R88D-1SN)			
iteiii	Oill	55F-ECT	75F-ECT	150F-ECT	
Rated voltage	VAC	380 to 480 (323 to 504)*1			
Nated Voltage	VAC	3-phase			
Power supply frequency	Hz	50/60 (47.5 to 63) *1			
Rated input current	Arms	16.0	23.0	40.0	
Rated output	W	5.5k	7.5k	15k	
Rated output current (FLA)	Arms	14.5	22.6	33.9	
Weight	kg	9.4	9.4	21.0	
External dimensions (W×H×D)	mm	200×180×235		220×400×250	

^{*1.} The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.

Installation and Characteristics

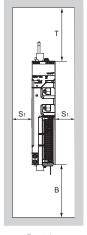
■ Space Conditions around Servo Drives

 Install the Servo Drives according to the dimension conditions shown in the following illustration, and ensure proper dispersion of heat from inside the Servo Drives and convection inside the panel.

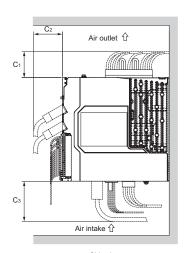
If the Servo Drives are installed side by side, install a fan for air circulation to prevent uneven temperatures inside the panel.

- R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/
 - -1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT/-1SN15H-ECT/-1SN20H-ECT/
 - -1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/
 - -1SN30F-ECT

Single-unit Installation

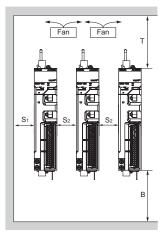


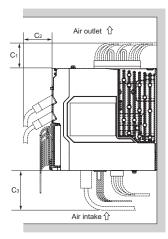




Side view

Side-by-side Installation





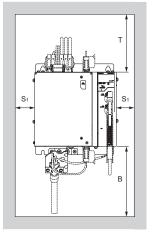
Front view Side view

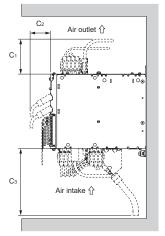
Dimensions	Distance	
T	100 mm min.	
В	100 mm min.	
S ₁	40 mm min.	
S ₂	10 mm min.	
6	R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/ -1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/ -1SN08H-ECT/-1SN10H-ECT	45 mm min.
C ₁	R88D-1SN15H-ECT/-1SN20H-ECT/ -1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/ -1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	60 mm min.
C ₂	50 mm min.	
C ₃	70 mm min.	

- · Install the Servo Drive on the vertical metal surface.
- To provide electrical conduction, remove any paint from the surface on which you install the Servo Drives. Also, it is recommended that you apply conductive plating if you make the mounting bracket by yourself.
- The recommended tightening torque for installing the Servo Drive is 1.5 N·m. Make sure that
 the threaded portion has the sufficient strength to withstand the recommended torque.
- You can install Servo Drives without the clearance of S₂ if the operating ambient temperature is from 0 to 45°C.

• R88D-1SN55H-ECT/-1SN75H-ECT/-1SN150H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT

• Single-unit Installation

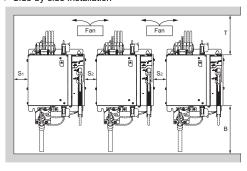




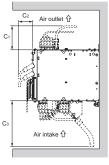
Front view

Side view

Side-by-side Installation







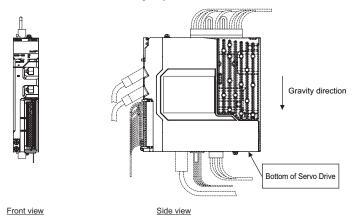
Side view

Dimensions	Distance	
Т	R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/- 1SN75F-ECT	200 mm min.
	R88D-1SN150H-ECT/-1SN150F-ECT	280 mm min.
В	500 mm min.	
S ₁	40 mm min.	
S ₂	40 mm min.	
C ₁	R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F- ECT	130 mm min.
·	R88D-1SN150H-ECT/-1SN150F-ECT	170 mm min.
C ₂	50 mm min.	
C ₃	450 mm min.	

- · Install the Servo Drive on the vertical metal surface.
- To provide electrical conduction, remove any paint from the surface on which you install the Servo Drives. Also, it is recommended that you apply conductive plating if you make the mounting bracket by yourself.
- - R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT: Tightening torque 3 N·m R88D-1SN150H-ECT/-1SN150F-ECT: Tightening torque 5.2 N·m
- Set S₂ distance over a value shown above table to install a Servo Drives.

■ Mounting Direction

Turn the bottom of Servo Drive in the gravity direction.



■ Operating Environment Conditions

The environment in which the Servo Drive is operated must meet the following conditions. The Servo Drive may malfunction if it is operated under any other conditions.

Item	Specifications
Operating ambient temperature	0 to 55°C
Operating ambient humidity	90% max. (with no condensation)
Operating atmosphere	No corrosive gases
Operating altitude	1,000 m max.

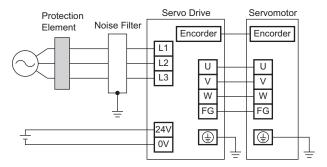
■ Ambient Temperature Control

- Operation in an environment in which there is minimal temperature rise is recommended to maintain a high level of reliability.
- When Servo Drives are installed in a closed space, such as a box, the ambient temperature
 may rise due to the heat that is generated from each unit. Use a fan or air conditioner to maintain the ambient temperature of the Servo Drive from under the operating environment conditions.
- The Servo Drive surface may rise in temperature of 30°C above the ambient temperature.
 Use heat-resistant materials for wiring, and provide a distance from any devices and wiring that are sensitive to heat.
- The use of the Servo Drive in a hot environment shortens its lifetime.
 When you use the Servo Drive in continuous operation, use a fan or air conditioner to maintain the ambient temperature at or below 40°C.

■ Keeping Foreign Objects Out of Units

- Take measures during installation and operation to keep foreign objects such as metal particles, oil, machining oil, dust, or water out of the Servo Drive.
- Place a cover over the Servo Drive or take other preventive measures to keep foreign objects such as drill filings out of the Servo Drive during installation. Be sure to remove the cover after installation is complete. If the cover is left on during operation, heat dissipation from the Servo Drive is blocked, which may result in malfunction.

■ Wiring Diagram

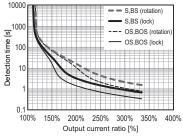


- The above diagram shows the wiring of Servomotor on the temperature protection.
- The length of motor cable must be 50 m or less.*1
- The length of encoder cable must be 50 m or less.*1
- Connect a leakage breaker and fuse as a protection element.
- *1 The cable length does not meet the EMC Directives. Refer to Compatibility Conditions of EU Directives.

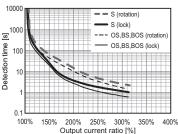
■ Overload Characteristics (Electronic Thermal Function)

- Solid state motor overload protection is provided in each model. The overload protection (electronic thermal) function is built into the Servo Drive to protect the Servo Drive and Servomotor from overloading. If an overload occurs, first eliminate the cause of the error and then wait for the Servomotor temperature to drop before you turn ON the power again. If the error reset is repeated at short intervals, the motor windings may burn out.
- The Servo Drive parameter shall be set at no more than the full load current rating of the Servomotor.
- In the some models, the detection time of the overload protection function is shorter than existing models. If the overload warning or error occur, change the operation pattern by increasing the acceleration/deceleration time or the like.

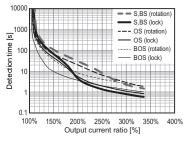
R88M-1M05030S



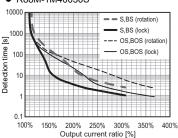
R88M-1M10030S



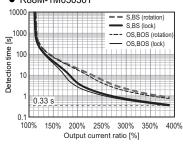
R88M-1M20030S



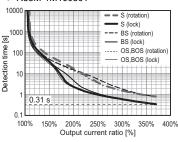
R88M-1M40030S



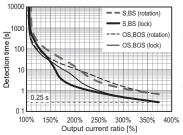
R88M-1M05030T



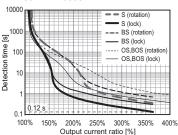
R88M-1M10030T



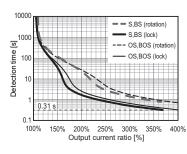
R88M-1M20030T



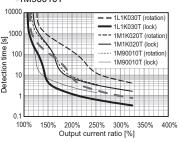
R88M-1M40030T



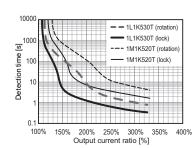
R88M-1M75030T



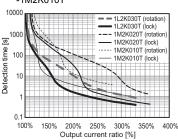
 R88M-1L1K030T/-1M1K020T/ -1M90010T



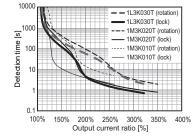
R88M-1L1K530T/-1M1K520T



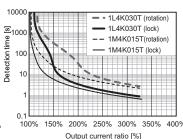
R88M-1L2K030T/-1M2K020T/ -1M2K010T



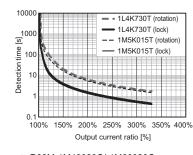
R88M-1L3K030T/-1M3K020T/ -1M3K010T



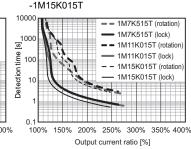
R88M-1I 4K030T/-1M4K015T



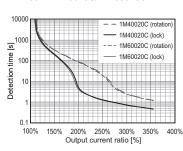
R88M-1L4K730T/-1M5K015T



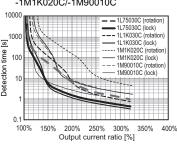
• R88M-1M7K515T/-1M11K015T/



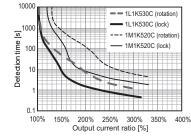
R88M-1M40020C/-1M60020C



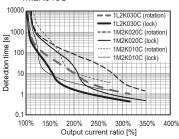
R88M-1L75030C/-1L1K030C/ -1M1K020C/-1M90010C



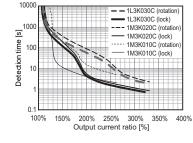
R88M-1L1K530C/-1M1K520C



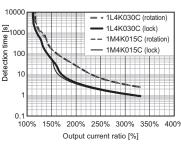
R88M-1L2K030C/-1M2K020C/ -1M2K010C



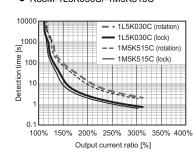
R88M-1L3K030C/-1M3K020C/ -1M3K010C



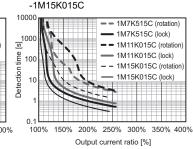
R88M-1L4K030C/-1M4K015C



R88M-1L5K030C/-1M5K515C



R88M-1M7K515C/-1M11K015C/ -1M15K015C



Terminal Block

■ Terminal Block Specifications

Symbol	Name	Specifications		
L1		R88D-1SN□□L-ECT • 100 to 400 W: Single-pl 50/60 Hz (47.5 to 63 Hz R88D-1SN□□H-ECT	hase 100 to 120 VAC (85 to 132 VAC)	
L2	Main circuit power supply input 1	• 100 to 750 W, 1.5 kW: 252 VAC) 50/60 Hz (47 • 100 to 15 kW: 3-phase	200 to 240 VAC (170 to 252 VAC)	
L3		50/60 Hz (47.5 to 63 Hz R88D-1SN□□F-ECT • 600 to 15 kW: 3-phase 50/60 Hz (47.5 to 63 Hz	380 to 480 VAC (323 to 504 VAC)	
+24V*2 0V*3	Control circuit power supply input	24 VDC±10%		
B1 ^{*4} B2 B3 ^{*5}	External Regeneration Resistor connection terminals	When the Internal Regeneration Resistor is used: *6 • Open between B1 and B2. • Short-circuit B2 and B3. When the External Regeneration Resistor is used: • Connect the External Regeneration Resistor between B1 and B2. • Open between B2 and B3.		
N1 N2	DC reactor connection terminals ^{*5}	When the DC reactor is Short-circuit N1 and When the DC reactor is Connect the DC reac	N2.	
U		Phase U	These are output terminals to the	
V	Motor connection	Phase V	Servomotor.	
W	terminals	Phase W	Be sure to wire them correctly.	
FG ^{*7}	terrinas	FG	This is a frame ground terminal for the Servomotor.	
DB1 DB2 DB3	External Dynamic brake Resistor con- nection terminals *8	When the Internal Dynamic brake Resistor is used: • Open between DB1 and DB2. • Short-circuit DB2 and DB3. When the External Dynamic brake Resistor is used: • Connect the External Dynamic brake Resistor between DB1 and DB2. • Open between DB2 and DB3.		

^{*1.} For single-phase, connect between any two phases out of the following: L1, L2, and L3.

^{*2.} For the R88D-1SN□□L-ECT, R88D-1SN0□H-ECT, and R88D-1SN10H-ECT, the symbol of this terminal is 24V.

^{*3.} For the R88D-1SN□□L-ECT, R88D-1SN0□H-ECT, and R88D-1SN10H-ECT, the symbol of this terminal is Ø .

^{*4.} For the R88D-1SN□□L-ECT, R88D-1SN0□H-ECT, and R88D-1SN10H-ECT, the symbol of this terminal is P/B1.

- *5. For the R88D-1SN150□-ECT, there is no terminal with the symbol.
- No Internal Regeneration Resistor is built into the R88D-1SNÓ1L-ECT, R88D-1SN01H-ECT, R88D-1SN02H-ECT, R88D-1SN02L-ECT, R88D-1SN04H-ECT, R88D-1SN150H-ECT, and R88D-1SN150F-ECT.
- *7. Only the R88D-1SN15H-ECT, R88D-1SN20H-ECT, R88D-1SN30H-ECT, R88D-1SN55H-ECT, R88D-1SN75H-ECT, R88D-1SN150H-ECT and R88D-1SN□□F-ECT have this terminal.
- *8. Only the R88D-1SN55□-ECT, R88D-1SN75□-ECT and R88D-1SN150□-ECT have this terminal.
- Main circuit connector (CNA): R88D-1SN□□L-ECT/R88D-1SN0□H-ECT/R88D-1SN10H-ECT

Pin No.	Symbol	1 11
1	L1	. 8888888888
2	L2	00000000000
3	L3	-
4	B3	-
5	B2	-
6	P/B1	-
7	N1	-
8	N2	-
9	N3 (Reserved)	-
10	24V	-
11	Ø	-
		-

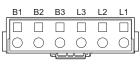
Motor connector (CNC): R88D-1SN□□L-ECT/R88D-1SN0□H-ECT/R88D-1SN10H-ECT

Pin No.	Symbol	1
1	U	Ė
2	V	
3	W	Ľ



Main circuit connector A (CNA): R88D-1SN15H-ECT/R88D-1SN20H-ECT/R88D-1SN30H-ECT/R88D-1SN06F-ECT/R88D-1SN10F-ECT/R88D-1SN15F-ECT/R88D-1SN20F-ECT/R88D-1SN30F-ECT

Pin No.	Symbol
	B1
	B2
	В3
	L3
	L2
	L1



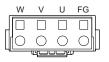
Main circuit connector B (CNB): R88D-1SN15H-ECT/R88D-1SN20H-ECT/R88D-1SN30H-ECT/R88D-1SN06F-ECT/R88D-1SN10F-ECT/R88D-1SN15F-ECT/R88D-1SN20F-ECT/R88D-1SN30F-ECT

Pin No.	Symbol
	N3 (Reserved)
	N2
	N1
	P (Reserved)



Motor connector (CNC): R88D-1SN15H-ECT/R88D-1SN20H-ECT/R88D-1SN30H-ECT/R88D-1SN06F-ECT/R88D-1SN10F-ECT/R88D-1SN15F-ECT/R88D-1SN20F-ECT/R88D-1SN30F-ECT

Pin No.	Symbol
	W
	V
	U
	FG



 Control power supply connector (CND): R88D-1SN15H-ECT/ R88D-1SN20H-ECT/ R88D-1SN30H-ECT/R88D-1SN06F-ECT/R88D-1SN10F-ECT/R88D-1SN15F-ECT/ R88D-1SN20F-ECT/R88D-1SN30F-ECT

Pin No.	Symbol
1	+24V
2	0V
3	



Main circuit connector A (CNA): R88D-1SN55□-ECT/R88D-1SN75□-ECT

Pin No.	Symbol	
	L1	L1 L2 L3 B3 B2 B1
	L2	
	L3	
	В3	
	B2	
	B1	

Main circuit connector B (CNB): R88D-1SN55□-ECT/R88D-1SN75□-ECT

Pin No.	Symbol	P N1 N2 N3
	P (Reserved)	
	N1	P N1 N2 N3
	N2	
	N3 (Reserved)	- <u> </u>

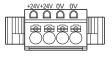
 Motor connector (CNC): R88D-1SN55□-ECT/R88D-1SN75□-ECT/ R88D-1SN150F-ECT

Pin No.	Symbol	
	FG	<u>[</u>
	U	
	V	4 1
	W	щ.



 Control power supply connector (CND): R88D-1SN55□-ECT/R88D-1SN75□-ECT/ R88D-1SN150□-ECT

Pin No.	Symbol
	+24V
	+24V
	0V
	0V



Main circuit connector E (CNE): R88D-1SN55□-ECT/R88D-1SN75□-ECT/R88D-1SN150□-ECT

Pin No.	Symbol	DB1 DB2 DB3
	DB1	DB1 DB2 DB3
	DB2	
	DB3	

• Main circuit terminal block (CNA): R88D-1SN150H-ECT

Pin No.	Symbol	
	P (Reserved)	 P N3 L3 L2 L1 ⊕
	N3 (Reserved)	
	L3	
	L2	
	L1	
	(1)	

● Main circuit connector B (CNB): R88D-1SN150□-ECT

Pin No.	Symbol	B1 B2
	B1	B1 B2
	B2	

• Motor terminal block (CNC): R88D-1SN150H-ECT

Pin No.	Symbol	U V W FG
	U	
	V	
	W	
	FG	

Main circuit connector A (CNA): R88D-1SN150F-ECT

Pin No.	Symbol	
	P (Reserved)	P N3 L3 L2 L1 🚇
	N3 (Reserved)	P N3 L3 L2 L1 🖶
	L3	
	L2	
	L1	-
	(1)	-

■ Terminal Block Wire Sizes

The following tables show the rated current that flows to the terminal block on the Servo Drive and the applicable wire sizes. Use the wire with the rated voltage of 600 V or higher for the main circuit.

The wire size is determined for when the heat-resistant polyvinyl chloride insulated wire (HIV) is used at the ambient temperature of 50°C.

Wire Sizes for 100-VAC Input Model: R88D-1SN□□L-ECT

The diagonal for the input model for all the Levi						
Item		Unit	Model (R88D-1SN)			
		Oilit	01L-ECT	02L-ECT	04L-ECT	
Power supply capacit	.y	kVA	0.4	0.6	1.0	
Main circuit power	Rated current	Arms	2.9	4.9	8.4	
	Wire size		AWG20 to 14 /0.5 to 2.0 mm ²	AWG18 to 14 /0.75 to 2.0 mm ²	AWG14 /2.0 mm ²	
Control circuit power supply input	Wire size		AWG20 to 16/0.5 to 1.5 mm ²			
Motor connection terminals*2	Rated current	Arms	1.5	2.5	4.8	
	Wire size		AWG22 to 14/ 0.32 to 2.0 mm ²	AWG20 to 14/ 0.5 to 2.0 mm ²	AWG18 to 14/ 0.75 to 2.0 mm ²	
	Wire size		AWG12/2.5 mm ² or larger			
Protective earth	Screw size		M4			
	Tightening torque	N∙m	1.2			

^{*1.} Connect between any two phases out of the following: L1, L2, and L3.

^{*2.} Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

● Wire Sizes for 200-VAC Input Model: R88D-1SN□□H-ECT

Item		11::4	Model (R88D-1SN)				
		Unit	01H-ECT	02H-ECT	04H-ECT	08H-ECT	
Power supply capacity		kVA	0.6	0.6	1.0	1.4	
Main circuit newer	Rated current	Arms	1.8/1.0 ^{*2}	2.7/1.5 ^{*2}	4.6/2.7 ^{*2}	7.3/4.0 ^{*2}	
Main circuit power supply input*1	Wire size		AWG22 to 14 /0.32 to 2.0 mm ²	AWG20 to 14 /0.5 to 2.0 mm ²	AWG18 to 14 /0.75 to 2.0 mm ²	AWG16 to 14 /1.3 to 2.0 mm ²	
Control circuit power supply input	Wire size		AWG20 to 16/0.5 to 1.5 mm ²			_	
	Rated current	Arms	0.8	1.5	2.5	4.6	
Motor connection terminals ^{*3}	Wire size		AWG22 to 1 /0.32 to 2.0		AWG20 to 14/0.5 to 2.0 mm ²	AWG18 to 14/0.75 to 2.0 mm ²	
	Wire size		AWG12/2.5 mm ² or larger				
Protective (Screw size		M4				
earth 🖃	Tightening torque	N·m	1.2				

^{*1.} For single-phase, connect between any two phases out of the following: L1, L2, and L3.

^{*3.} Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

Item		Unit	Model (R88D-1SN)			
		Unit	10H-ECT	15H-ECT	20H-ECT	30H-ECT
Power supply capacit	У	kVA	2.0	2.5	3.6	4.7
Main circuit	Rated current	Arms	5.8	15.7/9.0 ^{*2}	13.0	15.9
power supply input*1	Wire size		AWG16 to 14 /1.3 to 2.0 mm ²	AWG12 to 8	3/3.3 to 8.4 m	m ²
Control circuit power supply input	Wire size		AWG20 to 1	o 16/0.5 to 1.5 mm ²		
	Rated current	Arms	7.7	9.7	16.2	22.3
terminals*3	Wire size		AWG16 to 14 /1.3 to 2.0 mm ²	AWG14 to 8 /2.0 to 8.4 mm ²	AWG10 to 8 /5.3 to 8.4 m	
	Wire size		AWG12/2.5 mm ² or larger			
Protective (Screw size		M4			
earth 蚩	Tightening torque	N∙m	1.2			

^{*1.} For single-phase, connect between any two phases out of the following: L1, L2, and L3.

^{*2.} The first value is for single-phase input power and the second value is for 3-phase input power.

^{*2.} The first value is for single-phase input power and the second value is for 3-phase input power.

*3. Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

Item		Unit	Model (R88D-1SN)			
		Offic	55H-ECT	75H-ECT	150H-ECT	
Power supply capacit	ty	kVA	11.2 15.8		32.0	
Main circuit	Rated current	Arms	27.0	38.0	77.0	
power supply input	Wire size		AWG10 to 4 /5.3 to 25 mm ²	AWG8 to 4 /8.4 to 25 mm ²	AWG4 to 1 /21.2 to 50 mm ²	
Control circuit power supply input	Wire size		AWG20 to 16/0.5 to 1.5 mm ²			
Motor connection	Rated current	Arms	28.6	42.0	70.0	
terminals ^{*1}	Wire size		AWG10 to 4 /5.3 to 25mm ² AWG8 to 4 /8.4 to 25 mm ²		AWG4 to 1 /21.2 to 50 mm ²	
Protective earth	Wire size				AWG6/13.3 mm ² or larger	
	Screw size		M5			
	Tightening torque	N·m	2.3			

^{*1.} Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

● Wire Sizes for 400-VAC Input Model: R88D-1SN□□F-ECT

Item		Unit	Model (R88D-1SN)				
		Unit	06F-ECT	10F-ECT	15F-ECT	20F-ECT	30F-ECT
Power supply capacit	.y	kVA	1.4	2.0	2.1	4.2	5.0
	Rated current	Arms	2.4	3.1	4.3	6.5	8.4
Main circuit power supply input	Wire size	e size AWG16 to 8/1.3 to		o 8/1.3 to 8	o 8.4 mm ²		AWG 14 to 8 /2.0 to 8.4 mm ²
Control circuit power supply input	Wire size		AWG20 to 16/0.5 to 1.5 mm ²			_	
Rated Motor connection current		Arms	1.8	4.1	4.7	7.8	11.3
terminals*1	Wire size		AWG16 to 8/1.3 to 8.4 mm ² AWG14 to 8.4 mm ² AWG1				
	Wire size		AWG12/2.5 mm ² or larger				
Protective earth	Screw size		M4				
	Tightening torque	N·m	1.2				

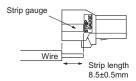
^{*1.} Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

Item		Unit	Model (R88D-1SN)			
		Offic	55F-ECT	75F-ECT	150F-ECT	
Power supply capacit	.y	kVA	13.3 19.1 33.3		33.3	
	Rated current	Arms	16.0	23.0	40.0	
supply input	Wire size		AWG12 to 4 /3.3 to 25 mm ²	AWG10 to 4 /5.3 to 25 mm ²	AWG8 to 4 /8.4 to 25 mm ²	
Control circuit power supply input	Wire size		AWG20 to 16/0.5 to 1.5 mm ²			
Motor connection terminals ^{*1}	Rated current	Arms	14.5	22.6	33.9	
	Wire size		AWG14 to 4 /2.0 to 25 mm ²	AWG10 to 4 /5.3 to 25 mm ²	AWG8 to 4 /8.4 to 25 mm ²	
Protective earth	Wire size		AWG12/2.5 mm ² or larger AWG10/5.3 mm ² or larger		² or larger	
	Screw size		M5			
	Tightening torque	N·m	2.3			

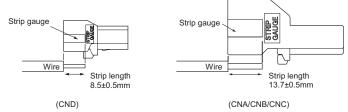
^{*1.} Provide the same current capacity for the wiring of the motor connection terminals and for that of B1 and B2.

■ Terminal Block Wiring Procedure

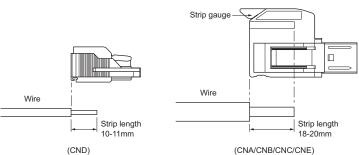
- Remove the terminal block from the Servo Drive before wiring.
 The Servo Drive may be damaged if the wiring is done with the terminal block in place.
- Strip off the covering from the wire.
 If the stripped wire is bended, loose or too large in diameter due to twist, retwist it gently and check its strip length by the use of a gauge before you use it.
 Smoothen the cut surface of wires and the stripped surface of covering. Or, you can use a ferrule.
- R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/ -1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT



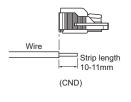
 R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/ -1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT

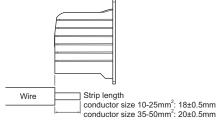


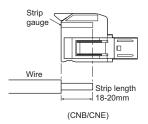
R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT



R88D-1SN150H-ECT







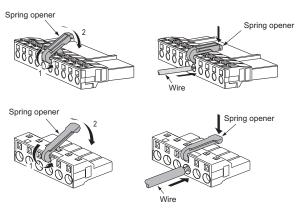
(Terminal block)

3. Connect the wires.

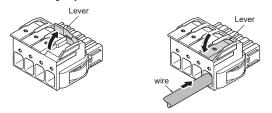
Insert the hook of the spring opener into a square hole located on the same side as the wire holes, and use your thumb to press down the lever of the spring opener until it clicks into place.

Insert the wire fully into the back of a wire hole while the lever of the spring opener is held down.

Release the lever, and then pull the wire gently to check that it does not come out.



Use fingers to push up the lever until it clicks into place. Insert the wire fully into the back of a wire hole while the lever is pushed up. Use fingers to push up the lever until it clicks into place. Pull the wire gently to make sure that it does not come out.



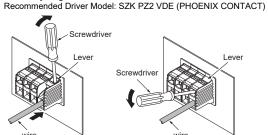
Insert a screwdriver into a hole of a lever and push up the lever.

Insert the wire fully into the back of a wire hole.

Insert the screwdriver into the hole of the lever and push down the lever.

Pull the wire gently to make sure that it is completely caught by a bracket and does not come out.

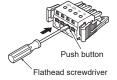
Use a fully tough screwdriver.

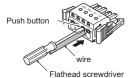


Insert the wire fully into the back of a wire hole while a push button is pressed with a flathead screwdriver.

Pull the wire gently to make sure that it does not come out.

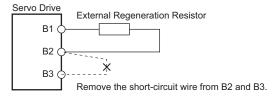
A solid wire or a twisted wire crimped the ferrule terminals can be inserted even if you do not press the push button.





■ Connection of External Regeneration Resistor

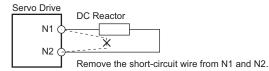
When an External Regeneration Resistor is required, remove the short-circuit wire from B2 and B3, and connect an External Regeneration Resistor between B1 and B2 as shown below.



* R88D-1SN150□-ECT does not have the B3 terminal and a short-circuit wire.

■ Connection of DC Reactor

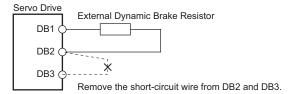
When a DC reactor is required, remove the short-circuit wire from N1 and N2, and connect a DC reactor between N1 and N2 as shown below.



* R88D-1SN150 ☐-ECT does not have the DC reactor connection terminal.

■ Connection of External Dynamic Brake Resistor

When an External Dynamic Brake Resistor is required, remove the short-circuit wire from DB2 and DB3, and connect an External Dynamic Resistor between DB1 and DB2 as shown below.



Compatibility Conditions of EU Directives

· This is a product designed for industrial environments.

Use in residential area may cause radio interference, in which case the user may be required to take adequate measures to reduce interference.

 This type of PDS is not intended to be used on a low-voltage public network which supplies domestic premises.

Manufacturer and EU Representative

Manufacturer: OMRON Corporation (Manufacturer)

Shiokoji Horikawa, Shimogyo-ku, Kyoto, 600-8530, Japan OMRON Europe B.V. (Representative and Importer in EU)

Wegalaan 67-69, 2132 JD Hoofddorp, The Netherlands

■ Compatibility Conditions of Low Voltage Directive

Installation Environment

EU Representative:

Item	Specifications
Operating ambient temperature and humidity	0 to 55°C, 90% max. (with no condensation)
Overvoltage category	III
Pollution Degree	2
Altitude	1,000 m max.
Protective structure	IP20 (To be built into the IP54 enclosure)
Protection class	I
Input power supply	AC power supply When the DC power input is used, the Servo Drive does not conform to EU standards.
Short-circuit current rating (SCCR)	5,000 Arms

■ Servo Drive Rating

● 100-VAC Input Model: R88D-1SN□□L-ECT

Item	Unit	Model (R88D-1SN)		
iteiii	Oilit	01L-ECT	02L-ECT	04L-ECT
Rated voltage	VAC	100 to 120		
Nated voltage	VAC	Single-phase		
Power supply frequency	Hz	50/60		
Rated input current	Arms	2.9	4.9	8.4
Rated output	W	100	200	400

200-VAC Input Model: R88D-1SN□□H-ECT

- 200 The input measures 201							
Item		Unit	Model (R88D-1SN)				
		Unit	01H-ECT	02H-ECT	04H-ECT	08H-ECT	
Rated voltage		VAC	200 to 240				
Nateu voltage		VAC	Single-phase/3-phase				
Power supply free	quency	Hz	50/60				
Rated input	Single-phase	Arms	1.8	2.7	4.6	7.3	
current	3-phase	Arms	1.0	1.5	2.7	4.0	
Rated output		W	100	200	400	750	

Item		Unit	Model (R88D-1SN)			
		Oilit	10H-ECT	15H-ECT	20H-ECT	30H-ECT
			200 to 240			
Rated voltage		VAC	3-phase	Single- phase/ 3-phase	3-phase	
Power supply fre	quency	Hz	50/60			
Rated input	Single-phase	Arms		15.7		
current 3-	3-phase	Arms	5.8	9.0	13.0	15.9
Rated output		W	1k	1.5k	2k	3k

Item	Unit		N)	
item	Unit	55H-ECT	75H-ECT	150H-ECT
Rated voltage	VAC	200 to 240		
Rated voltage	VAC	3-phase		
Power supply frequency	Hz	50/60		
Rated input current	Arms	27.0	38.0	77.0
Rated output	W	5.5k	7.5k	15k

400-VAC Input Model: R88D-1SN□□F-ECT Use a neutral grounded 400 VAC 3-phase power supply for the 400 VAC input models.

Item	Unit	Woder (Rood-13N)			
iteiii	Oilit	06F-ECT	10F-ECT	15F-ECT	20F-ECT
Rated voltage	VAC	380 to 480			
Rated voltage	VAC	3-phase			
Power supply frequency	Hz	50/60			
Rated input current	Arms	2.4	3.1	4.3	6.5
Rated output	W	600	1k	1.5k	2k
		Model (R88D-1SN)			
			Model (P	OOD 1CNI	
Item	Unit				
Item	Unit	30F-ECT	Model (R 55F-ECT	88D-1SN) 75F-ECT	150F-ECT
		30F-ECT 380 to 480			150F-ECT
Item Rated voltage	Unit VAC				150F-ECT
		380 to 480			150F-ECT
Rated voltage	VAC	380 to 480 3-phase			150F-ECT

Model (R88D-1SN)

- Control Circuit Power Supply Rating 24 VDC/1.2 A (Capacity of Drive 3 kW or less) Rating 24 VDC/1.6 A (Capacity of Drive 5.5 kW or more)
- Installation of Short-circuit Protection Element Connect an IEC 60269-1 CLASS gG fuse or an equivalent fuse the melting time is shorter, to the main circuit power.
 Select a fuse that satisfies the maximum current rating of the following table.

Servo Drive model	Maximum current rating
R88D-1SN01L-ECT	16 A
R88D-1SN02L-ECT	16 A
R88D-1SN04L-ECT	16 A
R88D-1SN01H-ECT	16 A
R88D-1SN02H-ECT	16 A
R88D-1SN04H-ECT	16 A
R88D-1SN08H-ECT	16 A
R88D-1SN10H-ECT	16 A
R88D-1SN15H-ECT	40 A
R88D-1SN20H-ECT	40 A
R88D-1SN30H-ECT	40 A
R88D-1SN06F-ECT	20 A
R88D-1SN10F-ECT	20 A
R88D-1SN15F-ECT	20 A
R88D-1SN20F-ECT	20 A
R88D-1SN30F-ECT	20 A

Connect the IEC60947 breaker or IEC 60269-1 CLASS gG fuse which should have the fusing time shorter than the UL class RK5 fuse or equivalence.

Select a breaker or a fuse that satisfies the maximum current rating of the following table.

Servo Drive model	Maximum current rating
R88D-1SN55H-ECT	60 A
R88D-1SN75H-ECT	60 A
R88D-1SN150H-ECT	125 A
R88D-1SN55F-ECT	30 A
R88D-1SN75F-ECT	30 A
R88D-1SN150F-ECT	60 A

■ Terminal Block Wire Sizes

The following tables show the rated current that flows to the terminal block on the Servo Drive and the applicable wire sizes.

Wire Sizes for 100-VAC Input Model: R88D-1SN□□L-ECT

Itam	ltem l		nit Model (R88D-1SN)				
iten			01L-ECT	02L-ECT	04L-ECT		
Power supply capa	acity	kVA	0.4	0.6	1.0		
Main circuit power	Rated current	Arms	2.9	4.9	8.4		
supply input ^{*1}	Wire size		0.5 to 1.5 mm ²	0.75 to 1.5 mm ²	1.5 mm ²		
Control circuit pow- er supply input	Wire size		0.5 to 1.5 mm ²				
Motor connection	Rated current	Arms	1.5	2.5	4.8		
terminals	Wire size		0.5 to 1.5 mm ²		0.75 to 1.5 mm ²		
	Wire size		2.5 mm ² or large	er	<u> </u>		
Protective earth	Screw size		M4				
earth 🖃	Tightening torque	N·m	1.2				

^{*1.} Connect between any two phases out of the following: L1, L2, and L3.

Wire Sizes for 200-VAC Input Model: R88D-1SN□□H-ECT

		1114	Model (R88D-1SN)				
Item		Unit	01H-ECT	02H-ECT	04H-ECT	08H-ECT	
Power supply capacity		kVA	0.6	0.6	1.0	1.4	
Main circuit power	Rated current	Arms	1.8/1.0 ^{*2}	2.7/1.5 ^{*2}	4.6/2.7 ^{*2}	7.3/4.0*2	
supply input ^{*1}	Wire size		0.5 to 1.5 mm ²		0.75 to 1.5 mm ²	1.5 mm ²	
Control circuit pow- er supply input	Wire size		0.5 to 1.5 mm ²				
Motor connection	Rated current	Arms	0.8	1.5	2.5	4.6	
terminals	Wire size		0.5 to 1.5 m	m ²		0.75 to 1.5 mm ²	
	Wire size		- 2.5 mm ² or larger			•	
Protective (Screw size		M4				
earth 蚩	Tightening torque	N·m	1.2				

^{*1.} For single-phase, connect between any two phases out of the following: L1, L2, and L3.

^{*2.} The first value is for single-phase input power and the second value is for 3-phase input power.

Item		Unit		Model (R	Model (R88D-1SN)		
item		Unit	10H-ECT	15H-ECT	20H-ECT	30H-ECT	
Power supply capacity		kVA	2.0	2.5	3.6	4.7	
Main circuit power supply input*1	Rated current	Arms	5.8	15.7/9.0 ^{*2}	13.0	15.9	
Supply Input	Wire size		1.5 mm ²	4.0 to 6.0 mr	n ²		
Control circuit power supply input	Wire size		0.5 to 1.5 mm ²				
Motor connection	Rated current	Arms	7.7	9.7	16.2	22.3	
terminals	Wire size		1.5 mm ²	2.5 to 6.0 mm ²	6.0 mm ²		
Protective (Wire size		2.5 mm ² or larger	4.0 mm ² or larger ^{*3}			
earth	Screw size		M4				
eaiii (=)	Tightening torque	N·m	1.2				

^{*1.} For single-phase, connect between any two phases out of the following: L1, L2, and L3.

*2. The first value is for single-phase input power and the second value is for 3-phase input power.

^{*3.} The wire size of protective earth must be greater than or equal to the wire size of main circuit power supply input.

Itam	Item			Model (R88D-1SN)				
item		Unit	55H-ECT	75H-ECT	150H-ECT			
Power supply capa	city	kVA	11.2	15.8	32.0			
Main circuit power	Rated current	Arms	27.0	38.0	77.0			
supply input	Wire size		6 to 25 mm ²	10 to 25 mm ²	25 to 50 mm ²			
Control circuit power supply input	Wire size		0.5 to 1.5 mm ²					
Motor connection terminals	Rated current	Arms	28.6	42.0	70.0			
terminais	Wire size		6 to 25 mm ²	10 to 25 mm ²	25 to 50 mm ²			
	Wire size		6 mm ² or larger	10 mm ² or larger	16 mm ² or larger			
Protective (Screw size		M5					
earth	Tightening torque	N·m	2.3					

Wire Sizes for 400-VAC Input Model: R88D-1SN□□F-ECT

Item		Unit	Model (R88D-1SN)				
		Unit	06F-ECT	10F-ECT	15F-ECT	20F-ECT	30F-ECT
Power supply capa	acity	kVA	1.4	2.0	2.1	4.2	5.0
Main circuit power	Rated current	Arms	2.4	3.1	4.3	6.5	8.4
supply input	Wire size		1.5 to 6.0 mm ²				2.5 to 6.0 mm ²
Control circuit power supply input	Wire size		0.5 to 1.5	mm ²			
Motor connection	Rated current	Arms	1.8	4.1	4.7	7.8	11.3
terminals	Wire size		1.5 to 6.0	mm ²		2.5 to 6.0	mm ²
	Wire size		2.5 mm ² d	or larger ^{*1}		•	
Protective (Screw size		M4				
earth	Tightening torque	N·m	1.2				

^{*1.} The wire size of protective earth must be greater than or equal to the wire size of main circuit power supply input.

Item		Unit	Model (R88D-1SN)			
iteii	item		55F-ECT	75F-ECT	150F-ECT	
Power supply capa	acity	kVA	13.3	19.1	33.3	
Main circuit power	Rated current	Arms	16.0	23.0	40.0	
supply input	Wire size		4 to 25 mm ²	6 to 25 mm ²	10 to 25 mm ²	
Control circuit power supply input	Wire size		0.5 to 1.5 mm ²			
Motor connection	Rated current	Arms	14.5	22.6	33.9	
terminals	Wire size		2.5 to 25 mm ²	6 to 25 mm ²	10 to 25 mm ²	
Dratactive (Wire size		4 mm ² or larger	6 mm ² or larger	10 mm ² or larger	
Protective earth	Screw size		M5			
	Tightening torque	N·m	2.3			

Wiring to Protective Earth Terminal Use a round terminal for the protective earth terminal.

■ Overload Protection (Electronic Thermal Function)

- · Servo Drive memorizes a load ratio after an overload occurs. Therefore, when you run a Servomotor under the same condition, an overload occurs earlier than when the first overload occurs
- Overload protection does not have Speed Sensitive.

■ Compatibility Conditions of EMC Directives

Wiring Conforming to EMC Directives

1S-series Servo Drives conform to EMC Directives (EN 61800-3) under the wiring conditions described in this section.

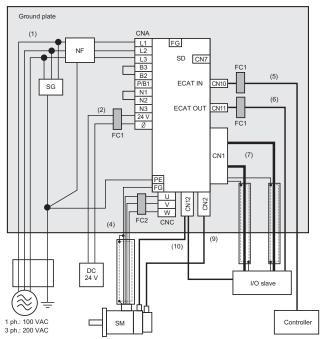
The following conditions are determined so that 1S-series products can conform to EMC Directives.

When the products are installed in the equipment, the customer must perform the check to confirm that the overall machine conforms to EMC Directives.

The following are the conditions required for conformance to the EMC Directives.

- · Install the Servo Drive on the ground plate.
- Install a noise filter and lightening surge absorbing element (surge absorber) on the power line.
- Use braided-shield cables for the I/O signals and encoder. Tinned soft steel wires must be used for the shield.
- · Ground the shield of each cable.

 Peripheral Equipment Connection Examples R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/ -1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT



Note: For single-phase inputs, connect between any two phases out of the following: L1, L2, and L3.

- Provide single-point grounding of the ground plate for unit frame grounding as shown in the above diagram.
- Use a ground wire with a minimum thickness of 2.5 mm² and arrange the wiring so that the
 protective earth wire is as short as possible.
- Install a surge absorber and noise filter near the main circuit connector of Servo Drive.
 Separate I/O wires from each other for the wiring.

Device Details

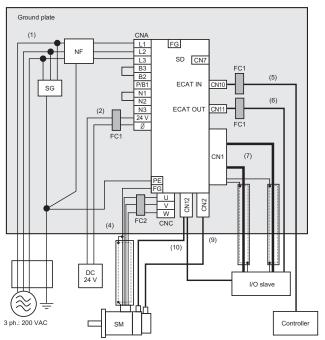
Symbol	Name	Manufacturer	Model	Remarks
SG	Surge	SOSHIN	LT-C12G801WS	1 ph. 100 VAC/200 VAC
SG	absorber	ELECTRIC	LT-C32G801WS	3 ph. 200 VAC
		SOSHIN	HF2020C-SZA- 33DDD	1 ph. 100 VAC/200 VAC (20 A)
		ELECTRIC	HF3020C-SZC- 33DDD	3 ph. 200 VAC (20 A)
				1 ph. R88D-1SN01L-ECT
			R88A-FI1S103	1 ph. R88D-1SN01H-ECT
				1 ph. R88D-1SN02H-ECT
NF	Noise filter	OMRON	R88A-FI1S105	1 ph. R88D-1SN02L-ECT
				1 ph. R88D-1SN04H-ECT
			R88A-FI1S109	1 ph. R88D-1SN04L-ECT
				1 ph. R88D-1SN08H-ECT
			R88A-FI1S202	3 ph. R88D-1SN01H-ECT
				3 ph. R88D-1SN02H-ECT
			R88A-FI1S203	3 ph. R88D-1SN04H-ECT
			R88A-FI1S208	3 ph. R88D-1SN08H-ECT
SD	Servo Drive	OMRON		*1
SM	Servomotor	OMRON		*1
FC1	Ferrite core	NEC TOKIN	ESD-SR-250	
FC2	Ferrite core	SEIWA ELECTRIC MFG	E04SR301334	
	I/O slave			
	Controller			

^{*1.} Servo Drives and Servomotors are combined according to the specifications.

· Cable Details

No.	Interface	Max. cable	Cable cla	Ferrite				
	interface	length/shield	EN/IEC 61800-3	EN/IEC 61000-6-7	core			
1	Power supply cable (main circuit)	3 m Non-shielded	Power supply port	AC input power supply port	None			
2	Power supply cable (control circuit)	3 m Non-shielded	Port for process measurement and control	Signal and control line	2 turns			
4	Motor cable (Servomotor)	20 m Shielded	Power supply interface	Signal and control line	2 turns			
5	EtherCAT communications cable (ECAT IN)	20 m Shielded	Signal interface	Signal and control line	1 turn			
6	EtherCAT communications cable (ECAT OUT)	20 m Shielded	Signal interface	Signal and control line	1 turn			
7	Safety/control	20 m Shielded	Signal interface	Signal and control line	None			
/	I/O cables	20 m Shielded	Signal interface	Signal and control line	None			
9	Encoder cable	20 m Shielded	Signal interface	Signal and control line	None			
10	Brake interlock cable	20 m Non-shielded	Signal interface	Signal and control line	None			

Peripheral Equipment Connection Examples R88D-1SN10H-ECT



- Provide single-point grounding of the ground plate for unit frame grounding as shown in the above diagram.
- Use a ground wire with a minimum thickness of 2.5 mm² and arrange the wiring so that the
 protective earth wire is as short as possible.
- Install a surge absorber and noise filter near the main circuit connector of Servo Drive.
 Separate I/O wires from each other for the wiring.

Device Details

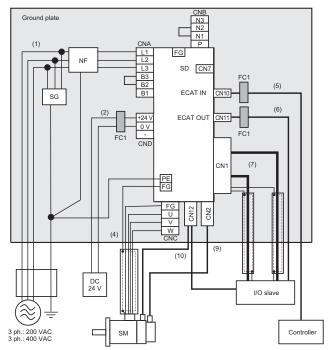
Symbol	Name	Manufacturer	Model	Remarks
SG	Surge absorber	SOSHIN ELECTRIC	LT-C32G801WS	3 ph. 200 VAC
NF	Noise filter	SOSHIN ELECTRIC	HF3020C-SZC-33DDD	3 ph. 200 VAC (20 A)
		OMRON	R88A-FI1S208	3 ph. R88D-1SN10H-ECT
SD	Servo Drive	OMRON	R88D-1SN10H-ECT	*1
SM	Servomotor	OMRON		*1
FC1	Ferrite core	NEC TOKIN	ESD-SR-250	
FC2	Ferrite core	SEIWA ELEC- TRIC MFG	E04SR301334	
	I/O slave			
	Controller			

^{*1.} Servo Drives and Servomotors are combined according to the specifications.

· Cable Details

No.	Interface	Max. cable	Cable cla	Ferrite	
NO.	interrace	length/shield	EN/IEC 61800-3	EN/IEC 61000-6-7	core
1	Power supply cable (main circuit)	3 m Non-shielded	Power supply port	AC input power supply port	None
2	Power supply cable (control circuit)	3 m Non-shielded	Port for process measurement and control	Signal and control line	2 turns
4	Motor cable (Servomotor)	20 m Shielded	Power supply interface	Signal and control line	2 turns
5	EtherCAT communications cable (ECAT IN)	20 m Shielded	Signal interface	Signal and control line	1 turn
6	EtherCAT communications cable (ECAT OUT)	20 m Shielded	Signal interface	Signal and control line	1 turn
7	Safety/control	20 m Shielded	Signal interface	Signal and control line	None
,	I/O cables	20 m Shielded	Signal interface	Signal and control line	None
9	Encoder cable	20 m Shielded	Signal interface	Signal and control line	None
10	Brake interlock cable	20 m Shielded	Signal interface	Signal and control line	None

 Peripheral Equipment Connection Examples R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN6F-ECT/-1SN10F-ECT/ -1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT



Note: For single-phase inputs, connect between any two phases out of the following: L1, L2, and L3.

Provide single-point grounding of the ground plate for unit frame grounding as shown in the

- Provide single-point grounding of the ground plate for unit frame grounding as shown in the above diagram.
- Use a ground wire with a minimum thickness of 2.5 mm² and arrange the wiring so that the
 protective earth wire is as short as possible.
- Install a surge absorber and noise filter near the main circuit connector A of Servo Drive.
 Separate I/O wires from each other for the wiring.

Device Details

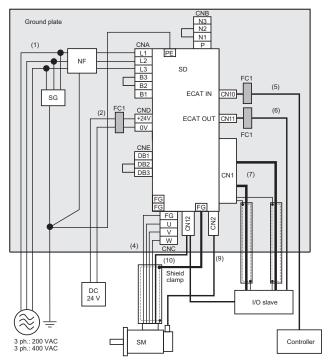
Symbol	Name	Manufacturer	Model	Remarks
	C	COCLUN	LT-C12G801WS	1 ph. 100 VAC/200 VAC
SG	Surge absorber	SOSHIN ELECTRIC	LT-C32G801WS	3 ph. 200 VAC
	absorbei	LLLOTRIC	LT-C35G102WS	3 ph. 400 VAC
		SOSHIN	HF2020C-SZC-33DDD	1 ph. 200 VAC (20 A)
		ELECTRIC	HF3020C-SZC-33DDD	3 ph. 200 VAC (20 A)
NF		LLLOTRIC	HF3020C-SZC	3 ph. 400 VAC (20 A)
			R88A-FI1S116	1 ph. R88D-1SN15H-ECT
	Noise filter	OMRON	R88A-FI1S216	3 ph. R88D-1SN15H-ECT
				3 ph. R88D-1SN20H-ECT
INF				3 ph. R88D-1SN30H-ECT
			R88A-FI1S309	3 ph. R88D-1SN06F-ECT
				3 ph. R88D-1SN10F-ECT
				3 ph. R88D-1SN15F-ECT
				3 ph. R88D-1SN20F-ECT
				3 ph. R88D-1SN30F-ECT
SD	Servo Drive	OMRON		*1
SM	Servomotor	OMRON		*1
FC1	Ferrite core	NEC TOKIN	ESD-SR-250	
	I/O slave			
	Controller			

^{*1.} Servo Drives and Servomotors are combined according to the specifications.

Cable Details

		Max. cable	Cable cla	ssification	Ferrite
No.	Interface	length/shield	EN/IEC 61800-3	EN/IEC 61000-6-7	core
1	Power supply cable (main circuit)	3 m Non-shielded	Power supply port	AC input power supply port	None
2	Power supply cable (control circuit)	3 m Non-shielded	Port for process measurement and control	Signal and control line	2 turns
4	Motor cable (Servomotor)	20 m Shielded	Power supply interface	Signal and control line	None
5	EtherCAT communications cable (ECAT IN)	20 m Shielded	Signal interface	Signal and control line	1 turn
6	EtherCAT communications cable (ECAT OUT)	20 m Shielded	Signal interface	Signal and control line	1 turn
7	Safety/control	20 m Shielded	Signal interface	Signal and control line	None
7	I/O cables	20 m Shielded	Signal interface	Signal and control line	None
9	Encoder cable	20 m Shielded	Signal interface	Signal and control line	None
10	Brake interlock cable	20 m Shielded	Signal interface	Signal and control line	None

Peripheral Equipment Connection Examples R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT



- Provide single-point grounding of the ground plate for unit frame grounding as shown in the above diagram. For grounding of the Servo Drive, use any of a PE terminal or FG terminals.
- Use a ground wire with a minimum thickness of 4.0 mm² and arrange the wiring so that the
 protective earth wire is as short as possible.
- Install a surge absorber and noise filter near the main circuit connector A of Servo Drive. Separate I/O wires from each other for the wiring.
- A shield clamp bracket comes with a power cable.

Device Details

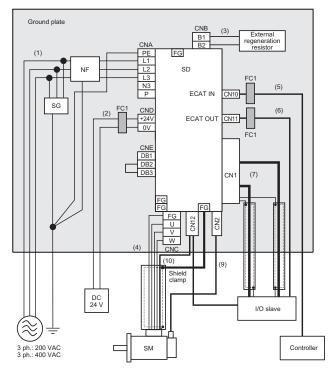
Symbol	Name	Manufacturer	Model	Remarks
SG	Surge	SOSHIN	LT-C32G801WS	3 ph. 200 VAC
36	absorber	ELECTRIC	LT-C35G102WS	3 ph. 400 VAC
			HF3040C-SZA-33EDD	3 ph. R88D-1SN55H-ECT
NF	Noise filter	SOSHIN ELECTRIC	HF3050C-SZB-33EDD HF3080C-SZC-33EDE	3 ph. R88D-1SN75H-ECT
			HF3040C-SZA-47DDD	3 ph. 400 VAC (40 A)
SD	Servo Drive	OMRON		*1
SM	Servomotor	OMRON		*1
FC1	Ferrite core	NEC TOKIN	ESD-SR-250	
	I/O slave			
	Controller			

^{*1.} Servo Drives and Servomotors are combined according to the specifications.

· Cable Details

No.	Interface	Max. cable	Cable cla	Ferrite	
NO.	interiace	length/shield	EN/IEC 61800-3	EN/IEC 61000-6-7	core
1	Power supply cable (main circuit)	3 m Non-shielded	Power supply port	AC input power supply port	None
2	Power supply cable (control circuit)	3 m Non-shielded	Port for process measurement and control	Signal and control line	2 turns
4	Motor cable (Servomotor)	20 m Shielded	Power supply interface	Signal and control line	None
5	EtherCAT communications cable (ECAT IN)	20 m Shielded	Signal interface	Signal and control line	1 turn
6	EtherCAT communications cable (ECAT OUT)	20 m Shielded	Signal interface	Signal and control line	1 turn
7	Safety/control	20 m Shielded	Signal interface	Signal and control line	None
1	I/O cables	20 m Shielded	Signal interface	Signal and control line	None
9	Encoder cable	20 m Shielded	Signal interface	Signal and control line	None
10	Brake interlock cable	20 m Shielded	Signal interface	Signal and control line	None

Peripheral Equipment Connection Examples R88D-1SN150H-ECT/-1SN150F-ECT



- Provide single-point grounding of the ground plate for unit frame grounding as shown in the above diagram. For grounding of the Servo Drive, use any of a PE terminal or FG terminals.
- Use a ground wire with a minimum thickness of 4.0 mm² and arrange the wiring so that the
 protective earth wire is as short as possible.
- Install a surge absorber and noise filter near the main circuit connector A of Servo Drive. Separate I/O wires from each other for the wiring.
- · A shield clamp bracket comes with a power cable.

Device Details

Symbol	Name	Manufacturer	Model	Remarks
SG	Surge	SOSHIN	LT-C32G801WS	3 ph. 200 VAC
36	absorber	ELECTRIC	LT-C35G102WS	3 ph. 400 VAC
NF	Noise filter	SOSHIN	HF3100C-SZC-33EDE	3 ph. 200 VAC
INF	Noise illei	ELECTRIC	HF3080C-SZC-47EDE	3 ph. 400 VAC
SD	Servo Drive	OMRON		*1
SM	Servomotor	OMRON		*1
FC1	Ferrite core	NEC TOKIN	ESD-SR-250	
	I/O slave			
	Controller			
	External re-		R88A-RR55002R5	3 ph. 200 VAC
	generation resistor	OMRON	R88A-RR55010	3 ph. 400 VAC

^{*1.} Servo Drives and Servomotors are combined according to the specifications.

· Cable Details

No.	Interface	Max. cable	Cable cla	Ferrite	
NO.	interiace	length/shield	EN/IEC 61800-3	EN/IEC 61000-6-7	core
1	Power supply cable (main circuit)	3 m Non-shielded	Power supply port	AC input power supply port	None
2	Power supply cable (control circuit)	3 m Non-shielded	Port for process measurement and control	Signal and control line	2 turns
3	Motor cable (External Regeneration)	0.5 m Shielded	Power supply interface	Signal and control line	None
4	Motor cable (Motor)	20 m Shielded	Power supply interface	Signal and control line	None
5	EtherCAT communications cable (ECAT IN)	20 m Shielded	Signal interface	Signal and control line	1 turn
6	EtherCAT communications cable (ECAT OUT)	20 m Shielded	Signal interface	Signal and control line	1 turn
7	Safety/control	20 m Shielded	Signal interface	Signal and control line	None
,	I/O cables	20 m Shielded	Signal interface	Signal and control line	None
9	Encoder cable	20 m Shielded	Signal interface	Signal and control line	None
10	Brake interlock cable	20 m Shielded	Signal interface	Signal and control line	None

Compatibility Conditions of UL/CSA Standards

Installation Environment

Item	Specifications
Maximum surrounding Air Temperature	55°C
Storage environment rating (For Canada)	-20 to 65°C
Overvoltage category	III
Pollution Degree	2
Location	At a maximum altitude of 1,000 m
Protection class	I
	AC power supply
Input power supply	When the DC power input is used, the Servo
	Drive does not conform to UL/CSA standards.

· Attach the included warning label inside the control panel.

■ Servo Drive Rating

● 100-VAC Input Model: R88D-1SN□□L-ECT

Item	Unit	Model (R88D-1SN)			
item	Oilit	01L-ECT	02L-ECT	04L-ECT	
Rated voltage	VAC	100 to 120			
Rated voltage	VAC	Single-phase			
Power supply frequency	Hz	50/60			
Rated input current	Arms	2.9	4.9	8.4	
Rated output current (FLA)	Arms	1.5	2.5	4.8	
Short-circuit current rating (SCCR)		120 V 5,000 Arms			

● 200-VAC Input Model: R88D-1SN□□H-ECT

Item		Unit	Model (R88D-1SN)					
		Oilit	01H-ECT	02H-ECT	04H-ECT	08H-ECT		
Rated voltage		VAC	200 to 240					
		VAC	Single-phas	Single-phase/3-phase				
Power supply frequency		Hz	50/60	50/60				
Rated input	Single-phase	Arms	1.8	2.7	4.6	7.3		
current	3-phase	Arms	1.0	1.5	2.7	4.0		
Rated output current (FLA)		Arms	0.8	1.5	2.5	4.6		
Short-circuit curre	ent rating (SCCR)		240 V 5,000 Arms					

Item		Unit	Model (R88D-1SN)			
		Oilit	10H-ECT	15H-ECT	20H-ECT	30H-ECT
Rated voltage			200 to 240			
		VAC	3-phase	Single- phase/3- phase	3-phase	
Power supply f	requency	Hz	50/60			
Rated input	Single-phase	Arms		15.7		
current	3-phase	Arms	5.8	9.0	13.0	15.9
Rated output c	urrent (FLA)	Arms	7.7	9.7	16.2	22.3
Short-circuit current rating (SCCR)			240 V 5,000 Arms			

Item	Unit	Model (R88D-1SN)				
item	Unit	55H-ECT	75H-ECT	150H-ECT		
Rated voltage	VAC	200 to 240				
Nated Voltage	VAC	3-phase				
Power supply frequency	Hz	50/60				
Rated input current	Arms	27.0	38.0	77.0		
Rated output current (FLA)	Arms	28.6	42.0	70.0		
Short-circuit current rating (SCCR)		240 V 5,000 Arms				

● 400-VAC Input Model: R88D-1SN□□F-ECT

Item	Unit	Model (R88D-1SN)					
item	Unit	06F-ECT	10F-ECT	15F-ECT	20F-ECT		
Rated voltage	VAC	380/219Y-48	380/219Y-480/277Y				
Rated voltage	VAC	3-phase					
Power supply frequency	Hz	50/60					
Rated input current	Arms	2.4	3.1	4.3	6.5		
Rated output current (FLA)	Arms	1.8	4.1	4.7	7.8		
Short-circuit current		480 V 5,000	Arms				

Item	Unit	Model (R88D-1SN)				
item	Oilit	30F-ECT	55F-ECT	75F-ECT	150F-ECT	
Rated voltage	VAC	380/219Y-48	380/219Y-480/277Y			
Rated voltage	VAC	3-phase				
Power supply frequency	Hz	50/60				
Rated input current	Arms	8.4	16.0	23.0	40.0	
Rated output current (FLA)	Arms	11.3	14.5	22.6	33.9	
Short-circuit current rating (SCCR)		480 V 5,000 Arms				

- Control Circuit Power Supply
- Capacity of Drive 3 kW or less
 Rating 24 VDC/1.2 A
- Control Circuit Overcurrent Protection is required.

 Capacity of Drive 5.5 kW or more

Rating 24 VDC (Class 2)/1.6A Terminal Block Wire Sizes

The following tables show the rated current that flows to the terminal block on the Servo Drive and the applicable wire sizes.

Use 75°C Copper Conductors only.

Wire Sizes for 100-VAC Input Model: R88D-1SN□□L-ECT

Ito	Item		Model (R88D-1SN)				
item		Unit	01L-ECT	02L-ECT	04L-ECT		
Power supply capacity		kVA	0.4	0.6	1.0		
	Rated current	Arms	2.9	4.9	8.4		
supply input*1	Wire size		AWG14				
Motor connection	Rated current	Arms	1.5	2.5	4.8		
terminals	Wire size		AWG14				
	Wire size		AWG12 or larg	ger			
Protective (Screw size		M4				
earth E	Tightening torque	Lb·In	10.7				

^{*1.} Connect between any two phases out of the following: L1, L2, and L3.

Wire Sizes for 200-VAC Input Model: R88D-1SN□□H-ECT

Item		Unit	Model (R88D-1SN)				
		Oilit	01H-ECT	02H-ECT	04H-ECT	08H-ECT	
Power supply capacity		kVA	0.6	0.6	1.0	1.4	
Main circuit power	Rated current	Arms	1.8/1.0 ^{*2}	2.7/1.5 ^{*2}	4.6/2.7 ^{*2}	7.3/4.0*2	
supply input ^{*1}	Wire size		AWG14				
Motor connection	Rated current	Arms	0.8	1.5	2.5	4.6	
terminals	Wire size		AWG14				
Durata ativa	Wire size		AWG12 or	larger			
Protective earth	Screw size		M4				
	Tightening torque	Lb·In	10.7				

^{*1.} For single-phase inputs, connect between any two phases out of the following: L1, L2, and L3.

^{*2.} The first value is for single-phase input power and the second value is for 3-phase input power.

Item		Unit	Model (R88D-1SN)				
		Oilit	10H-ECT	15H-ECT	20H-ECT	30H-ECT	
Power supply capacity		kVA	2.0	2.5	3.6	4.7	
Main circuit power supply input 1	Rated current	Arms	5.8	15.7/9.0 ^{*2}	13.0	15.9	
	Wire size		AWG14	AWG12 to 8			

Item		Unit	Model (R88D-1SN)				
		Unit	10H-ECT	15H-ECT	20H-ECT	30H-ECT	
Motor connection terminals	Rated current	Arms	7.7	9.7	16.2	22.3	
	Wire size		AWG14	AWG14 to 8	AWG10 to 8		
	Wire size		AWG12 or larger				
Protective (Screw size		M4				
earth	Tightening torque	Lb·ln	10.7				

^{*1.} For single-phase inputs, connect between any two phases out of the following: L1, L2, and L3.
*2. The first value is for single-phase input power and the second value is for 3-phase input power.

Item		Unit	Model (R88D-1SN)				
		Unit	55H-ECT	75H-ECT	150H-ECT		
Power supply cap	acity	kVA	11.2	15.8	32.0		
Main circuit power	Rated current	Arms	27.0	38.0	77.0		
supply input	Wire size		AWG8 to 4		AWG3 to 1		
Motor connection	Rated current	Arms	28.6	42.0	70.0		
terminals	Wire size		AWG8 to 4	AWG6 to 4	AWG3 to 1		
	Wire size		AWG10 or larger		AWG6 or larger		
Protective (Screw size		M5				
earth Enderth	Tightening torque	Lb·ln	20.4				

● Wire Sizes for 400-VAC Input Model: R88D-1SN□□F-ECT

Item		Unit		Мо	odel (R88D-1SN)		
		Unit	06F-ECT	10F-ECT	15F-ECT	20F-ECT	30F-ECT
Power supply ca	apacity	kVA	1.4	2.0	2.1	4.2	5.0
Main circuit	Rated current	Arms	2.4	3.1	4.3	6.5	8.4
power supply input	Wire size		AWG14 to 8				
Motor connection	Rated current	Arms	1.8	4.1	4.7	7.8	11.3
terminals	Wire size		AWG14 to 8				
	Wire size		AWG12 or	arger			
Protective arth	Screw size		M4				
	Tight- ening torque	Lb·ln	10.7				

Item		Unit		Model (R88D-1SN)			
		Unit	55F-ECT	75F-ECT	150F-ECT		
Power supply ca	apacity	kVA	13.3	19.1	33.3		
Main circuit	Rated current	Arms	16.0	23.0	40.0		
power supply input	Wire size		AWG12 to 4	AWG10 to 4	AWG8 to 4		
Motor	Rated current	Arms	14.5	22.6	33.9		
connection terminals	Wire size		AWG12 to 4	AWG10 to 4	AWG8 to 4		
	Wire size		AWG12 or larger	AWG10 or larger			
Protective (Screw size		M5				
Carui (E)	Tight- ening torque	Lb·ln	20.4				

- Wiring to Main Circuit Terminal
 In order to conform to UL/CSA standards, be sure to use the connector which comes with
 the Servo Drive.
- Wiring to Protective Earth Terminal
 Use a UL-listed round terminal for the protective earth terminal.
- Main Circuit Wiring
 Suitable for use on a circuit capable of delivering not more than 5,000 Arms symmetrical amperes, maximum rated input voltage when protected by UL-listed fuses or by UL-listed brak

Be sure to connect a UL-listed molded case fuse or a UL-listed braker.

Integral solid state short circuit protection does not provide branch circuit protection.

- Branch circuit protection must be provided in accordance with the Manufacturer Instructions, National Electrical Code and any additional local codes.
- Integral solid state short circuit protection (For Canada)
 Integral solid state short circuit protection does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the Canadian Electrical Code, Part 1.
- Use the fuse from the following table as well as an equivalent, or the fuse that belongs to the following class: CC, CF, G, J, R or T.

Servo Drive model	CLASS	Voltage (Minimum)	Ampere
R88D-1SN01L-ECT	RK5	120 V	15 A
R88D-1SN02L-ECT	RK5	120 V	15 A
R88D-1SN04L-ECT	RK5	120 V	15 A
R88D-1SN01H-ECT	RK5	240 V	15 A
R88D-1SN02H-ECT	RK5	240 V	15 A
R88D-1SN04H-ECT	RK5	240 V	15 A
R88D-1SN08H-ECT	RK5	240 V	15 A
R88D-1SN10H-ECT	RK5	240 V	15 A
R88D-1SN15H-ECT	RK5	240 V	40 A

Servo Drive model	CLASS	Voltage (Minimum)	Ampere
R88D-1SN20H-ECT	RK5	240 V	40 A
R88D-1SN30H-ECT	RK5	240 V	40 A
R88D-1SN06F-ECT	RK5	480 V	20 A
R88D-1SN10F-ECT	RK5	480 V	20 A
R88D-1SN15F-ECT	RK5	480 V	20 A
R88D-1SN20F-ECT	RK5	480 V	20 A
R88D-1SN30F-ECT	RK5	480 V	20 A

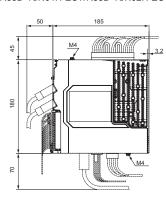
 Use the UL-listed breaker or UL class fuse (RK5, CC, CF, G, J, R or T) which has the rated current in the table.

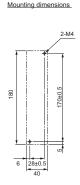
Servo Drive model	Voltage (Minimum)	Ampere
R88D-1SN55H-ECT	240 V	60 A
R88D-1SN75H-ECT	240 V	60 A
R88D-1SN150H-ECT	240 V	125 A
R88D-1SN55F-ECT	480 V	30 A
R88D-1SN75F-ECT	480 V	30 A
R88D-1SN150F-ECT	480 V	60 A

■ External and Mounting Dimensions

• R88D-1SN01L-ECT/R88D-1SN01H-ECT/R88D-1SN02H-ECT



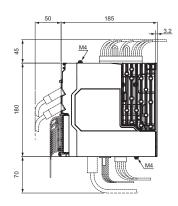


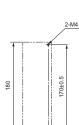


Servo Drive model	Weight
R88D-1SN01L-ECT	1.2 kg
R88D-1SN01H-ECT	1.2 kg
R88D-1SN02H-ECT	1.2 kg

• R88D-1SN02L-ECT/R88D-1SN04H-ECT

External Dimensions 55 42-M4





43±0.5

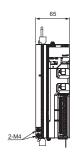
55

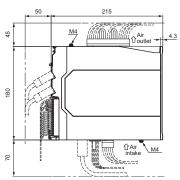
Mounting dimensions

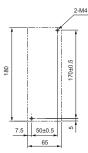
Servo Drive model	Weight
R88D-1SN02L-ECT	1.5 kg
R88D-1SN04H-ECT	1.5 kg

R88D-1SN04L-ECT/R88D-1SN08H-ECT/R88D-1SN10H-ECT

External dimensions Mounting dimensions

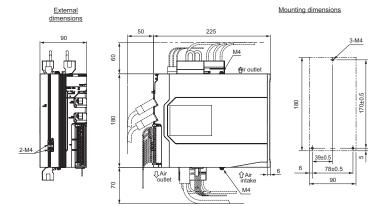






Servo Drive model	Weight
R88D-1SN04L-ECT	1.9 kg
R88D-1SN08H-ECT	2.0 kg
R88D-1SN10H-ECT	2.0 kg

R88D-1SN15H-ECT/R88D-1SN20H-ECT/R88D-1SN30H-ECT/R88D-1SN10F-ECT/R88D-1SN10F-ECT/R88D-1SN10F-ECT/R88D-1SN30F-ECT/R

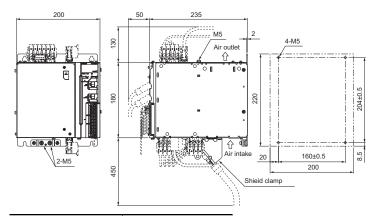


Servo Drive model	Weight
R88D-1SN15H-ECT	3.4 kg
R88D-1SN20H-ECT	3.4 kg
R88D-1SN30H-ECT	3.4 kg
R88D-1SN06F-ECT	3.4 kg
R88D-1SN10F-ECT	3.4 kg
R88D-1SN15F-ECT	3.4 kg
R88D-1SN20F-ECT	3.4 kg
R88D-1SN30F-ECT	3.4 kg

• R88D-1SN55H-ECT/R88D-1SN75H-ECT/R88D-1SN55F-ECT/R88D-1SN75F-ECT

External dimensions

Mounting dimensions



Servo Drive model	Weight
R88D-1SN55H-ECT	9.4 kg
R88D-1SN75H-ECT	9.4 kg
R88D-1SN55F-ECT	9.4 kg
R88D-1SN75F-ECT	9.4 kg

• R88D-1SN150H-ECT

External dimensions

Mounting dimensions

Air outlet 1

Air outlet 2

Air outlet 2

Air outlet 3

Air intake 30

Air intake 30

Air intake 320

Servo Drive model	Weight
R88D-1SN150H-ECT	21 kg

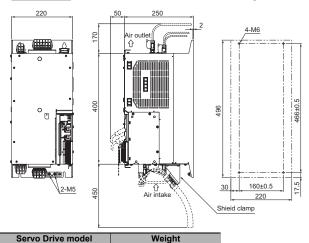
Shieid clamp

• R88D-1SN150F-ECT

External dimensions

R88D-1SN150F-ECT

Mounting dimensions



21 kg

Korean Radio Regulations (KC)

· Observe the following precaution if you use this product in Korea.

사용자안내문

이 기기는 업무용 환경에서 사용할 목적으로 적합성평가를 받은 기기로서 가정용 환경에서 사용하는 경우 전파간선의 우려가 있습니다

■ Guide for Users

This equipment has been evaluated for conformity in a commercial environment. When used in a residential environment, it may cause radio interference.

- The 1S-series Servo Drives comply with the Korean Radio Regulations (KC).
- The 1S-series Servomotors are exempt from the Korean Radio Regulations (KC).

National standard (GB)

Rated output 550 W or more Servomotors comply with the following national standard (GB).

GB 30253《永磁同步电动机能效限定值及能效等级》

Combinations of Servo Drives and Servomotors

Combination Tables

The tables in this section show the possible combinations of 1S-series Servo Drives and Servomotors. The Servomotors and Servo Drives can only be used in the listed combinations. "

at the end of the motor model number is for options, such as the shaft type and brake.

3.000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Rated output	Servomotor	Servo Drive
Single-phase 100	50 W	R88M-1M05030S-□	R88D-1SN01L-ECT
VAC	100 W	R88M-1M10030S-□	R88D-1SN01L-ECT
	200 W	R88M-1M20030S-□	R88D-1SN02L-ECT
	400 W	R88M-1M40030S-□	R88D-1SN04L-ECT
Single-phase/3-phase	50 W	R88M-1M05030T-□	R88D-1SN01H-ECT
200 VAC	100 W	R88M-1M10030T-□	R88D-1SN01H-ECT
	200 W	R88M-1M20030T-□	R88D-1SN02H-ECT
	400 W	R88M-1M40030T-□	R88D-1SN04H-ECT
	750 W	R88M-1M75030T-□	R88D-1SN08H-ECT
	1.5 kW	R88M-1L1K530T-□	R88D-1SN15H-ECT
3-phase 200 VAC	1 kW	R88M-1L1K030T-□	R88D-1SN10H-ECT
	2 kW	R88M-1L2K030T-□	R88D-1SN20H-ECT
	3 kW	R88M-1L3K030T-□	R88D-1SN30H-ECT
	4 kW	R88M-1L4K030T-□	R88D-1SN55H-ECT
	4.7 kW	R88M-1L4K730T-□	R88D-1SN55H-ECT

Main circuit power supply voltage	Rated output	Servomotor	Servo Drive
3-phase 400 VAC	750 W	R88M-1L75030C-□	R88D-1SN10F-ECT
	1 kW	R88M-1L1K030C-□	R88D-1SN10F-ECT
	1.5 kW	R88M-1L1K530C-□	R88D-1SN15F-ECT
	2 kW	R88M-1L2K030C-□	R88D-1SN20F-ECT
	3 kW	R88M-1L3K030C-□	R88D-1SN30F-ECT
	4 kW	R88M-1L4K030C-□	R88D-1SN55F-ECT
	5 kW	R88M-1L5K030C-□	R88D-1SN55F-ECT

• 2,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Rated output	Servomotor	Servo Drive
Single-phase/3-phase 200 VAC	1.5 kW	R88M-1M1K520T-□	R88D-1SN15H-ECT
3-phase 200 VAC	1 kW	R88M-1M1K020T-□	R88D-1SN10H-ECT
	2 kW	R88M-1M2K020T-□	R88D-1SN20H-ECT
	3 kW	R88M-1M3K020T-□	R88D-1SN30H-ECT
3-phase 400 VAC	400 W	R88M-1M40020C-□	R88D-1SN06F-ECT
	600 W	R88M-1M60020C-□	R88D-1SN06F-ECT
	1 kW	R88M-1M1K020C-□	R88D-1SN10F-ECT
	1.5 kW	R88M-1M1K520C-□	R88D-1SN15F-ECT
	2 kW	R88M-1M2K020C-□	R88D-1SN20F-ECT
	3 kW	R88M-1M3K020C-□	R88D-1SN30F-ECT

• 1,500-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Rated output	Servomotor	Servo Drive
3-phase 200 VAC	4 kW	R88M-1M4K015T-□	R88D-1SN55H-ECT
	5 kW	R88M-1M5K015T-□	R88D-1SN55H-ECT
	7.5 kW	R88M-1M7K515T-□	R88D-1SN75H-ECT
	11 kW	R88M-1M11K015T-□	R88D-1SN150H-ECT
	15 kW	R88M-1M15K015T-□	R88D-1SN150H-ECT
3-phase 400 VAC	4 kW	R88M-1M4K015C-□	R88D-1SN55F-ECT
	5.5 kW	R88M-1M5K515C-□	R88D-1SN55F-ECT
	7.5 kW	R88M-1M7K515C-□	R88D-1SN75F-ECT
	11 kW	R88M-1M11K015C-□	R88D-1SN150F-ECT
	15 kW	R88M-1M15K015C-□	R88D-1SN150F-ECT

• 1,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Rated output	Servomotor	Servo Drive
3-phase 200 VAC	900 W	R88M-1M90010T-□	R88D-1SN10H-ECT
	2 kW	R88M-1M2K010T-□	R88D-1SN20H-ECT
	3 kW	R88M-1M3K010T-□	R88D-1SN30H-ECT
3-phase 400 VAC	900 W	R88M-1M90010C-□	R88D-1SN10F-ECT
	2 kW	R88M-1M2K010C-□	R88D-1SN20F-ECT
	3 kW	R88M-1M3K010C-□	R88D-1SN30F-ECT

■ Servomotor Characteristics

• 3,000-r/min Servomotors

Item	Unit	Model (R88M-) 100 VAC					
	Unit	1M05030S	1M10030S	1M20030S	1M40030S		
Rated output*1	W	50 (45)	100 (95)	200 (190)	400 (320)		
Rated torque*1	N⋅m	0.159(0.143)	0.318 (0.302)	0.637 (0.605)	1.27 (1.02)		
Rated rotation speed	r/min	3,000					
Maximum rotation speed	r/min	6,000					
Rated current*1	Arms	1.2	1.5	2.5	4.8 (4.0)		
Rated frequency	Hz	250	250	250	250		

Item	Unit	Model (R88M-) 200 VAC					
Item	Onit	1M05030T	1M10030T	1M20030T	1M40030T	1M75030T	
Rated output*1	W	50 (45)	100 (95)	200 (190)	400 (320)	750 (675)	
Rated torque*1	N·m	0.159 (0.143)	0.318 (0.302)	0.637 (0.605)	1.27 (1.02)	2.39 (2.15)	
Rated rotation speed	r/min	3,000					
Maximum rotation speed	r/min	6,000				_	
Rated current*1	Arms	0.67	0.84	1.5	2.5 (2.1)	4.6 (4.2)	
Rated frequency	Hz	250	250	250	250	250	

Item	Unit		Model (R88M-) 200 VAC						
iteiii	Ullit	1L1K030T	1L1K530T	1L2K030T	1L3K030T	1L4K030T	1L4K730T		
Rated output	W	1,000	1,500	2,000	3,000	4,000	4,700		
Rated torque	N⋅m	3.18	4.77	6.37	9.55	12.7	15.0		
Rated rotation speed	r/min	3,000							
Maximum rota- tion speed	r/min	5,000							
Rated current	Arms	5.2	8.8	12.5	17.1	22.8	25.7		
Rated frequency	Hz	250	250	250	250	250	250		

Item	Unit	Model (R88M-) 400 VAC						
Item	Unit	1L75030C	1L1K030C	1L1K530C	1L2K030C			
Rated output	W	750	1,000	1,500	2,000			
Rated torque	N⋅m	2.39	3.18	4.77	6.37			
Rated rotation speed	r/min	3,000	3,000					
Maximum rotation speed	r/min	5,000	5,000					
Rated current	Arms	3.0	3.0	4.5	6.3			
Rated frequency	Hz	250	250	250	250			

Item	Unit	Model (R88M-) 400 VAC				
Itelli	Oilit	1L3K030C	1L4K030C	1L5K030C		
Rated output	W	3,000	4,000	5,000		
Rated torque	N⋅m	9.55	12.7	15.9		
Rated rotation speed	r/min	3,000				
Maximum rotation speed	r/min	5,000				
Rated current	Arms	8.7	12.8	13.6		
Rated frequency	Hz	250	250	250		

^{*1.} For models with an oil seal, values in parentheses are used due to derating. Derating is not required for models without values in parentheses.

• 2,000-r/min Servomotors

Item	Unit	Model (R88M-) 200 VAC					
Itelli	Oilit	1M1K020T	1M1K520T	1M2K020T	1M3K020T		
Rated output	W	1,000	1,500	2,000	3,000		
Rated torque	N⋅m	4.77	7.16	9.55	14.3		
Rated rotation speed	r/min	2,000					
Maximum rotation speed	r/min	3,000	3,000				
Rated current	Arms	5.2	8.6	11.3	15.7		
Rated frequency	Hz	167	167	167	167		

		Model (R88M-) 400 VAC						
Item	Unit	1M4002 0C	1M6002 0C	1M1K02 0C	1M1K52 0C	1M2K02 0C	1M3K02 0C	
Rated output	W	400	600	1,000	1,500	2,000	3,000	
Rated torque	N⋅m	1.91	2.86	4.77	7.16	9.55	14.3	
Rated rotation speed	r/min	2,000	•	•	•	•		
Maximum rotation speed	r/min	3,000						
Rated current	Arms	1.1	1.6	2.9	4.1	5.7	8.6	
Rated frequency	Hz	167	167	167	167	167	167	

• 1,500-r/min Servomotors

Item	Unit		Model	(R88M-) 20	200 VAC			
Item	Unit	1M4K015T	1M5K015T	1M7K515T	1M11K015T	1M15K015T		
Rated output	W	4,000	5,000	7,500	11,000	15,000		
Rated torque	N⋅m	25.5	31.8	47.8	70.0	95.5		
Rated rotation speed	r/min	1,500	1,500					
Maximum rotation speed	r/min	3,000			2,000			
Rated current	Arms	25.7	25.8	41.2	57.0	60.7		
Rated frequency	Hz	100	100	100	125	125		

Item	Unit		Model (R88M-) 400 VAC			
iteiii	Oilit	1M4K015C	1M5K515C	1M7K515C	1M11K015C	1M15K015C
Rated output	W	4,000	5,500	7,500	11,000	15,000
Rated torque	N⋅m	25.5	35.0	47.8	70.0	95.5
Rated rotation speed	r/min	1,500				
Maximum rotation speed	r/min	3,000 2,000				
Rated current	Arms	12.8	14.0	22.0	31.4	33.3
Rated frequency	Hz	100	100	100	125	125

• 1,000-r/min Servomotors

Item Unit		Model (R88M-) 200 VAC			
iteiii	Ullit	1M90010T	1M2K010T	1M3K010T	
Rated output	W	900	2,000	3,000	
Rated torque	N⋅m	8.59	19.1	28.7	
Rated rotation speed	r/min	1,000			
Maximum rotation speed	r/min	2,000			
Rated current	Arms	6.7	14.4	21.2	
Rated frequency	Hz	83	67	67	

Item Uni		Model (R88M-) 400 VAC				
item	Ullit	1M90010C	1M2K010C	1M3K010C		
Rated output	W	900	2,000	3,000		
Rated torque	N⋅m	8.59	19.1	28.7		
Rated rotation speed	r/min	1,000				
Maximum rotation speed	r/min	2,000				
Rated current	Arms	3.6	7.1	10.6		
Rated frequency	Hz	83	67	67		

Motor Power Cable

■ Combinations of Motor Power Cables and Servomotors

Applicable Servomotors		Model			
	Applicable Servollotors	Without brake wire	With brake wire		
	3,000-r/min Servomotors 100 W, 200 W, 400 W, 750 W	R88A-CA1A□□□S R88A-CA1A□□□SF			
	3,000-r/min Servomotors 50 W, 200 W, 400 W, 750 W	R88A-CA1A□□□SFR			
200 VAC	3,000-r/min Servomotors 1 kW 2,000-r/min Servomotors 1 kW 1,000-r/min Servomotors 900 W	R88A-CA1B□□□S R88A-CA1B□□□SF	R88A-CA1B□□□B R88A-CA1B□□□BF		
200 VAC	3,000-r/min Servomotors 1.5 kW 2,000-r/min Servomotors 1.5 kW	R88A-CA1C□□□S R88A-CA1C□□□SF	R88A-CA1C□□□B R88A-CA1C□□□BF		
400 VAC	3,000-r/min Servomotors 750 W, 1 kW, 1,5 kW, 2 kW 2,000-r/min Servomotors 400 W, 600 W, 1 kW, 1.5 kW, 2 kW 1,000-r/min Servomotors 900 W	R88A-CA1C□□□S R88A-CA1C□□□SF	R88A-CA1D□□□B R88A-CA1D□□□BF		
	3,000-r/min Servomotors 2 kW (200 VAC), 3 kW (200 VAC/ 400 VAC) 2,000-r/min Servomotors 2 kW (200 VAC), 3 kW (200 VAC/ 400 VAC) 1,000-r/min Servomotors 2 kW (200 VAC/400 VAC), 3 kW (400 VAC)	R88A-CA1EDDDS R88A-CA1EDDDSF	R88A-CA1E□□□B R88A-CA1E□□□BF		
200 VAC	1,000-r/min Servomotors 3 kW	R88A-CA1F□□□S R88A-CA1F□□□SF	R88A-CA1F□□□B R88A-CA1F□□□BF		
200 VAC 400 VAC	200 VAC 3,000-r/min Servomotors 4 kW, 4.7 kW 1,500-r/min Servomotors 4 kW, 5 kW 400 VAC 3,000-r/min Servomotors 4 kW, 5 kW 1,500-r/min Servomotors 4 kW, 5,5 kW, 7.5 kW	R88A-CA1H□□□SF	R88A-CA1H□□□BF R88A-CA1HE□□□BF*1		
	1,500-r/min Servomotors 11 kW, 15 kW	R88A-CA1J□□□SF	R88A-CA1J□□□BF R88A-CA1JE□□□BF*1		
200 VAC	1,500-r/min Servomotors 7.5 kW, 11 kW, 15 kW	R88A-CA1K□□□SF	R88A-CA1K□□□BF R88A-CA1KE□□□BF ^{*1}		

*1. R88A-CA1 B is an extension cable. This cable can be used when extending a power cable whether it has a brake wire or not.

Specifications for Combinations of Unit Versions and Motor Power Cables

For the motor power cables, there are two types of cable versions available: version 1.0 and 1.1, and eight types of cable lengths available: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, and 50 m. When you use a unit version 1.2 or earlier of Servo Drive, use a motor power cable of 20 m or less. The following table shows the specifications for combinations of cable versions. cable lengths, and unit versions.

			Specifications for combinations					
1	Motor Power Cable				ersion earlier		ersion r later	
			Cable version		Cable version		Cable version	
Model (R88A-)	Cable length	Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1	
CA1A□□□S CA1A□□□SF CA1A□□□SFR	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available	
CA1A□□□B CA1A□□□BF	30 m, 40 m, 50 m		Yes		Unavail- able		Available	
CA1B□□□S CA1B□□□SF CA1B□□□B	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available	
CA1B□□□BF	30 m, 40 m, 50 m		Yes		Unavail- able		Available	
CA1C□□□S CA1C□□□SF CA1C□□□B	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available	
CA1C□□□BF	30 m, 40 m, 50 m		Yes		Unavail- able		Available	
CA1D□□□B CA1D□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		Available		Available		
	30 m, 40 m, 50 m	Yes		Unavail- able		Available		
CA1EDDDS CA1EDDDSF CA1EDDDB	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available	
CA1E□□□BF	30 m, 40 m, 50 m		Yes		Unavail- able		Available	

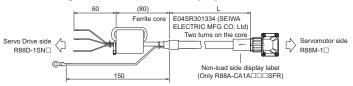
				Speci	fications f	or combina	ations
Motor Power Cable			Unit version 1.2 or earlier		Unit version 1.3 or later		
Model (R88A-)	Cable length	Cable	version	Cable v	ersion/	Cable v	ersion/
Wouel (Rook-)	Cable leligtii	Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1
CA1FUUUS CA1FUUUSF CA1FUUUB	3 m, 5 m, 10 m, 15 m, 20 m	Yes		Available		Available	
CA1F□□□BF	30 m, 40 m, 50 m	Yes		Unavail- able		Available	
CA1H0□□SF CA1H0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		Available		Available	
CA1HE□□BF	10 m, 20 m	Yes		Unavail- able*1		Avail- able ^{*2}	
CA1J0□□SF CA1J0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		Available		Available	
CA1JE□□BF	10 m, 20 m	Yes		Unavail- able ^{*1}		Avail- able ^{*2}	
CA1K0□□SF CA1K0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes		Available		Available	
CA1KE□□BF	10 m, 20 m	Yes		Unavail- able*1		Avail- able ^{*2}	

^{*1.} You cannot use an extension cable for a unit version 1.2 or earlier of Servo Drive.

^{*2.} This can be used when the total wire length of motor power cables per Servo Drive is 50 m or less. Refer to 93 page Combination of Power Cable and Extension Cable for details.

■ External Dimensions of Motor Power Cables

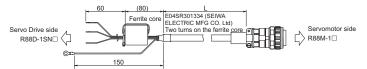
R88A-CA1A SFR88A-CA1A SFR88A-CA1A SFR88A-CA1A SFR Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1A003S	3 m		Approx. 0.4 kg
R88A-CA1A005S	5 m		Approx. 0.6 kg
R88A-CA1A010S	10 m		Approx. 1.1 kg
R88A-CA1A015S	15 m	6.8/7.2 dia.*1	Approx. 1.5/1.6 kg*1
R88A-CA1A020S	20 m	6.6/7.2 dia.	Approx. 2.0/2.1 kg*1
R88A-CA1A030S	30 m		Approx. 3.1 kg
R88A-CA1A040S	40 m		Approx. 4.0 kg
R88A-CA1A050S	50 m		Approx. 4.9 kg
R88A-CA1A003SF	3 m		Approx. 0.4 kg
R88A-CA1A005SF	5 m		Approx. 0.6 kg
R88A-CA1A010SF	10 m		Approx. 1.1 kg
R88A-CA1A015SF	15 m	6.8/7.2 dia.*1	Approx. 1.5/1.6 kg*1
R88A-CA1A020SF	20 m	6.6/7.2 dia.	Approx. 2.0/2.1 kg*1
R88A-CA1A030SF	30 m		Approx. 3.0 kg
R88A-CA1A040SF	40 m		Approx. 4.0 kg
R88A-CA1A050SF	50 m	Ī	Approx. 4.9 kg
R88A-CA1A003SFR	3 m		Approx. 0.4 kg
R88A-CA1A005SFR	5 m		Approx. 0.6 kg
R88A-CA1A010SFR	10 m		Approx. 1.1 kg
R88A-CA1A015SFR	15 m	6.8/7.2 dia.*1	Approx. 1.5/1.6 kg*1
R88A-CA1A020SFR	20 m		Approx. 2.0/2.1 kg*1
R88A-CA1A030SFR	30 m		Approx. 3.0 kg
R88A-CA1A040SFR	40 m		Approx. 4.0 kg
R88A-CA1A050SFR	50 m		Approx. 4.9 kg

^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

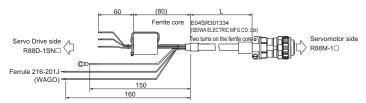
● R88A-CA1B□□□S/R88A-CA1B□□□SF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1B003S	3 m		Approx. 1.0/1.4 kg*1
R88A-CA1B005S	5 m		Approx. 1.6/2.0 kg*1
R88A-CA1B010S	10 m		Approx. 2.9/3.7 kg*1
R88A-CA1B015S	15 m	10.8/13.3 dia.*1	Approx. 4.3/5.4 kg*1
R88A-CA1B020S	20 m	10.6/13.3 dia.	Approx. 5.7/7.2 kg*1
R88A-CA1B030S	30 m		Approx. 10.4 kg
R88A-CA1B040S	40 m	•	Approx. 13.7 kg
R88A-CA1B050S	50 m		Approx. 17.0 kg
R88A-CA1B003SF	3 m		Approx. 1.0/1.4 kg*1
R88A-CA1B005SF	5 m		Approx. 1.6/2.1 kg*1
R88A-CA1B010SF	10 m		Approx. 2.9/3.9 kg*1
R88A-CA1B015SF	15 m	10.8/15.3 dia.*1	Approx. 4.3/5.7 kg*1
R88A-CA1B020SF	20 m	10.8/15.3 dia.	Approx. 5.7/7.5 kg*1
R88A-CA1B030SF	30 m		Approx. 11.0 kg
R88A-CA1B040SF	40 m		Approx. 14.5 kg
R88A-CA1B050SF	50 m		Approx. 17.9 kg

^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

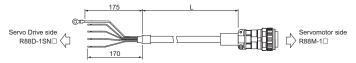
R88A-CA1B□□□B/R88A-CA1B□□□BF Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1B003B	3 m		Approx. 1.2/1.4 kg*1
R88A-CA1B005B	5 m		Approx. 1.9/2.1 kg*1
R88A-CA1B010B	10 m		Approx. 3.5/3.8 kg*1
R88A-CA1B015B	15 m	12.5/13.3 dia.*1	Approx. 5.1/5.5 kg*1
R88A-CA1B020B	20 m	12.5/13.3 dia.	Approx. 6.7/7.3 kg*1
R88A-CA1B030B	30 m		Approx. 10.7 kg
R88A-CA1B040B	40 m		Approx. 14.0 kg
R88A-CA1B050B	50 m		Approx. 17.4 kg
R88A-CA1B003BF	3 m		Approx. 1.2/1.3 kg*1
R88A-CA1B005BF	5 m		Approx. 1.9 kg
R88A-CA1B010BF	10 m		Approx. 3.5 kg
R88A-CA1B015BF	15 m	12.5/14.7 dia.*1	Approx. 5.1 kg
R88A-CA1B020BF	20 m	12.5/14.7 dia.	Approx. 6.7/6.8 kg*1
R88A-CA1B030BF	30 m		Approx. 9.9 kg
R88A-CA1B040BF	40 m		Approx. 12.9 kg
R88A-CA1B050BF	50 m		Approx. 16.0 kg

^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

● R88A-CA1C□□□S/R88A-CA1C□□□SF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1C003S	3 m		Approx. 1.0/1.3 kg*1
R88A-CA1C005S	5 m		Approx. 1.6/2.0 kg*1
R88A-CA1C010S	10 m		Approx. 2.9/3.6 kg*1
R88A-CA1C015S	15 m	10.8/13.3 dia.*1	Approx. 4.3/5.3 kg*1
R88A-CA1C020S	20 m	10.6/13.3 ula.	Approx. 5.7/7.1 kg*1
R88A-CA1C030S	30 m		Approx. 10.3 kg
R88A-CA1C040S	40 m		Approx. 13.6 kg
R88A-CA1C050S	50 m		Approx. 16.9 kg
R88A-CA1C003SF	3 m		Approx. 1.0/1.3 kg*1
R88A-CA1C005SF	5 m		Approx. 1.6/2.1 kg*1
R88A-CA1C010SF	10 m		Approx. 2.9/3.8 kg*1
R88A-CA1C015SF	15 m	10.8/15.3 dia.*1	Approx. 4.3/5.6 kg*1
R88A-CA1C020SF	20 m	10.8/15.3 dia.	Approx. 5.7/7.5 kg*1
R88A-CA1C030SF	30 m		Approx. 10.9 kg
R88A-CA1C040SF	40 m		Approx. 14.4 kg
R88A-CA1C050SF	50 m		Approx. 17.9 kg

^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

R88A-CA1C□□□B/R88A-CA1C□□□BF Connection configuration and external dimensions [mm]

170 180

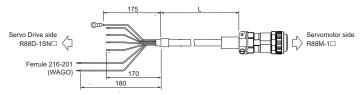
(WAGO)

Servo Drive side R88D-1SND Servomotor side R88M-1D

		0	
Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1C003B	3 m		Approx. 1.2/1.3 kg*1
R88A-CA1C005B	5 m	1	Approx. 1.9/2.0 kg*1
R88A-CA1C010B	10 m		Approx. 3.5/3.7 kg*1
R88A-CA1C015B	15 m	12.5/13.3 dia.*1	Approx. 5.1/5.5 kg*1
R88A-CA1C020B	20 m	12.5/13.5 dia.	Approx. 6.7/7.2 kg*1
R88A-CA1C030B	30 m		Approx. 10.6 kg
R88A-CA1C040B	40 m	1	Approx. 14.0 kg
R88A-CA1C050B	50 m	1	Approx. 17.3 kg
R88A-CA1C003BF	3 m		Approx. 1.2 kg
R88A-CA1C005BF	5 m	1	Approx. 1.9 kg
R88A-CA1C010BF	10 m	1	Approx. 3.5/3.4 kg*1
R88A-CA1C015BF	15 m	12.5/14.7 dia.*1	Approx. 5.1 kg
R88A-CA1C020BF	20 m	12.5/14.7 dia. '	Approx. 6.7 kg
R88A-CA1C030BF	30 m		Approx. 9.8 kg
R88A-CA1C040BF	40 m	1	Approx. 12.9 kg
R88A-CA1C050BF	50 m		Approx. 16.0 kg

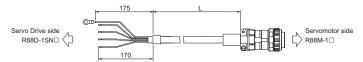
^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

● R88A-CA1D□□□B/R88A-CA1D□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1D003B	3 m		Approx. 1.3 kg
R88A-CA1D005B	5 m		Approx. 1.9 kg
R88A-CA1D010B	10 m		Approx. 3.5 kg
R88A-CA1D015B	15 m	12.5 dia	Approx. 5.2 kg
R88A-CA1D020B	20 m	12.5 dla.	Approx. 6.8 kg
R88A-CA1D030B	30 m		Approx. 10.0 kg
R88A-CA1D040B	40 m		Approx. 13.3 kg
R88A-CA1D050B	50 m		Approx. 16.5 kg
R88A-CA1D003BF	3 m		Approx. 1.3 kg
R88A-CA1D005BF	5 m		Approx. 1.9 kg
R88A-CA1D010BF	10 m		Approx. 3.5 kg
R88A-CA1D015BF	15 m	12.5 dia	Approx. 5.2 kg
R88A-CA1D020BF	20 m	12.5 dla.	Approx. 6.8 kg
R88A-CA1D030BF	30 m		Approx. 10.0 kg
R88A-CA1D040BF	40 m		Approx. 13.3 kg
R88A-CA1D050BF	50 m		Approx. 16.5 kg

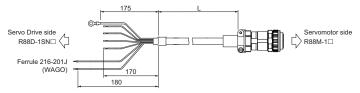
● R88A-CA1E□□□S/R88A-CA1E□□□SF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1E003S	3 m		Approx. 1.2/1.7 kg*1
R88A-CA1E005S	5 m		Approx. 1.9/2.6 kg*1
R88A-CA1E010S	10 m	1	Approx. 3.5/4.8 kg*1
R88A-CA1E015S	15 m	12.0/15.0 dia.*1	Approx. 5.1/7.1 kg*1
R88A-CA1E020S	20 m	12.0/15.0 dia.	Approx. 6.7/9.4 kg*1
R88A-CA1E030S	30 m		Approx. 13.8 kg
R88A-CA1E040S	40 m	1	Approx. 18.2 kg
R88A-CA1E050S	50 m	1	Approx. 22.5 kg
R88A-CA1E003SF	3 m		Approx. 1.2/1.4 kg*1
R88A-CA1E005SF	5 m	1	Approx. 1.9/2.2 kg*1
R88A-CA1E010SF	10 m		Approx. 3.5/4.0 kg*1
R88A-CA1E015SF	15 m	12.0/15.5 dia.*1	Approx. 5.1/5.9 kg*1
R88A-CA1E020SF	20 m	12.0/15.5 dia.	Approx. 6.7/7.8 kg*1
R88A-CA1E030SF	30 m		Approx. 11.4 kg
R88A-CA1E040SF	40 m	1	Approx. 14.9 kg
R88A-CA1E050SF	50 m	1	Approx. 18.5 kg

^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

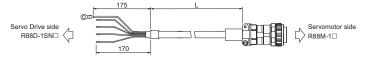
● R88A-CA1E□□□B/R88A-CA1E□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1E003B	3 m		Approx. 1.4/1.8 kg*1
R88A-CA1E005B	5 m		Approx. 2.2/2.8 kg*1
R88A-CA1E010B	10 m		Approx. 4.1/5.1 kg*1
R88A-CA1E015B	15 m	14.0/15.0 dia.*1	Approx. 6.0/7.5 kg*1
R88A-CA1E020B	20 m	14.0/15.0 dia.	Approx. 7.8/9.9 kg*1
R88A-CA1E030B	30 m		Approx. 14.5 kg
R88A-CA1E040B	40 m		Approx. 19.1 kg
R88A-CA1E050B	50 m		Approx. 23.7 kg
R88A-CA1E003BF	3 m		Approx. 1.4/1.5 kg*1
R88A-CA1E005BF	5 m		Approx. 2.2 kg
R88A-CA1E010BF	10 m		Approx. 4.1/4.0 kg*1
R88A-CA1E015BF	15 m	14.2/15.5 dia.*1	Approx. 6.0/5.9 kg*1
R88A-CA1E020BF	20 m	14.2/15.5 dia. :	Approx. 7.8 kg
R88A-CA1E030BF	30 m		Approx. 11.4 kg
R88A-CA1E040BF	40 m		Approx. 15.0 kg
R88A-CA1E050BF	50 m		Approx. 18.6 kg

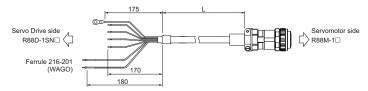
^{*1.} In \triangle/\Box , \triangle and \Box represent the value of cable version 1.0 and that of cable version 1.1 respectively.

R88A-CA1F□□□S/R88A-CA1F□□□SF Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1F003S	3 m		Approx. 1.9 kg
R88A-CA1F005S	5 m		Approx. 3.0 kg
R88A-CA1F010S	10 m		Approx. 5.8 kg
R88A-CA1F015S	15 m	14.5 dia.	Approx. 8.6 kg
R88A-CA1F020S	20 m	14.5 ula.	Approx. 11.4 kg
R88A-CA1F030S	30 m		Approx. 16.9 kg
R88A-CA1F040S	40 m		Approx. 22.5 kg
R88A-CA1F050S	50 m		Approx. 28.1 kg
R88A-CA1F003SF	3 m		Approx. 1.9 kg
R88A-CA1F005SF	5 m		Approx. 3.0 kg
R88A-CA1F010SF	10 m		Approx. 5.8 kg
R88A-CA1F015SF	15 m	14.5 dia.	Approx. 8.6 kg
R88A-CA1F020SF	20 m	14.5 dia.	Approx. 11.4 kg
R88A-CA1F030SF	30 m		Approx. 16.9 kg
R88A-CA1F040SF	40 m		Approx. 22.5 kg
R88A-CA1F050SF	50 m		Approx. 28.1 kg

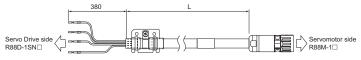
● R88A-CA1F□□□B/R88A-CA1F□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1F003B	3 m		Approx. 2.2 kg
R88A-CA1F005B	5 m		Approx. 3.5 kg
R88A-CA1F010B	10 m		Approx. 6.7 kg
R88A-CA1F015B	15 m	17.0 dia.	Approx. 9.9 kg
R88A-CA1F020B	20 m	17.0 dia.	Approx. 13.0 kg
R88A-CA1F030B	30 m		Approx. 19.4 kg
R88A-CA1F040B	40 m		Approx. 25.8 kg
R88A-CA1F050B	50 m	Ī	Approx. 32.1 kg
R88A-CA1F003BF	3 m		Approx. 2.2 kg
R88A-CA1F005BF	5 m		Approx. 3.5 kg
R88A-CA1F010BF	10 m		Approx. 6.7 kg
R88A-CA1F015BF	15 m	17.0 dia.	Approx. 9.9 kg
R88A-CA1F020BF	20 m	17.0 dia.	Approx. 13.0 kg
R88A-CA1F030BF	30 m		Approx. 19.4 kg
R88A-CA1F040BF	40 m		Approx. 25.8 kg
R88A-CA1F050BF	50 m		Approx. 32.1 kg

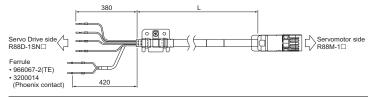
● R88A-CA1H□□□SF

Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1H003SF	3 m	15.0 dia.	Approx. 1.9 kg
R88A-CA1H005SF	5 m		Approx. 2.8 kg
R88A-CA1H010SF	10 m		Approx. 4.9 kg
R88A-CA1H015SF	15 m		Approx. 7.2 kg
R88A-CA1H020SF	20 m		Approx. 9.4 kg

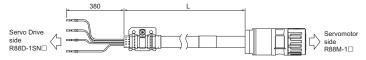
R88A-CA1H□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1H003BF	3 m	15.0 dia.	Approx. 1.9 kg
R88A-CA1H005BF	5 m		Approx. 2.8 kg
R88A-CA1H010BF	10 m		Approx. 4.9 kg
R88A-CA1H015BF	15 m		Approx. 7.2 kg
R88A-CA1H020BF	20 m		Approx. 9.4 kg

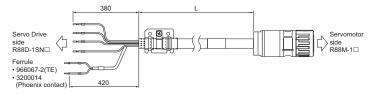
● R88A-CA1J□□□SF

Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1J003SF	3 m		Approx. 2.4 kg
R88A-CA1J005SF	5 m		Approx. 3.3 kg
R88A-CA1J010SF	10 m	17.3 dia.	Approx. 6.0 kg
R88A-CA1J015SF	15 m		Approx. 8.7 kg
R88A-CA1J020SF	20 m		Approx. 11.5 kg

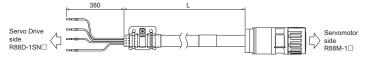
R88A-CA1J□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1J003BF	3 m		Approx. 2.4 kg
R88A-CA1J005BF	5 m		Approx. 3.3 kg
R88A-CA1J010BF	10 m	17.3 dia.	Approx. 6.0 kg
R88A-CA1J015BF	15 m		Approx. 8.7 kg
R88A-CA1J020BF	20 m		Approx. 11.5 kg

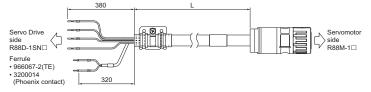
● R88A-CA1K□□□SF

Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1K003SF	3 m	23.2 dia.	Approx. 4.8 kg
R88A-CA1K005SF	5 m		Approx. 6.7 kg
R88A-CA1K010SF	10 m		Approx. 12.5 kg
R88A-CA1K015SF	15 m		Approx. 18.7 kg
R88A-CA1K020SF	20 m		Approx. 24.9 kg

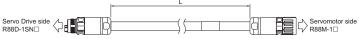
R88A-CA1K□□□BF



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1K003BF	3 m		Approx. 4.8 kg
R88A-CA1K005BF	5 m	23.2 dia.	Approx. 6.7 kg
R88A-CA1K010BF	10 m		Approx. 12.5 kg
R88A-CA1K015BF	15 m		Approx. 18.7 kg
R88A-CA1K020BF	20 m		Approx. 24.9 kg

● R88A-CA1HE□□□BF

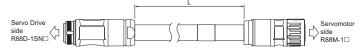
Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1HE10BF	10 m	15.0 dia.	Approx. 5.2 kg
R88A-CA1HE20BF	20 m		Approx. 9.7 kg

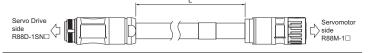
● R88A-CA1JE□□□BF

Connection configuration and external dimensions [mm]



Model	Length [L]	Outer diameter of sheath	Weight
R88A-CA1JE10BF	10 m	17.3 dia.	Approx. 6.2 kg
R88A-CA1JE20BF	20 m		Approx. 11.7 kg

● R88A-CA1KE□□□BF

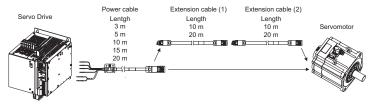


Model	Length [L]	sheath	Weight
R88A-CA1KE10BF	10 m	23.2 dia.	Approx. 12.8 kg
R88A-CA1KE20BF	20 m	25.2 dia.	Approx. 25.2 kg

■ Combination of Power Cable and Extension Cable

Specifications for cases when a power cable is used with extension cables are given below. When Servomotor is 4 kW or more and the power cable is over 20 m, follow the below list that specifies the combination of power cable with extension cable.

You can use an extension cable when you use a unit version 1.3 or later of Servo Drive. When you use a unit version 1.2 or earlier of Servo Drive, use a motor power cable of 20 m or less.



Length [L]					
Total	Power cable	Extension cable (1)	Extension cable (2)	Combination	
3	3			Power cable	
5	5			Power cable	
10	10			Power cable	
15	15			Power cable	
20	20			Power cable	
30	20	10		Power cable + extension cable (1)	
40	20	20		Power cable + extension cable (1)	
50	20	10	20	Power cable + extension cable (1) + extension cable (2)*1	

 $^{^{\}star}$ 1. Extension cable (1); 20 m + Extension cable (2); 10 m can be usable.

Maintenance

■ Servo Drive Lifetime

- The lifetime of Servo Drive depends on application conditions. When the ambient temperature is 40°C and the average output is 70% of the rated output, the design life expectancy is ten years.
- The use of the Servo Drive in a hot environment shortens its lifetime. We recommend that the
 ambient temperature and the power supply ON time be reduced as much as possible to
 lengthen the lifetime of the Servo Drive.
- · The lifetimes for the different parts of Servo Drive are given below.

Name	Lifetime
	Approx. 36,500 operations (lifetime depends on application conditions.)
	Approx. 36,500 operations (lifetime depends on application conditions.)

Product Disposal

Comply with the local ordinance and regulations when disposing of the product.



Dispose of in accordance with WEEE Directive

Reference Manuals

Manual name	Models	Cat. No.
	R88M-1L□/-1M□ R88D-1SN□-ECT	1586

OMRON Corporation (Manufacturer)

Shiokoji Horikawa, Shimogyo-ku, Kyoto, 600-8530, Japan Contact: www.ia.omron.com

Regional Headquarters

OMRON EUROPE B.V.(Representative and Importer in EU)

Wegalaan 67-69, 2132 JD Hoofddorp, The Netherlands Tel: (31)2356-81-300/Fax: (31)2356-81-388

OMRON Electronics Ltd.

Opal Drive, Fox Milne, Milton Keynes MK15 0DG, U.K. Tel: (44)-0-1908-258258/Fax: (44)-0-1908-258158

OMRON ASIA PACIFIC PTE. LTD.

No. 438A Alexandra Road # 05-05/08 (Lobby 2), Alexandra Technopark, Singapore 119967

Tel: (65) 6835-3011/Fax: (65) 6835-3011

OMRON ELECTRONICS LLC

2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900/Fax: (1) 847-843-7787

OMRON (CHINA) CO., LTD.

Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-5037-2222/Fax: (86) 21-5037-2200

Note: Specifications subjuect to change without notice.